

# **TECHNICAL TRAINING**

## **DIAGNOSTIC LEVEL II**



***All types HA16PX-HA18PX  
(HA46JRT – HA51JRT)***

# How to use this document?

**MAINTENANCE AND REPAIR OPERATIONS ON YOUR HAULOTTE MACHINE  
MUST BE DONE ONLY BY TRAINED, EXPERIENCED AND AUTHORIZED TECHNICIANS**

**You have between the hands the summary given during the HAULOTTE technical training , It will enable you to find information necessary for the maintenance and the repair of your HAULOTTE machine .**

**Thanks to the guide below you will reach the required chapter quickly.**

## **Chapter 1: Main features and functions**

It is a resume of the information contained in the manual user delivered with the machine: components, overall dimensions, working zones , commands, etc...

## **Chapter 2: Study of the wiring diagram**

You will find there the elements following:

- A summary of the standardized symbols used by HAULOTTE Group
- The complete wiring diagram of the studied model
- The non exhaustive list of the electric looms and electronic boards
- Localization of the main safety units (tilt , limit switches, sensors,transducers...)
- Logical equations of operation: by function, to diagnose the main dysfunctions

## **Chapter 3: Study of the hydraulic diagram**

You will find there the elements following:

- a summary of the standardized symbols used by HAULOTTE Group
- the complete hydraulic diagram of the studied model
- a localization of the main hydraulics manifold (proportional block , on/off movements block,...)

## **Chapter 4: Adjustments**

This is the adjustments and calibrations, hydraulics and electric, necessary to the good maintenance of the material. You will find as well the methods of adjustment with table values.

## **Chapter 5: Guide of breakdown**

Quick summary of the step to be followed for possible sources of breakdown.

In case of any defect or any dysfunction you will be able to identify the elements in question, whatever they are electric or hydraulic.

## **Chapter 6: Summary of the versions**

This manual treats of the latest version, however this summary table enables you to find the former versions of the material (electric and hydraulics).

## **Chapter 7: Special functions**

This chapter gathers all the functions and adjustment specific to carry out on the machine. There does not exist for all the materials and depends on the studied model.

It must be the subject of a special attention as an intervention badly carried out can deteriorate the good performance of the machine and thus consequently the safety of the users.

Only a technician HAULOTTE or approved by HAULOTTE Services is able to carry out this kind of intervention.

On this chapter, some special adjustment (sensors) are also explained prior to calibration ( depends on the model)

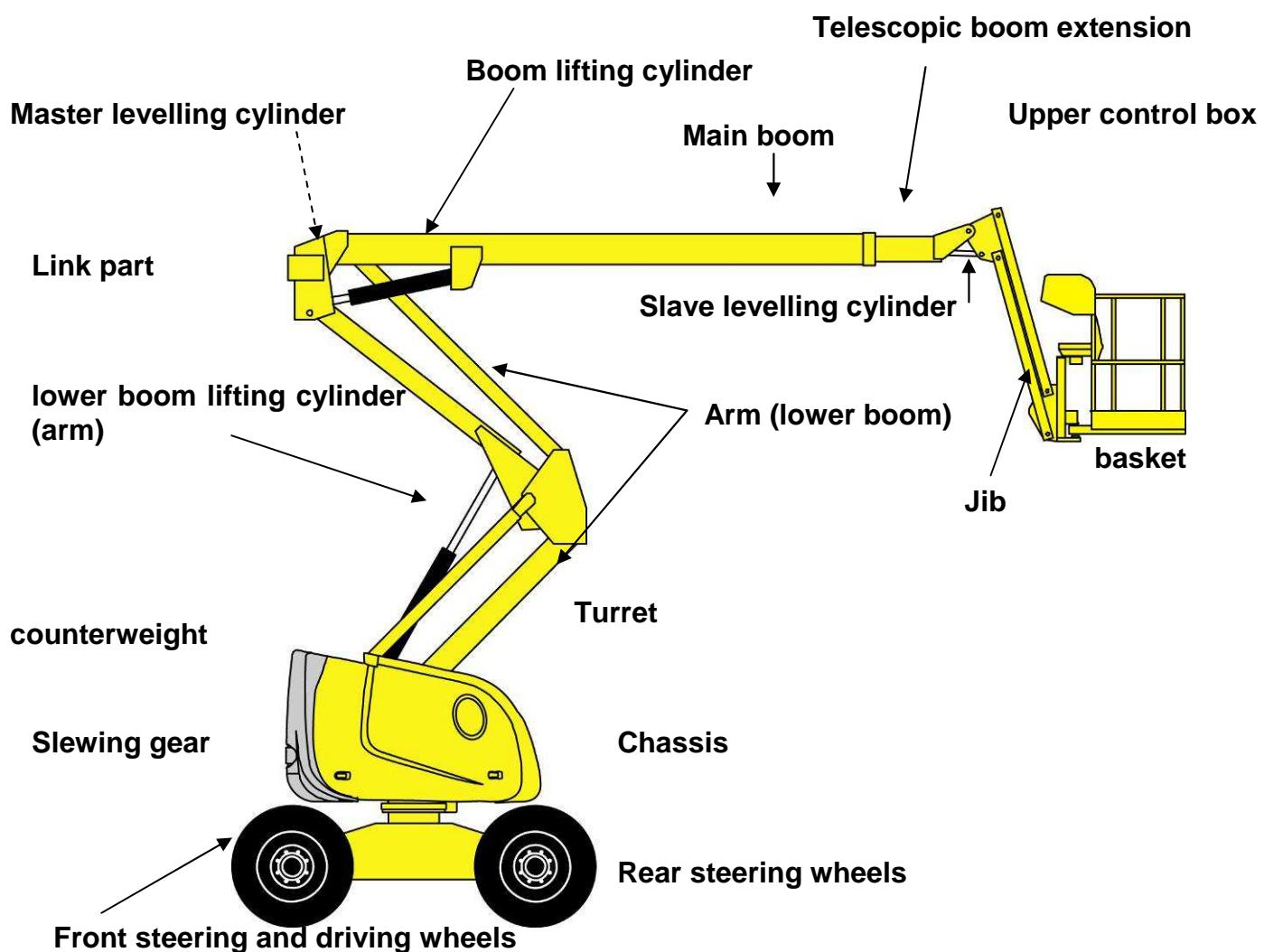
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## 1. MAIN FEATURES AND FUNCTIONS

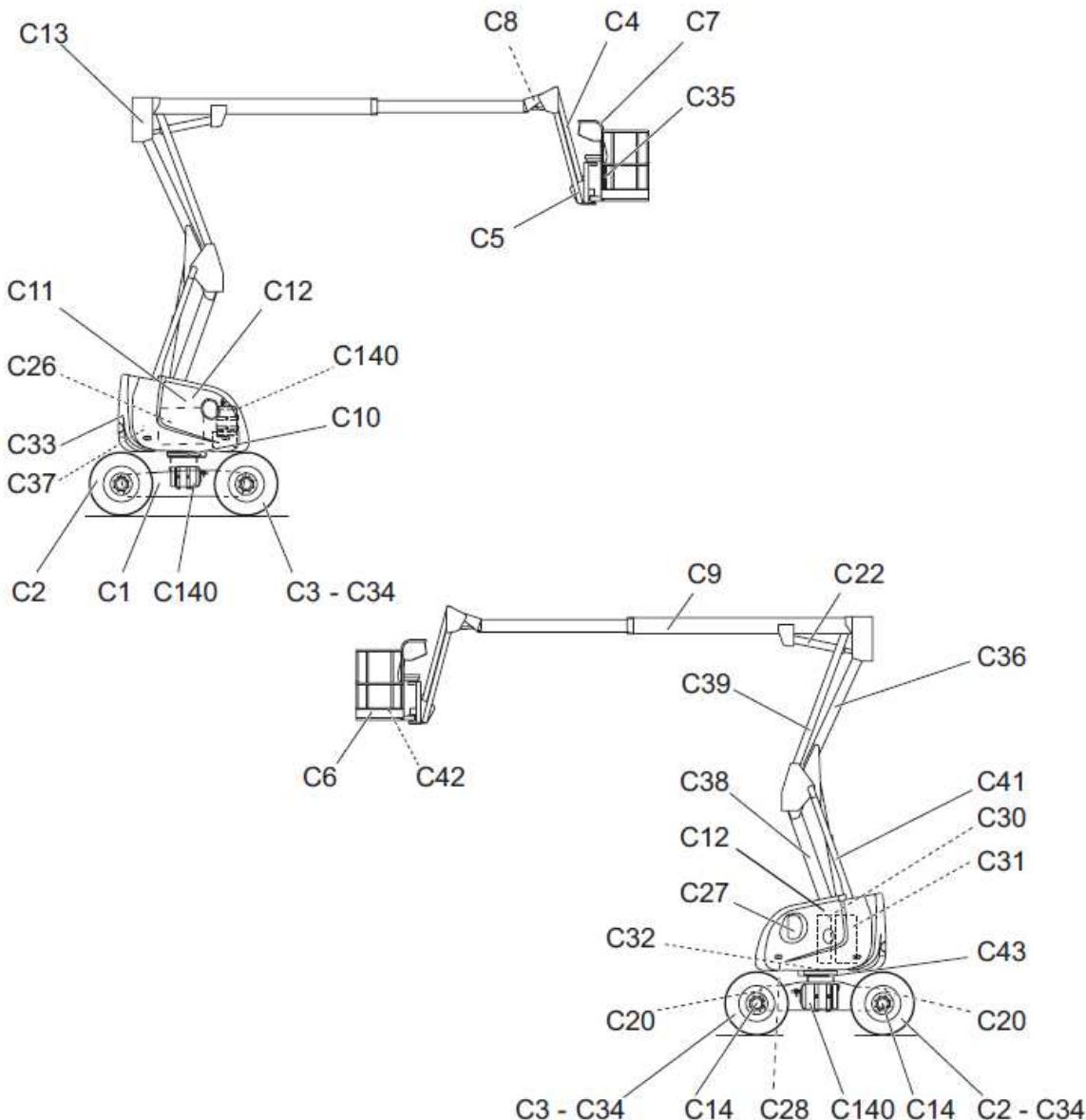
### 1.1. THE DESIGN



## **1.2. CHARACTERISTICS**

## **1.2.1. MAIN COMPONENTS**

HA16X - HA16SPX (HA46SJRT) - HA16PX (HA46JRT)  
- HA18SPX (HA51SJRT) - HA18PX (HA51JRT) - View  
of components for articulated arms under 20 m (65  
ft 7 in)

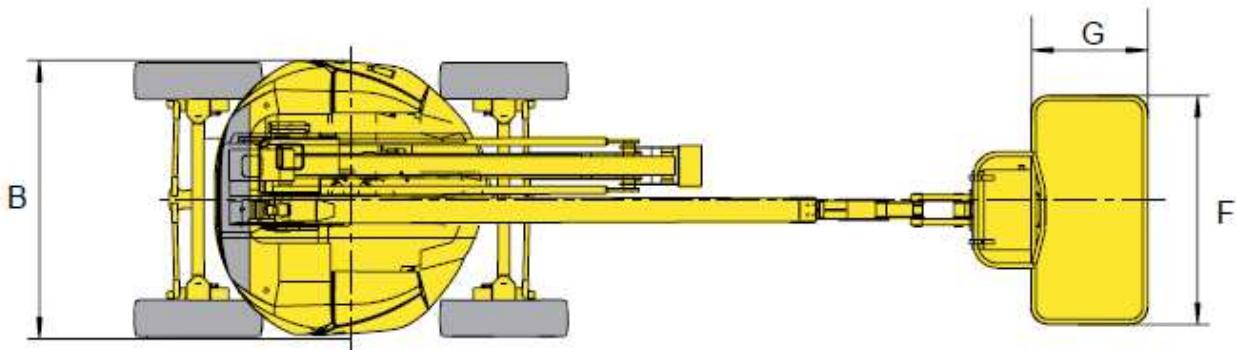
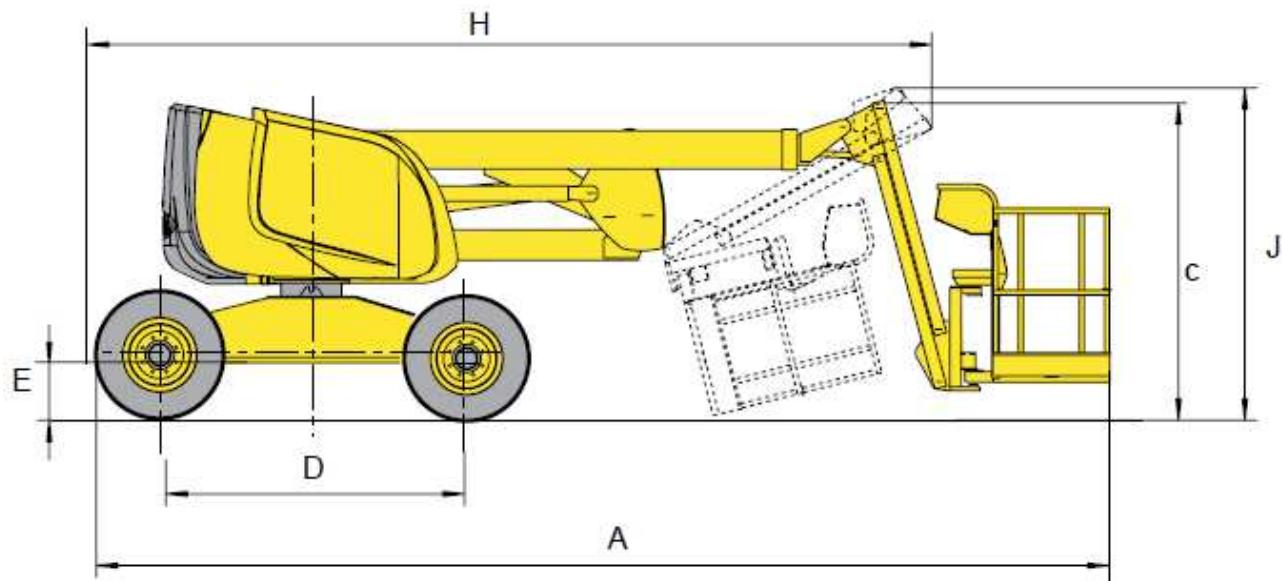


Marking	Description
C1	Rolling chassis
C2	Front driven steering axle
C3	Rear drive and/or steer wheel
C4	Jib
C5	Platform support incorporating load limiter
C6	Platform
C7	Platform control box
C8	Compensation receiver cylinder
C9	Boom (or boom tube)
C10	Slew ring
C11	Turntable assembly
C12	Hood
C13	Arm/Boom link piece
C14	Hydraulic drive motor and reducer
C20	Tie-down (and/or lifting) points
C22	Boom lift cylinder
C26	Engine and hydraulic pump
C27	Ground control box
C28	Tilt detector
C30	Hydraulic tank
C31	Fuel tank
C32	Turntable rotation gearbox
C33	Counterweight
C34	Drive wheels
C35	Document holder
C36	Top arm
C37	Starter battery
C38	Bottom arm
C39	Top tie rod
C41	Bottom tie rod
C42	'Enable Switch' pedal
C43	Turntable rotation lock pin
C140	Gas bottles <sup>1</sup>

1. For US only

## 1.2.2. OVERALL DIMENSIONS

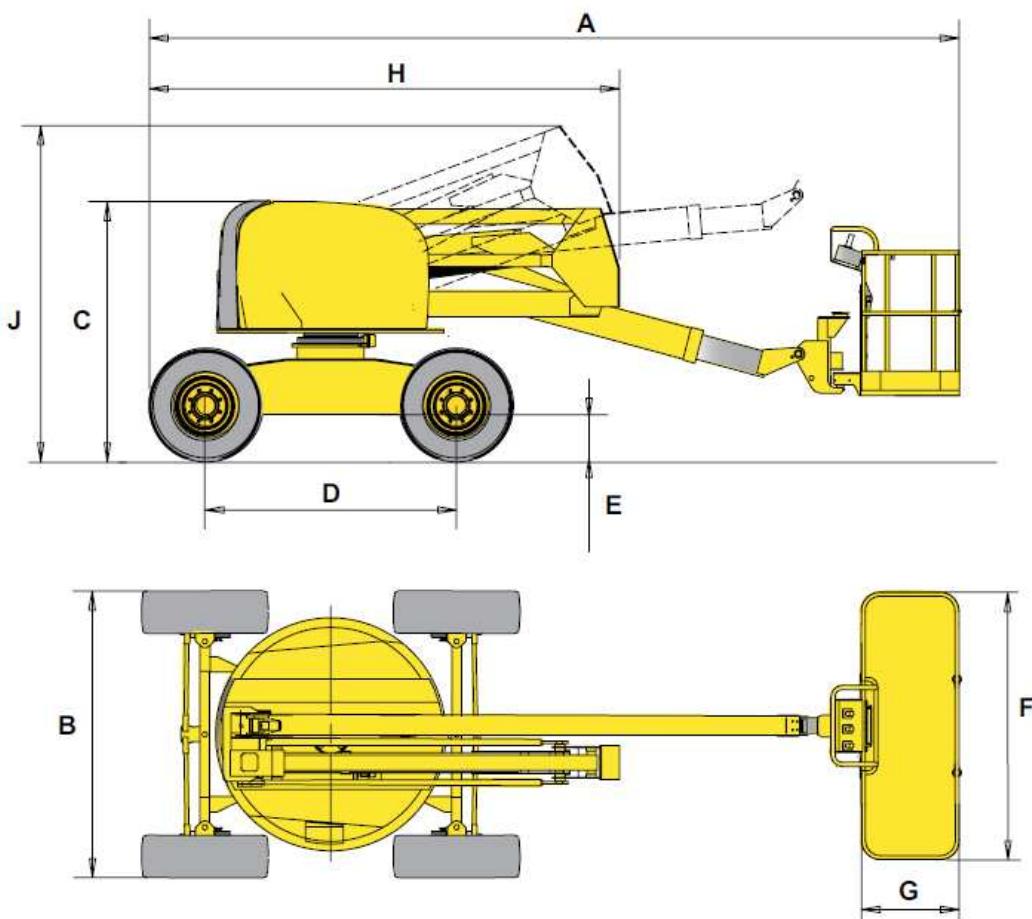
General diagram HA16PX (HA46JRT) - HA18PX  
(HA51JRT) - HA16SPX (HA46SJRT) - HA18SPX  
(HA51SJRT)



Marking	HA16PX (HA46JRT)		HA18PX (HA51JRT)	
	Mètre	Feet Inch	Mètre	Feet Inch
A	6,95	22 ft 9 in	7,60	24 ft 11 in
B	2,30	7 ft 6 in	2,30	7 ft 6 in
C	2,30	7 ft 7 in	2,30	7 ft 7 in
D	2,00	6 ft 7 in	2,00	6 ft 6 in
E	0,40	1 ft 3 in	0,40	1 ft 3 in
F x G	1,80/2,30 x 0,80	5 ft 10 in / 7 ft 6 in x 2 ft 7 in	1,80/2,30 x 0,80	5 ft 10 in / 7 ft 6 in x 2 ft 7 in
H	5,25	17 ft 2 in	5,90	19 ft 4 in
J	2,30	7 ft 7 in	2,30	7 ft 7 in

Marking	HA16SPX (HA46SJRT)		HA18SPX (HA51SJRT)	
	Mètre	Feet Inch	Mètre	Feet Inch
A	6,80	22 ft 3 in	7,50	24 ft 7 in
B	2,30	7 ft 6 in	2,30	7 ft 6 in
C	2,20	7 ft 2 in	2,20	7 ft 2 in
D	2,00	6 ft 7 in	2,00	6 ft 7 in
E	0,35	1 ft 1 in	0,35	1 ft 1 in
F x G	1,80 x 0,80	5 ft 10 in x 2 ft 7 in	1,80 x 0,80	5 ft 10 in x 2 ft 7 in
H	5,30	17 ft 4 in	5,80	19 ft 0 in
J	2,30	7 ft 6 in	2,30	7 ft 6 in

General diagram HA16X

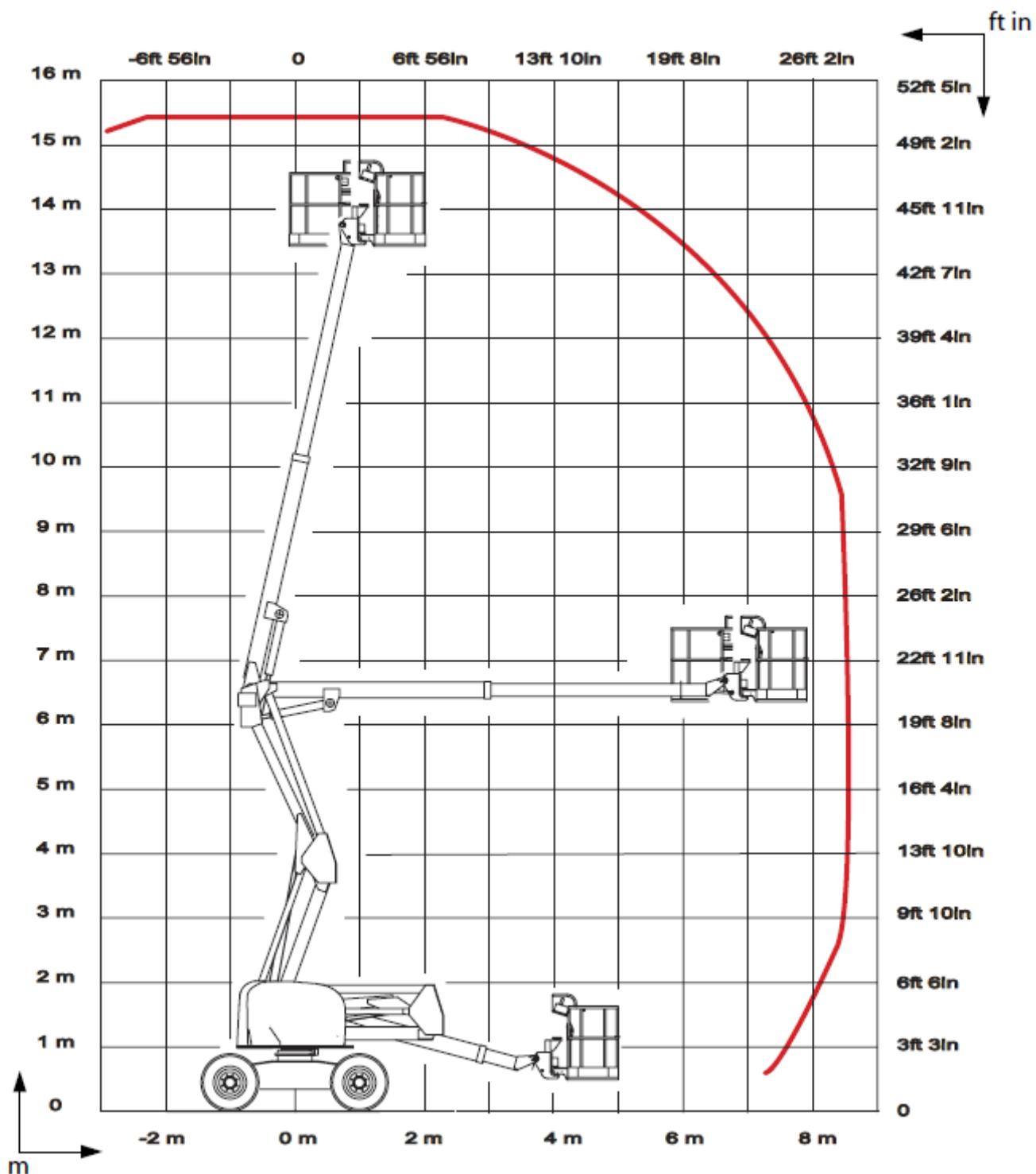


Marking	HA16X	
	Mètre	Feet Inch
A	6,70	22 ft 0 in
B	2,25	7 ft 5 in
C	2,08	6 ft 9 in
D	2,00	6 ft 7 in
E	0,37	1 ft 3 in
F x G	1,80/2,30 x 0,80	5 ft 10 in / 7 ft 6 in x 2 ft 7 in
H	6,70	21 ft 11 in
J	2,25	7 ft 5 in

### 1.2.3. WORKING ZONE

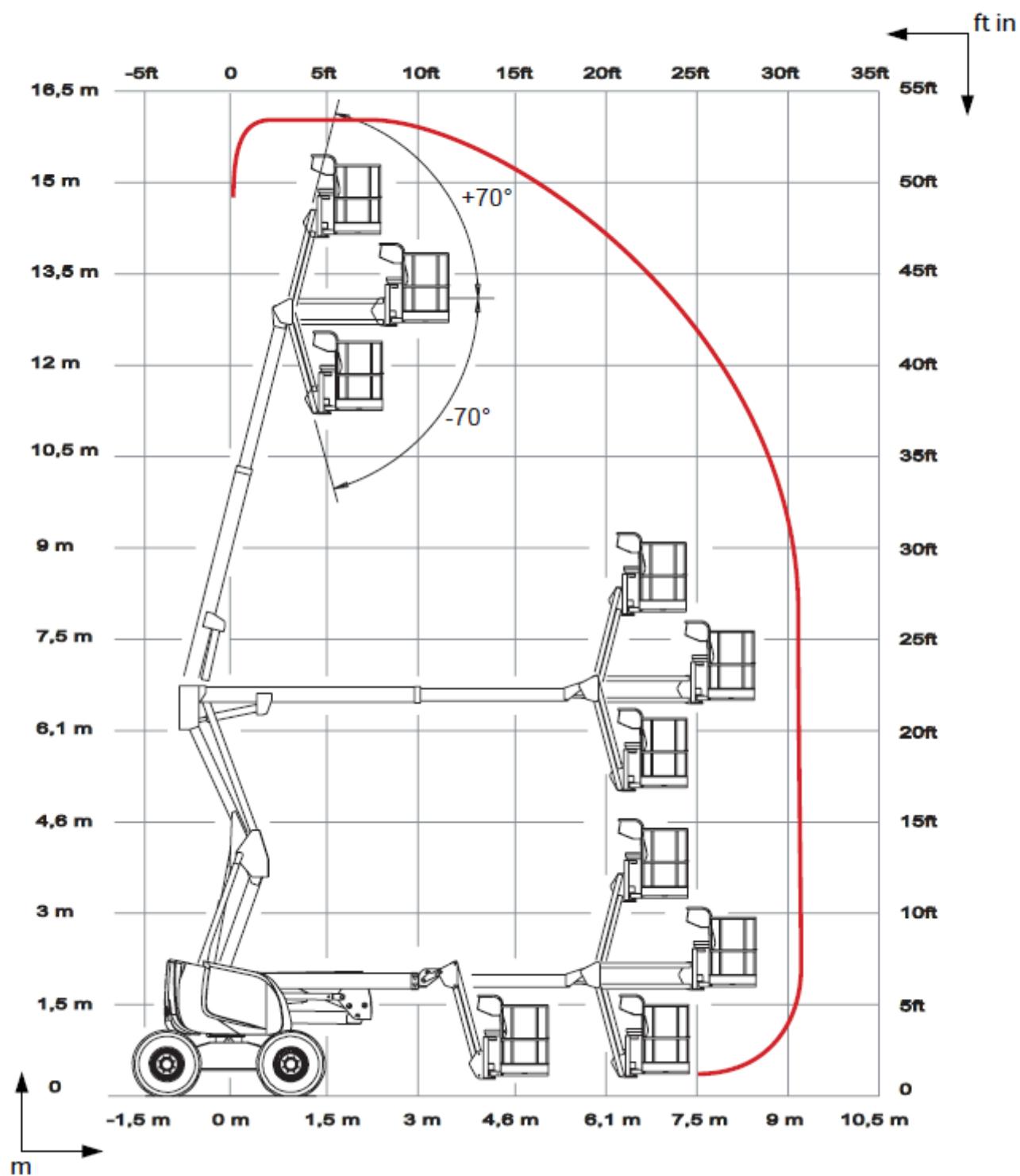
HA16X

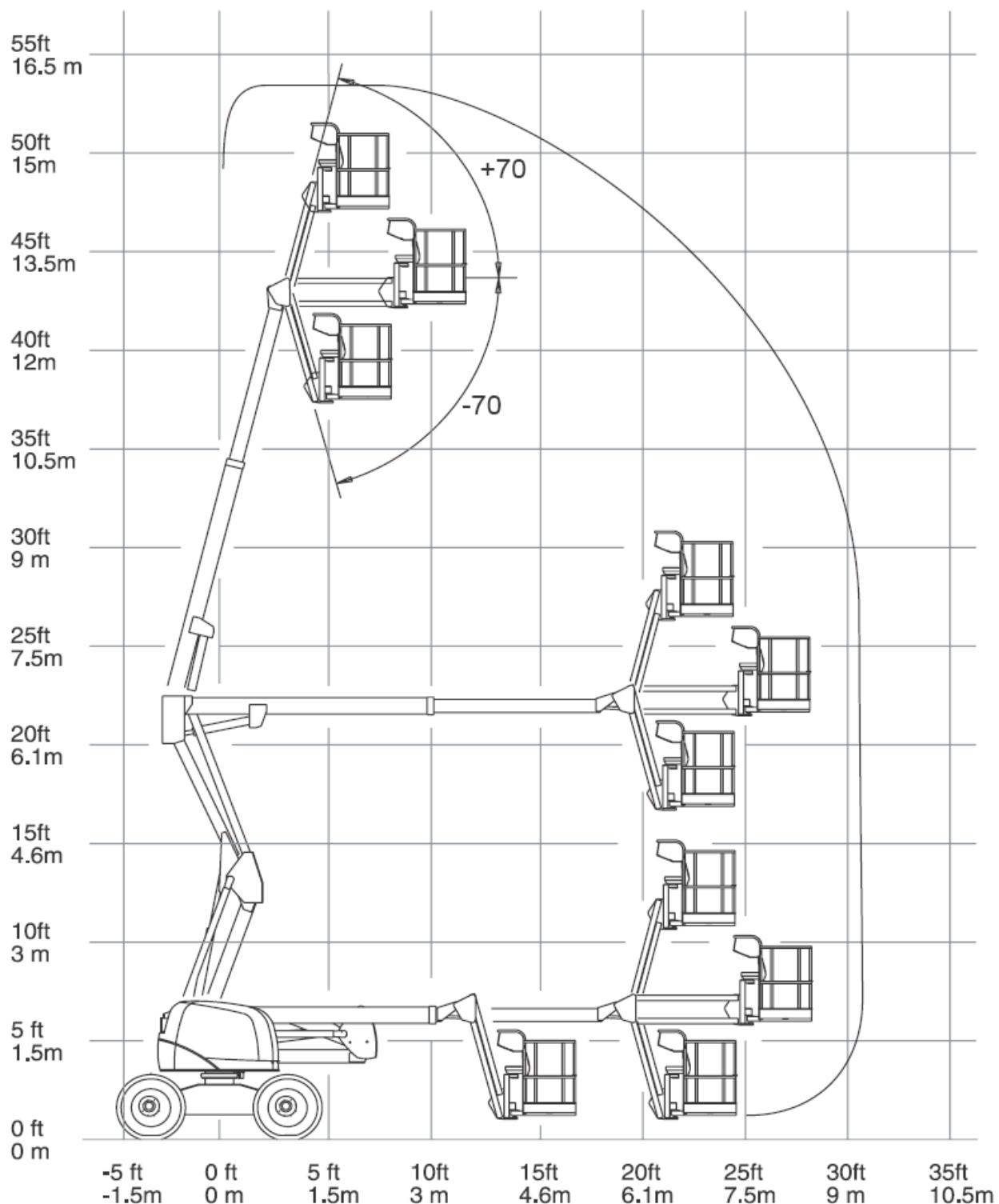
Working area



**MACHINE HA16PX (HA46JRT)**

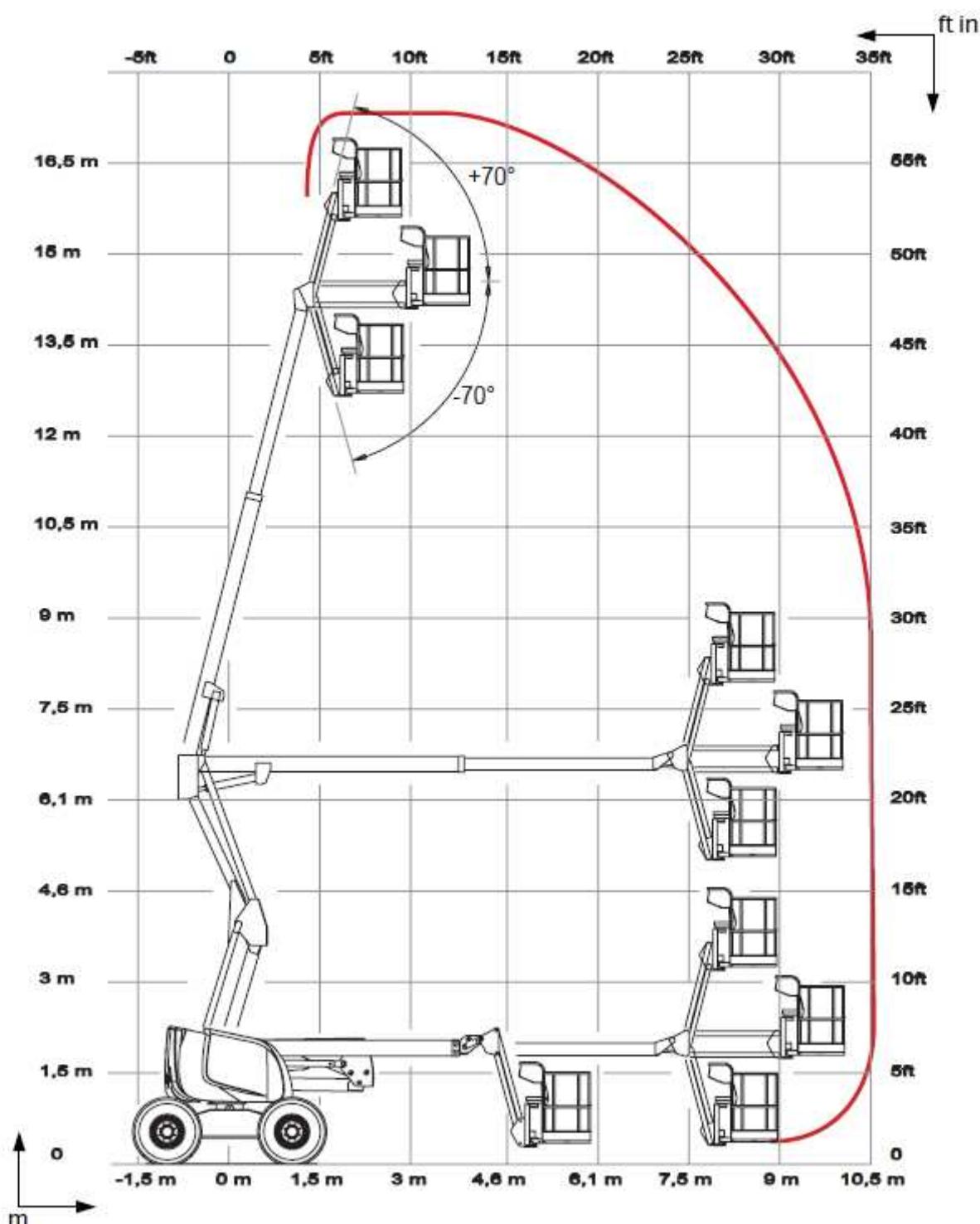
Working area





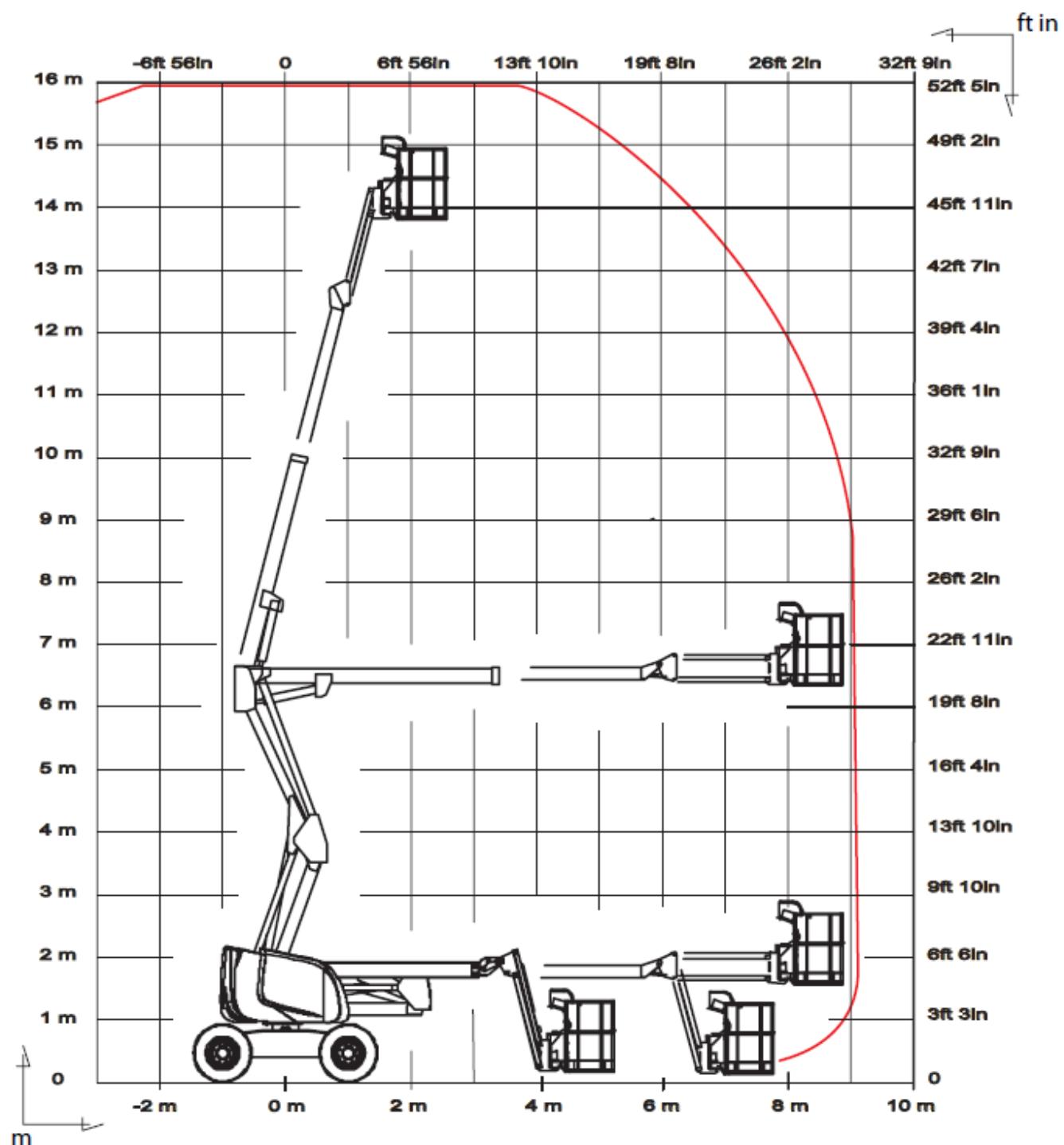
## MACHINE HA18PX (HA51JRT)

Working area



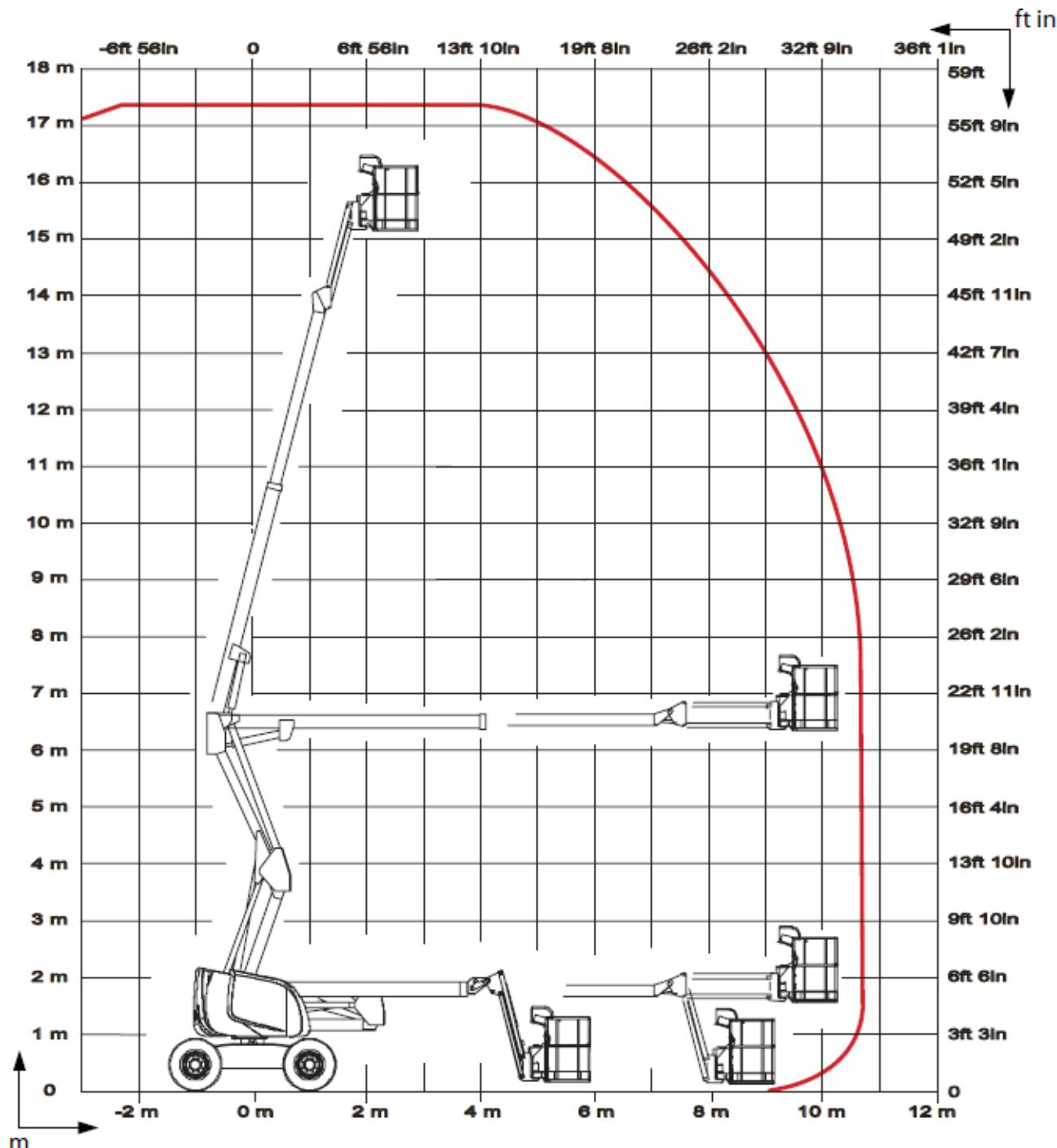
## MACHINE HA16SPX (HA46SJRT)

### Working area



### 3.6 - MACHINE HA18SPX (HA51SJRT)

#### Working area



## 1.2.4. FEATURES

Machine	HA16X	
Characteristics	Metric	Imperial
Length of machine in stowed position	7,60 m	(24 ft 11 in)
Width of the machine in stowed position	2,26 m	(7 ft 5 in)
Machine height	2,08 m	(6 ft 9 in)
Maximum ground clearance	0,35 m	(1 ft 1 in)
Transport height	2,26 m	(7 ft 5 in)
Transport length	6,70 m	(21 ft 11 in)
Maximum work height	15,45 m	(50 ft 8 in)
Maximum platform height	13,45 m	(44 ft 1 in)
Maximum drift	8,45 m	(27 ft 8 in)
Maximum radius	7,35 m	(24 ft 1 in)
Turntable rotation	350 °	
Boom rotation angle	+76° / -18° s	
Jib working range	+70° / -70° s	
Platform length	0,80 m	(2 ft 7 in)
Platform width	1,80 m -2,30 m	(5 ft 10 in) - (7 ft 6 in)
Platform rotation angle	+90° / -90° s	
Outer turning radius (without axle outriggers retracted)	9,30 m	(30 ft 6 in)
Inner turning radius (with axles retracted)	3,55 m	(11 ft 7 in)
Lateral distance between the wheels	2,00 m	(6 ft 6 in)
Tilt	5 °	
Maximum authorized wind speed	45 km/h	(28 mph)
Total weight	6500 kg	(14330 lb)
Maximum platform load	230 kg	(507 lb)
Engine type	Diesel - Deutz F3L1011F	
Engine power	28 kW	(38 Hp)
Engine power when idle	15 kW	(20,3 Hp)
Fuel consumption when idle	2309 g/kWh	
Sound level at 10 m (32 ft 9 in)	75 dB (A)	
Vibration in the hands	<2,5 m/s <sup>2</sup>	(98,4 in/s <sup>2</sup> )
Vibration in the feet	<0,5 m/s <sup>2</sup>	(19,6 in/s <sup>2</sup> )
Fuel tank capacity	55 l	(14 gal US)
Hydraulic tank capacity	100 l	(26 gal US)
Starter battery	12 V-95 Ah	
Differential blocking	Yes	
Maximum climbable slope	50 %	
Type of tyres	Foam-filled-14 x 17,5	
Maximum pressure on hard ground	10,1 bar	(146,4 psi)
Maximum pressure on soft ground	3 bar	(43,5 psi)
Low drive speed	0,4 km/h	(0,2 mph)
Medium-speed driving	1,5 km/h	(0,9 mph)
High drive speed	6,0 km/h	(3,7 mph)

Machine	HA16PX (HA46JRT)		HA18PX (HA51JRT)	
Characteristics	Metric	Imperial	Metric	Imperial
Length of machine in stowed position	6,95 m	(22 ft 9 in)	7,60 m	(24 ft 11 in)
Width of the machine in stowed position	2,30 m	(7 ft 6 in)	2,30 m	(7 ft 6 in)
Machine height	2,20 m	(7 ft 2 in)	2,20 m	(7 ft 2 in)
Maximum ground clearance	0,40 m	(1 ft 3 in)	0,40 m	(1 ft 3 in)
Transport height	2,15 m	(7 ft 0 in)	2,15 m	(7 ft 0 in)
Transport length	5,25 m	(17 ft 2 in)	5,90 m	(19 ft 4 in)
Maximum work height	16,00 m	(52 ft 5 in)	17,30 m	(56 ft 9 in)
Maximum platform height	14,00 m	(45 ft 11 in)	15,30 m	(50 ft 2 in)
Maximum drift	9,10 m	(29 ft 10 in)	10,60 m	(34 ft 9 in)
Maximum radius	8,70 m	(28 ft 6 in)	10,07 m	(33 ft 0 in)
Turntable rotation	360 °			
Boom rotation angle	+74° / -3° s			
Jib working range	+70° / -70° s			
Platform length	0,80 m	(2 ft 7 in)	0,80 m	(2 ft 7 in)
Platform width	1,80 m -2,30 m	(5 ft 10 in) - (7 ft 6 in)	1,80 m -2,30 m	(5 ft 10 in) - (7 ft 6 in)
Platform rotation angle	+90° / -90° s			
Outer turning radius (without axle outriggers retracted)	4,00 m	(13 ft 1 in)	4,00 m	(13 ft 1 in)
Inner turning radius (with axles retracted)	1,90 m	(6 ft 2 in)	1,90 m	(6 ft 2 in)
Lateral distance between the wheels	2,00 m	(6 ft 6 in)	2,00 m	(6 ft 6 in)
Tilt	5 °			
Maximum authorized wind speed	60-45 km/h	(37 - 28 mph)	60-45 km/h	(37 - 28 mph)
Total weight	7240 kg	(15961 lb)	8120 kg	(17901 lb)
Maximum platform load	230 kg	(507 lb)	230 kg	(507 lb)
Engine type	Diesel - Deutz F3L1011F			
Engine power	28 kW	(38 Hp)	28 kW	(38 Hp)
Engine power when idle	15 kW	(20,3 Hp)	15 kW	(20,3 Hp)
Fuel consumption when idle	2309 g/kWh			
Sound level at 10 m (32 ft 9 in)	75 dB (A)			
Vibration in the hands	<2,5 m/s <sup>2</sup>	(98,4 in/s <sup>2</sup> )	<2,5 m/s <sup>2</sup>	(98,4 in/s <sup>2</sup> )
Vibration in the feet	<0,5 m/s <sup>2</sup>	(19,6 in/s <sup>2</sup> )	<0,5 m/s <sup>2</sup>	(19,6 in/s <sup>2</sup> )
Fuel tank capacity	72 l	(19 gal US)	72 l	(19 gal US)
Hydraulic tank capacity	100 l	(26 gal US)	100 l	(26 gal US)
Starter battery	12 V-95 Ah			
Differential blocking	Yes			
Maximum climbable slope	50 %			
Type of tyres	Foam-filled-385/65D22,5			
Wheel nut torque	32,5 daN.m	(236 lbf.ft)	32,5 daN.m	(236 lbf.ft)
Slew ring torque	21,5 daN.m	(158 lbf.ft)	21,5 daN.m	(158 lbf.ft)
Maximum pressure on hard ground	8 bar	(116 psi)	8,2 bar	(118 psi)
Maximum pressure on soft ground	3,2 bar	(46 psi)	3,6 bar	(52 psi)
Micro drive speed	0,22 km/h	(0,1 mph)	0,22 km/h	(0,1 mph)
Low drive speed	0,38 km/h	(0,2 mph)	0,38 km/h	(0,2 mph)
Medium-speed driving	0,77 km/h	(0,4 mph)	0,77 km/h	(0,4 mph)
High drive speed	1,52 km/h	(0,9 mph)	1,52 km/h	(0,9 mph)

Machine	HA16SPX (HA46SJRT)		HA18SPX (HA51SJRT)	
Characteristics	Metric	Imperial	Metric	Imperial
Length of machine in stowed position	6,80 m	(22 ft 3 in)	7,50 m	(24 ft 7 in)
Width of the machine in stowed position	2,30 m	(7 ft 6 in)	2,30 m	(7 ft 6 in)
Machine height	2,20 m	(7 ft 2 in)	2,20 m	(7 ft 2 in)
Maximum ground clearance	0,35 m	(1 ft 1 in)	0,35 m	(1 ft 1 in)
Transport height	2,25 m	(7 ft 4 in)	2,25 m	(7 ft 4 in)
Transport length	5,30 m	(17 ft 4 in)	5,80 m	(19 ft 0 in)
Maximum work height	16,00 m	(52 ft 5 in)	17,30 m	(56 ft 9 in)
Maximum platform height	14,00 m	(45 ft 11 in)	15,30 m	(50 ft 2 in)
Maximum drift	9,10 m	(29 ft 10 in)	10,60 m	(34 ft 9 in)
Maximum radius	8,60 m	(28 ft 2 in)	10,00 m	(32 ft 9 in)
Turntable rotation	350 °			
Boom rotation angle	+75° / -0° s			
Jib working range	+70° / -70° s			
Platform length	0,80 m	(2 ft 7 in)	0,80 m	(2 ft 7 in)
Platform width	1,80 m	(5 ft 10 in)	1,80 m	(5 ft 10 in)
Platform rotation angle	+90° / -90° s			
Outer turning radius (without axle outriggers retracted)	9,30 m	(30 ft 6 in)	9,30 m	(30 ft 6 in)
Inner turning radius (with axles retracted)	3,55 m	(11 ft 7 in)	3,55 m	(11 ft 7 in)
Lateral distance between the wheels	2,00 m	(6 ft 6 in)	2,00 m	(6 ft 6 in)
Tilt	5 °			
Maximum authorized wind speed	45 km/h	(28 mph)	45 km/h	(28 mph)
Front-axle load	2700 kg	(5952 lb)	. kg	(. lb)
Rear-axle load	3900 kg	(8598 lb)	. kg	(. lb)
Total weight	6600 kg	(14550 lb)	7500 kg	(16534 lb)
Maximum platform load	230 kg	(507 lb)	230 kg	(507 lb)
Engine type	Diesel - Deutz F3L2011F			
Engine power	30,9 kW	(42 Hp)	30,9 kW	(42 Hp)
Engine power when idle	15 kW	(20,3 Hp)	15 kW	(20,3 Hp)
Fuel consumption when idle	2309 g/kWh			
Sound level at 10 m (32 ft 9 in)	75 dB (A)			
Vibration in the hands	<2,5 m/s <sup>2</sup>	(98,4 in/s <sup>2</sup> )	<2,5 m/s <sup>2</sup>	(98,4 in/s <sup>2</sup> )
Vibration in the feet	<0,5 m/s <sup>2</sup>	(19,6 in/s <sup>2</sup> )	<0,5 m/s <sup>2</sup>	(19,6 in/s <sup>2</sup> )
Fuel tank capacity	55 l	(14 gal US)	55 l	(14 gal US)
Hydraulic tank capacity	100 l	(26 gal US)	100 l	(26 gal US)
Starter battery	12 V-95 Ah			
Differential blocking	Yes			
Maximum climbable slope	40 %			
Type of tyres	Foam-filled-14 x 17,5			
Wheel nut torque	32,5 daN.m	(236 lbf.ft)	32,5 daN.m	(236 lbf.ft)
Slew ring torque	21,5 daN.m	(158 lbf.ft)	21,5 daN.m	(158 lbf.ft)
Maximum pressure on hard ground	10,1 bar	(146 psi)	13 bar	(188 psi)
Maximum pressure on soft ground	3 bar	(43 psi)	3,5 bar	(50 psi)
Micro drive speed	0,7 km/h	(0,4 mph)	0,7 km/h	(0,4 mph)
Low drive speed	1,5 km/h	(0,9 mph)	1,5 km/h	(0,9 mph)
Medium-speed driving	2,3 km/h	(1,4 mph)	2,3 km/h	(1,4 mph)
High drive speed	5,5 km/h	(3,4 mph)	5,5 km/h	(3,4 mph)

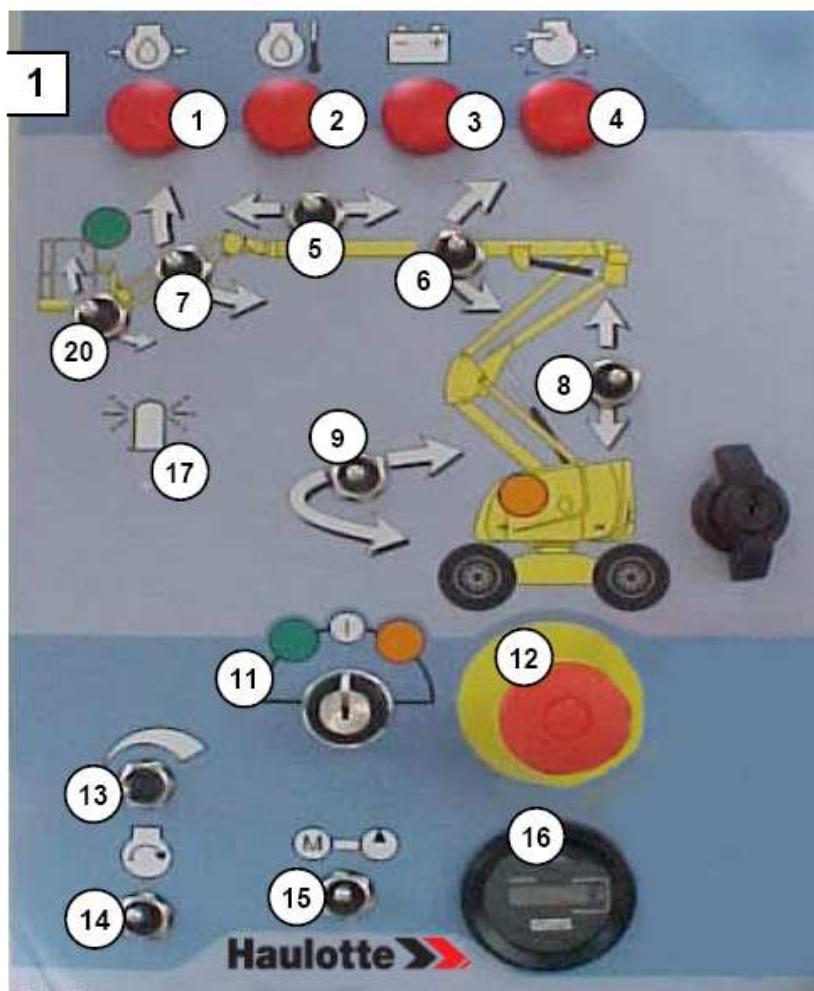
Machine Characteristics	HA16PX (HA46JRT)	HA18PX (HA51JRT)	
Metric	Imperial	Metric	Imperial
Petrol / gas engine		PSI OPU-9T CPLG-PHSG-ZDFS	
Engine power	23 kW 2400 tr/mn	(31 Hp) 2400 rpm	23 kW 2400 tr/mn (31 Hp) 2400 rpm
Engine power when idle		From 1200 tr/mn to 2400 tr/mn	
Sound level at 10 m (32 ft 9 in)		<104 dB (A)	
Petrol supply			
Fuel tank capacity	72 l	(19 gal US)	72 l (19 gal US)

### 1.3. THE COMMANDS (UP/DOWN)



## Controls and indicators

Marking	Description	Function
26	Fault indicator	Operation malfunction <sup>1</sup> Machine on excessive slope
30	Platform overload indicator	Platform overload
31	Power ON indicator	On : Machine switched on Off : Machine switched off
32	Radius limitation indicator	The indicator flashes : Close to radius limitation The indicator flashes continuously : Radius limitation reached
33	Drive joystick	Move forward : Forward drive Move backward : Reverse drive
	Front axle steering selector	Press right side of button : Right-hand steering Press left side of button : Left-hand steering
34	Rear axle steering selector	Move to the right : Right-hand steering Move to the left : Left-hand steering
	Differential lock selector	Press in and hold (activated) : Maximum drive torque (on difficult or sloping ground) Release (deactivated) : Standard torque
37	Jib lifting / lowering selector	Move upwards : Jib lifting Move downwards : Jib lowering
	Platform rotation selector	Move to the right : Counter clockwise (CCW) rotation Move to the left : Clockwise rotation
40	Platform leveling selector	Move upwards : Lifting of platform Move downwards : Lowering of platform
	Back-up unit selector	Press in and hold : Back-up unit activated Release : Back-up unit deactivated
42	Engine start-up selector	Starting the engine
43	Horn selector	Horn
44	Petrol/Gas selector <sup>2</sup>	LPG : Gas supply G : Petrol or Optional diesel power supply
	Emergency stop button	Pulled out (activated) : Ground control box energized Pushed down (deactivated) : De-energizes control system



## Controls and indicators

Marking	Description	Function
1	Electric pre-heating indicator	On : Engine in pre-heating mode Off : Engine pre-heated, starting possible
2	Engine oil pressure light	Low engine oil pressure <sup>1</sup>
3	Engine temperature indicator	High engine oil temperature <sup>(1.)</sup>
4	Battery charge indicator	Low battery charge <sup>(1.)</sup>
5	Air filter clogging indicator	Clogged air filter <sup>(1.)</sup>
6	Platform overload indicator	Platform overload
		Close to radius limitation : • The indicator flashes • Movement is slowed down
7	Radius limitation indicator	Radius limitation reached : • The indicator flashes continuously • An automatic movement is performed to return to the authorized radius limitation
8	Jib lifting / lowering selector	Move upwards : Jib lifting Move downwards : Jib lowering
9	Boom telescoping selector	Move to the left : To telescope out Move to the right : To telescope in
10	Boom raising selector	Move upwards : Boom raising Move downwards : Boom lowering
12	Arm lifting selector	Move upwards : Arm lifting Move downwards : Boom lowering
13	Platform levelling or transport position selector	Move to the right : Platform leveling lowered or placed in transport position Move to the left : Platform compensation lifted or placed in operating position
14	Turntable rotation selector	Move to the left : Counter clockwise (CCW) rotation Move to the right : Clockwise rotation
15	Emergency stop button	Pulled out (activated) : Ground control box energized Pushed down (deactivated) : De-energizes control system
19	Back-up unit selector <sup>2</sup>	Press in and hold : Back-up unit activated Release : Back-up unit deactivated
20	Hour meter	Total machine running hours
21	Engine acceleration selector	Move to the right : Engine speed increases Move to the left : Engine idle speed
22	Engine start-up selector	Starting the engine
23	Petrol/Gas selector <sup>3</sup>	LPG : Gas supply G : Petrol or Optional diesel power supply
24	Beacon light on/off	Move upwards : Beacon light on Move downwards : Beacon light off
72	Control box energizing key selector	Left : Platform control box energized Center : De-energizes control system Right : Ground control box energized
167	Engine temperature indicator <sup>4</sup>	Coolant temperature
228	'Enable Switch' selector / Back-up unit selector <sup>5</sup>	Move upwards : Movement validation Move downwards : Back-up unit activatedMovement validation

1. Perform the required maintenance (see the machine maintenance book)

2. For machines fitted with

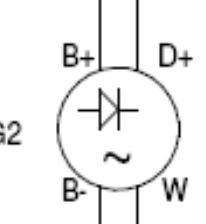
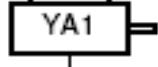
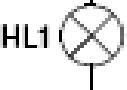
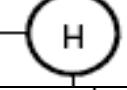
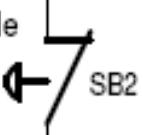
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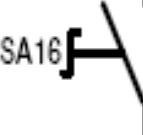
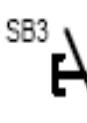
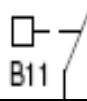
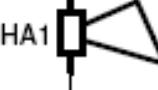
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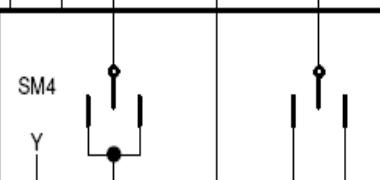
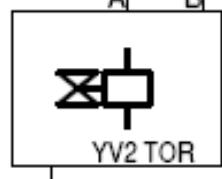
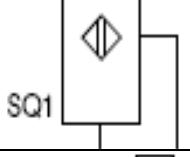
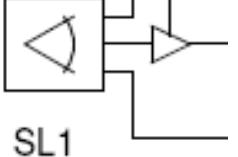
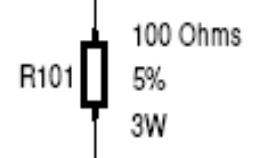
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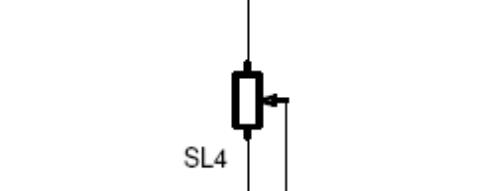
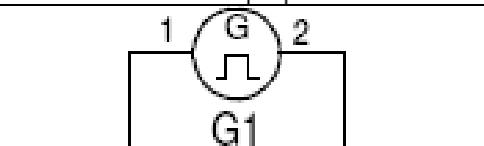
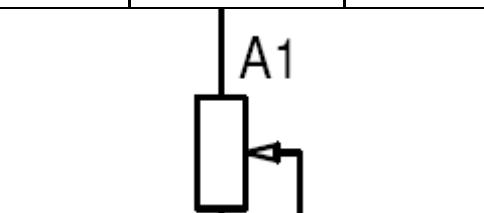
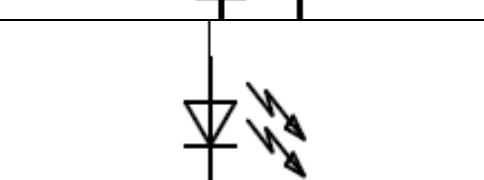
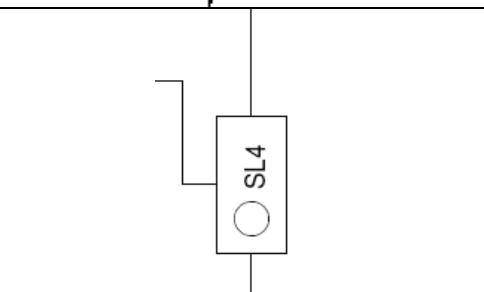
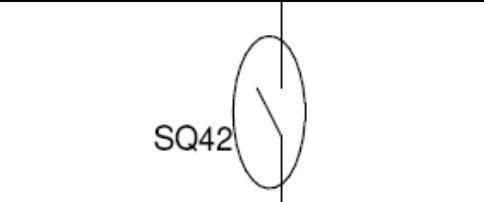
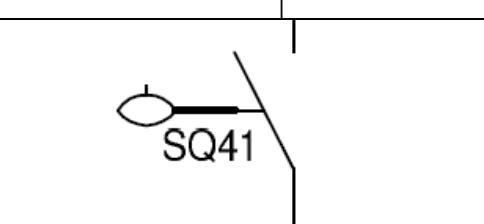
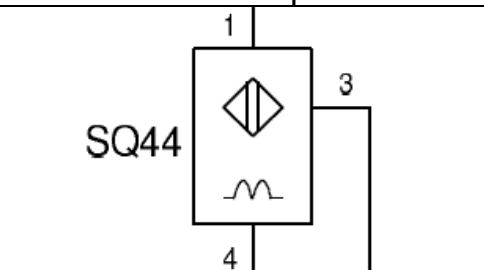
## 2. THE ELECTRICAL PART

### 2.1. SYMBOLS USED

	GB1	Battery with one element
	G2	Alternator
	FU4 10A	Fuse (Here 10 amps)
	YA1	Coil doble roll
	M4	Electric motor
	HL1	light
	D5	Diode
	H	Hourmeter
	AU Nacelle SB2	Standard push-button of safety "mushroom-headed button"

	Rotary knob
	Push-button
	Limit switch
	Pressure switch
	Key selector with 3 positions (T turret, O neutral, N platform)
	Toggle switch with 2 positions
	Electrovalve
	relay
	horn
	Proportional electrovalve

	Controller/joysticks
	Pedals "dead man" or "foot dead man" switch
	buzzer
	"light"
	Electrovalve "ON/OFF" (bang-bang)
	Tilt sensor (ramp detection)
	Angle sensor (reach limitation)
	Contact "mercury" (angle detection)
	Resistor (here value 100 ohms, 3 Watts, tolerance of 5%)

	Sensor length (reach limitation)
	Pressure sensor (weighing)
	Angle sensor (weighing)
	Standard light "Led"
	Strain gauge
	Flexible Blade Switch (ILS) detection of the magnets on the telescopic boom/arm extension
	Level detector (diesel tank)
	Proximity detector with impulses (detection teeth slew ring)

## 2.2. METHODOLOGY OF CONTROL

**Note:** during an intervention on a component or a loom, it is important to remember to switch OFF the power supply of the machine in order to avoid any risk.

### 2.2.1. ELECTRIC CONTINUITY CONTROL

The continuity check of a loom or an electric component determines the resistor of this device, in order to detect a possible interruption of continuity (open circuit, short-circuit...).

This control is carried out with a multimeter commutated in position Ohmmeter ( $\Omega$ ).

First of all, it is necessary to determine the terminals of the component or the cable to control and insulate them.

Then, connect the multimeter in order to record the value.

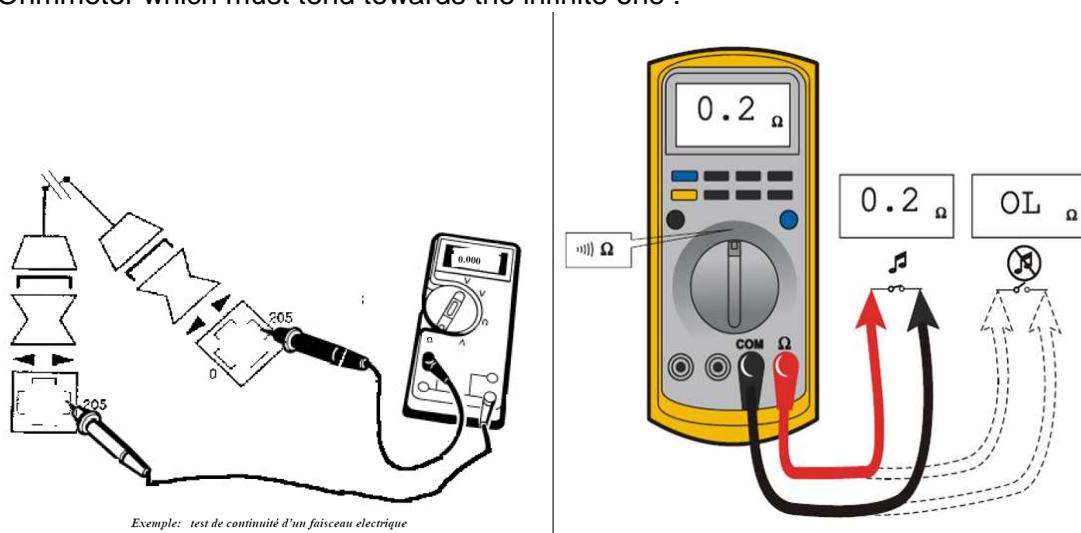
It must indicate a value of resistor close to  $0 \Omega$  if continuity is good.

In the contrary case (resistor which tends towards the infinite one :  $\infty$ ), continuity presents a defect.

#### Control of insulation

At the contrary of continuity, insulation represents a non electric connection between the ground and the component

The test of insulation consists in obtaining the opposite result of that described for continuity, i.e. a value of the Ohmmeter which must tend towards the infinite one :  $\infty$



### 2.2.2. CONTROL OF AN ON/OFF VALVE

Note: These tests are to be carried out when power is ON .

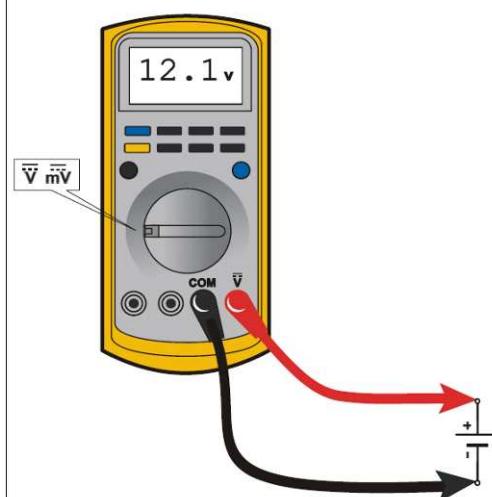
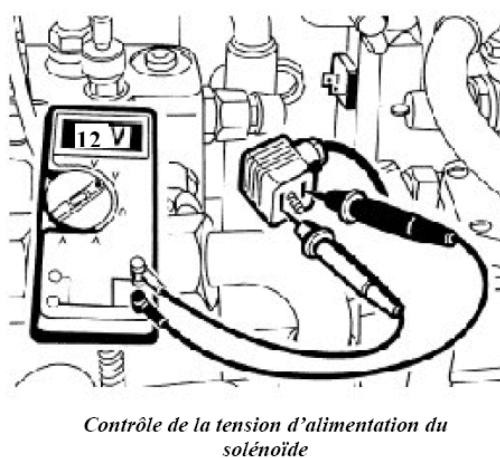
Also control the state of the terminals or any other connectors (oxydation...)

#### Control supply of the coil

Disconnect the plug socket of supply of the valve in order to connect in derivation the multimeter on the terminals of the connector (see below).

Select the position to voltmeter (V), then activate the command to the valve which must be tested.

The voltage indicated by the voltmeter must be close to the tension of battery



### Control intensity of the coil

Disconnect the plug socket of supply of the valve in order to connect in series the multimeter on the terminals of the connector (example below).

Select the position Ammeter (A), then activate the command to the valve which must be tested.

The intensity indicated by the voltmeter must be of approximately 2A (to be checked according to the data manufacturer)



### Control resistance of the coil

Disconnect the plug socket of supply of the valve in order to connect the multimeter on the terminals of the connector industry.

Select the position Ohmmeter ( $\Omega$ ), then compare the value measured with that of the data manufacturer. In the event of nonconformity of the coil, replace it.

## 2.2.3. CONTROL OF COMPONENTS

- **Control of an electric relay**

Disconnect the relay, then locate its various terminals.

Control the resistor of the solenoid terminals 85 and 86 (see manufacturer datas) using a multimeter in Ohmmeter position.

If the resistor is null, change the relay.

If this test is OK, check continuity between terminals 30 and 87a and insulation between terminals 30 and 87

In the event of dysfunction, replace the relay.

- **supply control of the relay**

Locate the relay without disconnecting it and locating its various terminals.

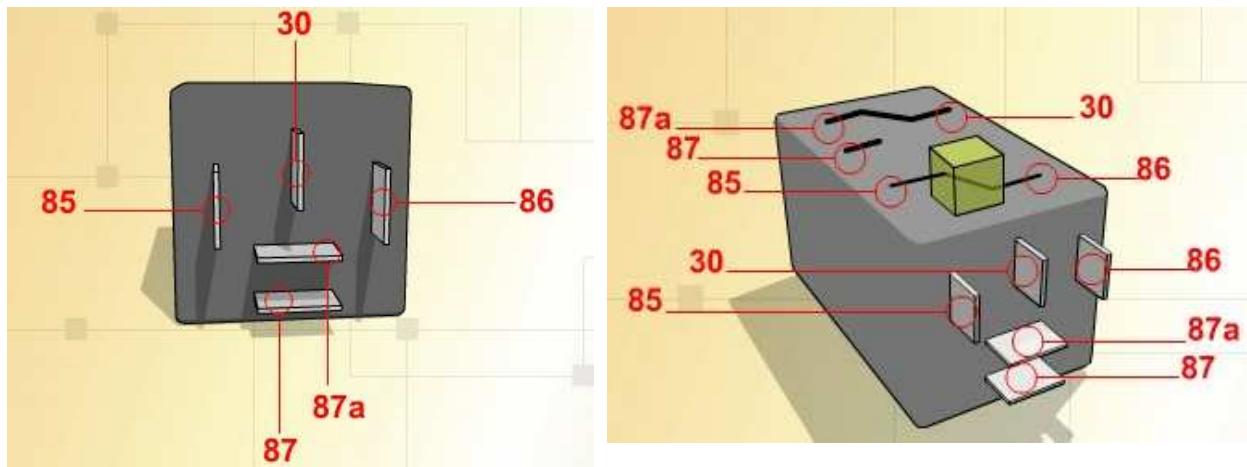
Control the continuity of terminal 86 with the ground

.(In the event of defect of continuity, check the concerned loom)

Connect the multimeter in position Voltmeter (V) between terminal 30 and the ground and thus control the power supply of the component (It must be close to the battery voltage Vbat)

Select the function of this relay and check the output voltage between terminal 87 and ground.

In the event of dysfunction, replace the relay



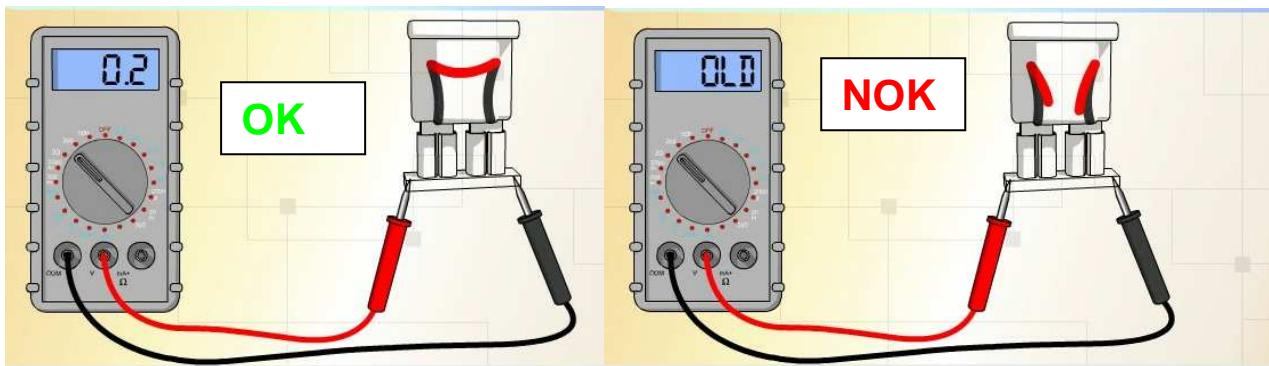
- Control of a fuse

### Color code

Intensité	Couleur		
	Mini. fusible	Fusible	Maxi. fusible
3 A	Violet	Violet	
5 A	Beige	Beige	
7.5 A	Marron	Marron	
10 A	Rouge	Rouge	
15 A	Bleu	Bleu	
20 A	Jaune	Jaune	
25 A	Blanc	Blanc	
30 A	Vert	Vert	
40 A		Orange	Orange
50 A			Rouge
60 A			Bleu
70 A			Marron

### Fuse check

Multimeter in  $\Omega$  position, it must indicate a value near 0



- Control of a diode

Locate the diode and disconnect it from the loom.

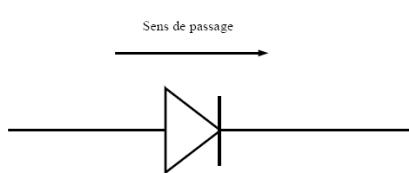
Control must be done with a multimeter in "diode" position.

Connect the multimeter on each terminal of the diode, in one direction then on the other.

In one direction, the diode should have no continuity,

in the other it must beep

If the diode is beeping in both ways, replace it.



Représentation normalisée d'une diode

## 2.3. THE WIRING DIAGRAM

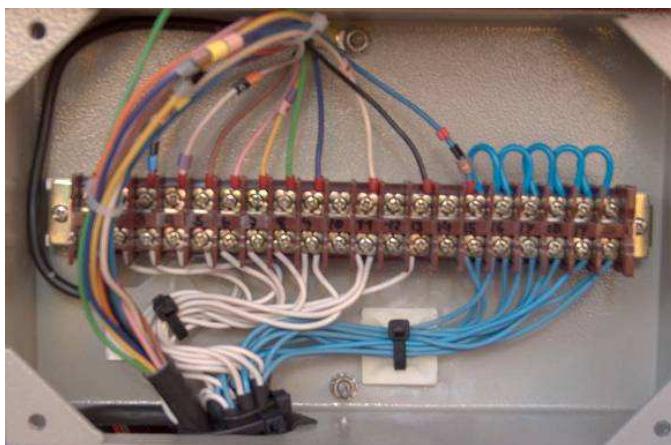
See all versions at the end of this manual

## 2.4. THE MAIN PRINTED CIRCUIT (LOW CONTROL BOX)

See at the end of this manual

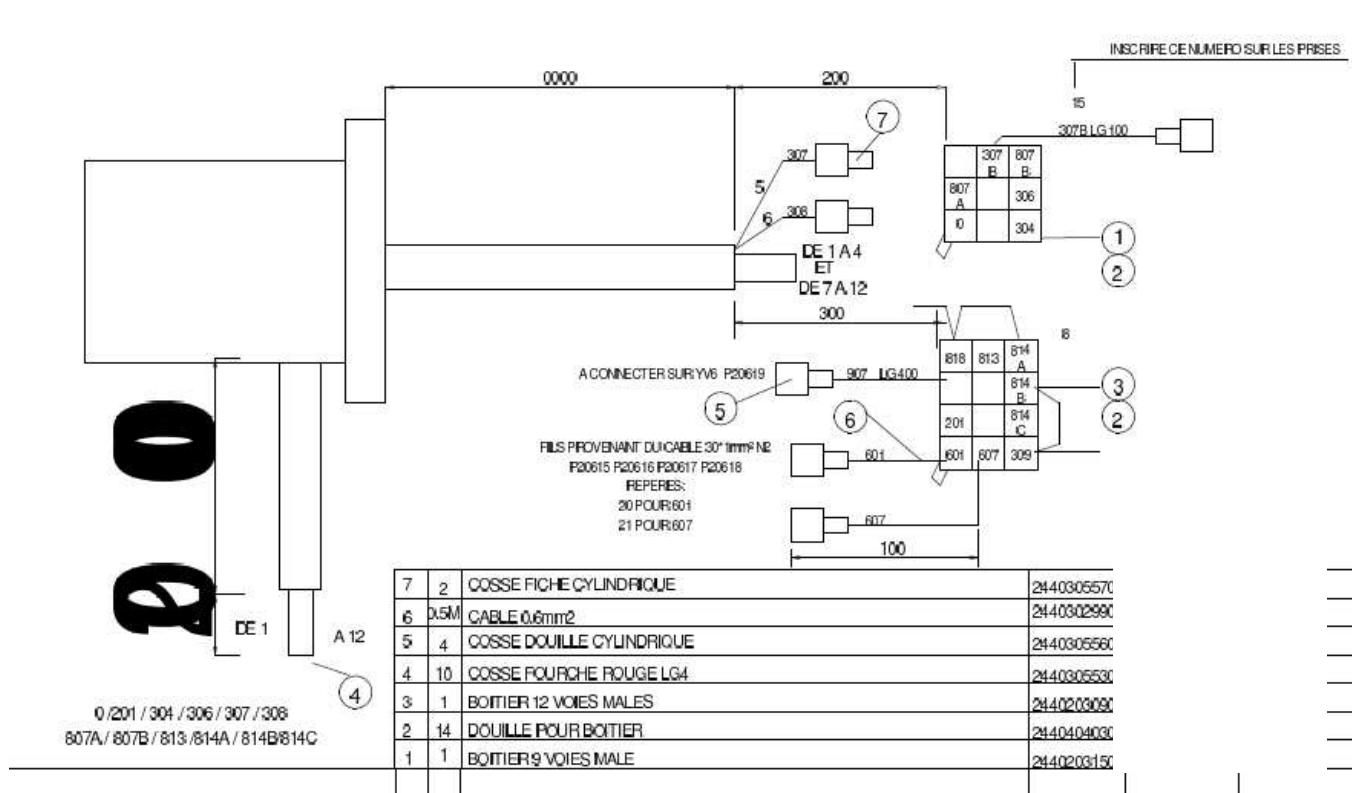
## 2.5. LOOMS

### 2.5.1. JUNCTION BOX (CHASIS)

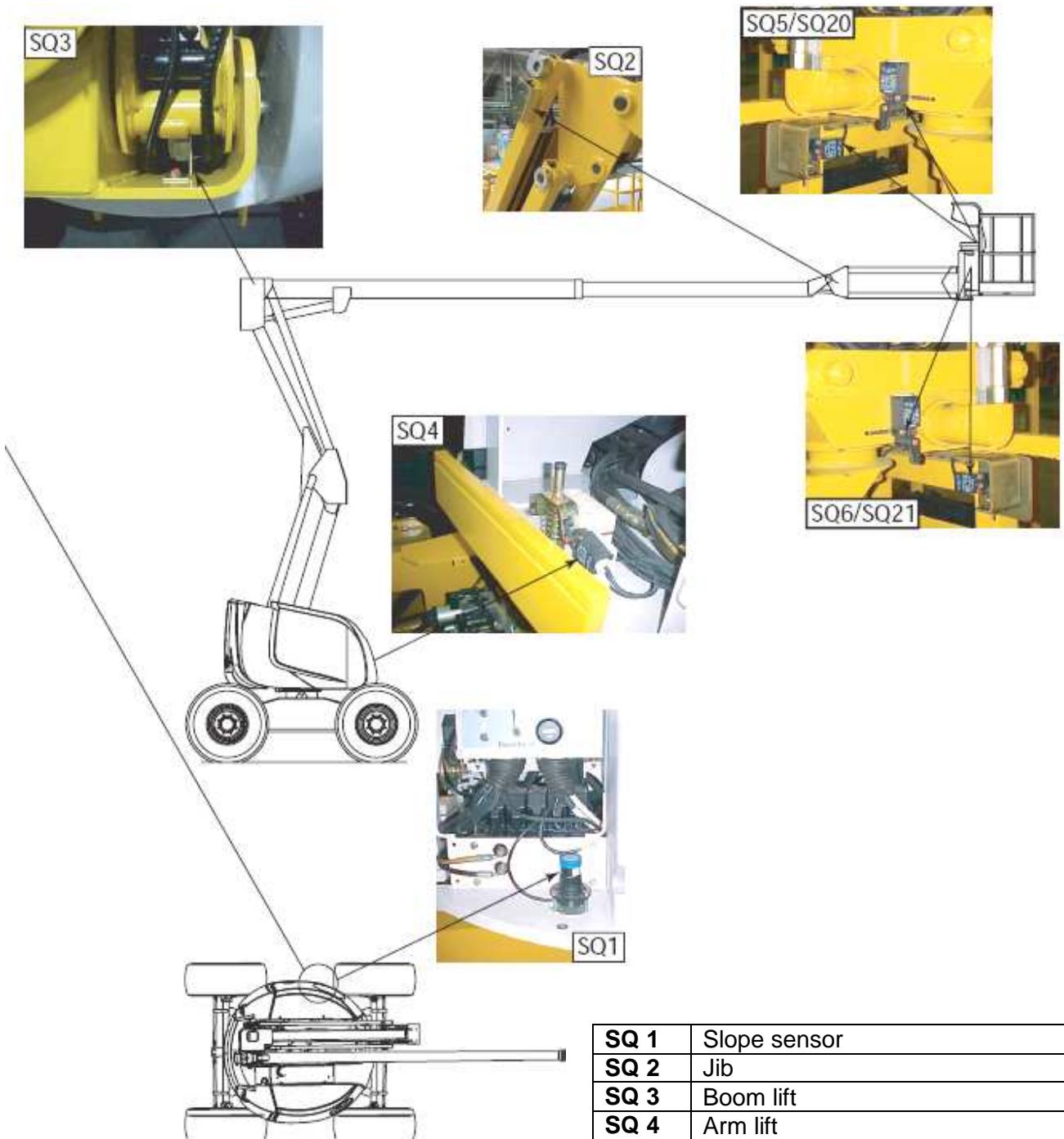


Locate cables terminal block	Electrovalve	Cables color
1		0 - orange
2	YV22A	red
3	YV22B	306 - purple
4	YV21A	307 - white
5	YV21B	308 - brown
6	YV9	807A - pink
7	YV13	807 B - yellow
8	YV8	813 green
9	YV10-YV23	814A dark blue
11	YV12-YV17	814 B light brown
13	YV11	814C black
15-20	+ EV	201 blue

## 2.5.2. SLIP RING (P20620)

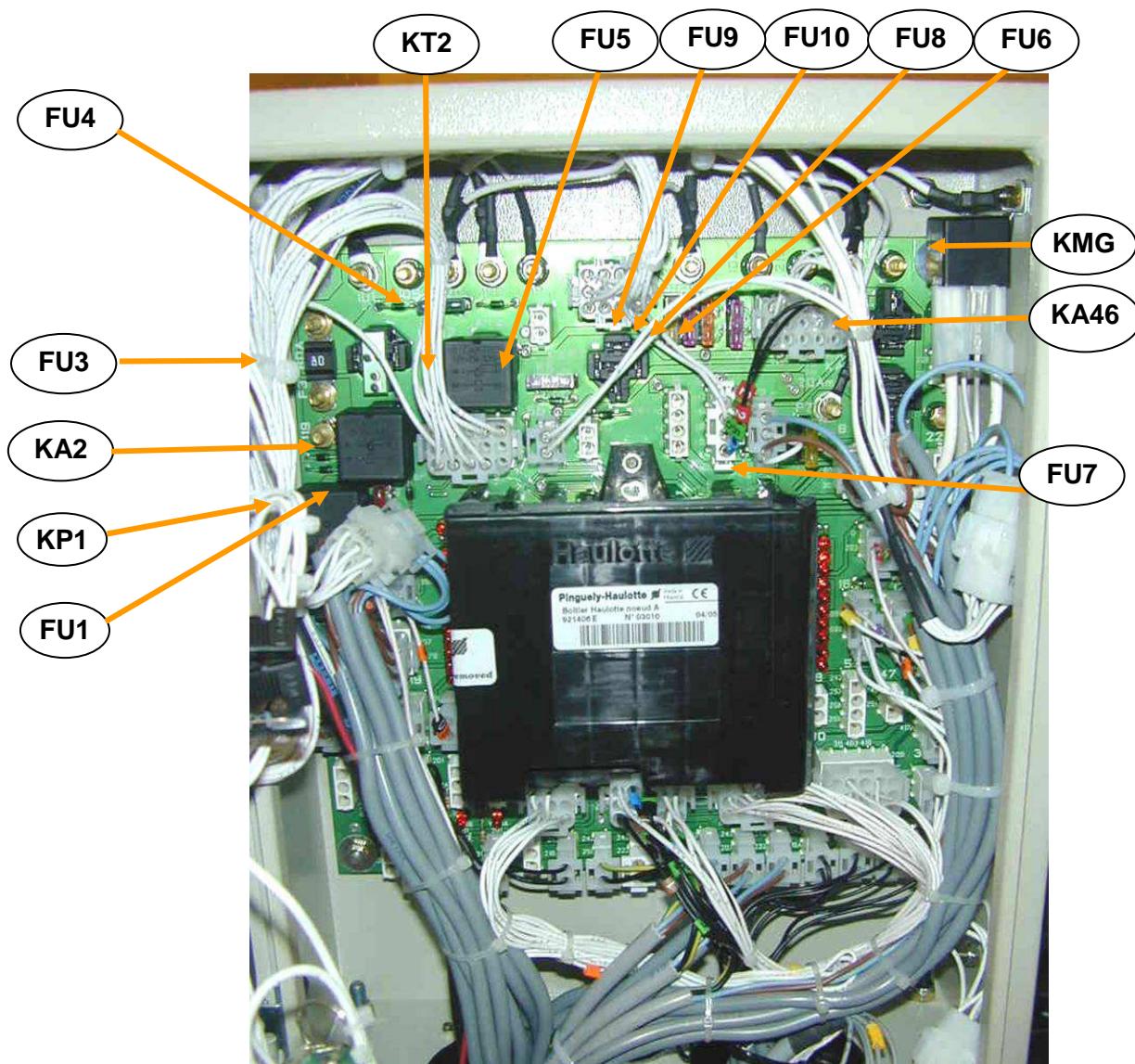


## 2.6. THE MAIN SAFETY COMPONENTS



<b>SQ 1</b>	Slope sensor
<b>SQ 2</b>	Jib
<b>SQ 3</b>	Boom lift
<b>SQ 4</b>	Arm lift
<b>SQ 5</b>	Overload
<b>SQ 6</b>	Overload
<b>SQ 20</b>	Basket rotation left side
<b>SQ 21</b>	Basket rotation right side

## 2.7. LIST OF COMPONENTS



In the following tables

the column n°2 gives the coordinates of the components on different sheets from the wiring schematics in order to find their position easily.

The first figure corresponds to the number of page and to the second to the column (generally from 1 to 20) of the corresponding page

the column n°3 indicates the position on the connector of the printed circuit board or the module if it is necessary

The state noted "0" corresponds to 0V, opened contact or not activated.

The state noted "1" corresponds to the tension of the circuit, closed or activated contact.

## 2.7.1. ENGINE

ENGINE ELEMENTS		
M3	01 – 4	Starter
G2	01 – 10	Alternator
YA2	01 – 15	Accelerator valve coil
YA1	01.-18	Start/stop engine valve coil
U1		Head module

## 2.7.2. FUSES

FUSES			
FU1	01 – 18		Engine stop 10A (115)
FU3	01 – 15		Accelerator 80A (119)
FU4	02 – 3		+ main 30A (120)
FU5	02 – 8		+ turret 30 A(212)
FU6	02.-11		+ platform 3A (211)
FU7	02.-12		+ valves 20A (201) if valve permanently: FU7 blows up
FU8	02 – 13		+ permanent 5A (242)
FU9	02 – 15		+ accessories 20A (905)
FU10	04 – 12		+ YV1 Load Sensing 3A (302)
FU11	01 – 3		+ emergency pump 250A (100)
FU13	01 – 2		cooler option
FU	01 - 15		Fuse 30A inside harness YA2 coil – no label

### 2.7.3. INPUTS

COMMANDS			
SA 1	02 - 9		Selection (upper/lower control box)
SA 2	03 - 2	28.7	Accelerator (605)
SA 3	03 - 3	29.11	Differential lock (807)
SA 4	03 - 5	30.3 30.4	Basket rotation SA4a left (3100) SA4b right (3110)
SA 5	03 - 6	30.5 30.6	Basket compensation (upper control box) SA5a lift (401) SA5b descent (402)
SA 6	03 - 9	4.6 4.9	Jib (lower control box) SA6b lift (406) SA6a descent (405)
SA 7	03 - 10	30.9 30.8	jib (upper control box) SA7a lift (410) SA7b descent (409)
SA 8	03 - 12	4.15 4.14	Telescopic boom extension (lower control box) SA8a retraction (411) SA8b extension (412)
SA9	03 - 13	30.10 30.11	Telescopic boom extension (upper control box) SA9a retraction (418) SA9b extension (419)
SA 11	03 - 15	29.10 29.9	Selection of drive speed Low speed: 805=1 and 804=0 Medium speed: 805=0 and 804=0 High speed: 805=0 and 804=1
SA12	03 - 16	29.7 29.8	Steering rear axle SA12a right (707) SA12b left (708)
SA 13	05 - 17	28.1 28.2	Boom (lower control box) SA13a lift (504) SA13b descent (505)

SA14	05 - 15		Arm (lower control box) SA14a lift (510) SA14b Descent (511)
SA 15	05 - 14		Orientation (lower control box) SA15a right (517) SA15b left (516)
SA17	03 - 7		Basket compensation (lower control box) SA17a lift (401) SA17b descent (402)
SA19	02 - 8		Emergency pump upper control box (620)
SA20	02 - 11		Emergency pump lower control box (620)
SB 1	02 - 11		Emergency stop turret (120)
SB 2	02 - 11		Emergency stop basket (102)
SB 3	03 - 18	4.12	Engine start lower control box (117a)
SB 4	03 - 19	3.2	Engine start upper control box (117b)
SB 5	03 - 19	29.12	Buzzer (115a)
SB 6	02 - 19		Dead man's pedals (917)
SM 4	05 - 9		Drive joystick SM4d right steering (705) Left SM4g steering (703) Off neutral SM4ab (606) Y signal (612) FWD from 2.5 to 4.5 V REV from 2.5 to 0.5 V
SM 31	05 - 3		turret rotation and boom raising joystick SM off neutral 31ab (420a) X signal orientation (512) Signal from 0.5 to 2.5 and 2.5 with 4,5V Y signal boom lift (403) Lift from 2.5 to 4,5V Descent from 2.5 to 0,5V

SM 2	05 - 6	30.13 30.15	Arm lifting joystick SM off neutral 2ab (420b) Y signal (506) Extension from 2.5 to 4,5V Retraction from 2.5 to 0,5V
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MODULES		
U1		module Head node A

SAFETY INPUTs			
SQ1	04 - 4	39.3	Tilt sensor (205 = 0 if in slope)
SQ2	04 - 5	3.3	Jib (206 = 0 if jib above horizontal )
SQ3	04 - 6	41.2	Boom (207 = 0 if boom unfolded)
SQ4	04 - 7	42.2	Arm (232=0 if arm unfolded)
SQ5	04 - 2	30.2	Overload (214a)
SQ6	04 - 2	30.2	Overload (214)
SQ20	03 - 4	30.4	Basket rotation right (311)
SQ21	03 - 5	30.3	Basket rotation left (310)
B1	04 - 19	27.2	Air filter clogging (110 = GND if filter clogged)
B2	04 - 18	27.3	Pressure switch for oil engine Temp (111= GND if T > 85°C)
B3	04 - 18	27.4	Pressure switch oil engine (112 = 0 if P > 0.5 bars)
B4	04 - 17	40 .2	Pressure switch for hydraulic oil temperature (904 = 0 if T >85°C)
D+	04 - 20	27.1	Alternator (109 = 12V mini if alternator runs)
W	04 - 20	27.7	Frequency (108)

## 2.7.4. OUTPUTS

RELAYS			
KP1	04 - 18		Engine start/stop (150)
KT2	04 - 19		Accelerator (605a)
KA2	04 - 20		Starter (146)
KA43	01 - 11		Relay alternator (109)
KMG	02 - 9		General relay (241)
KM4	02 - 8		Relay emergency pump (622)

VALVES			
YV 1	04 - 12	20	Load Sensing (303)
YV2	05 - 16	12.3 12.1	Telescope
			YV2a extension (305)
			YV2b retraction (415)
YV3	05 - 14	22.3	Boom (403a)
			Lift: from 50 to 75% of the tension of battery
			Descent: from 50 to 25% of the tension of battery
YV4	05 - 11	23.3	Arm (506a)
			Lift: from 50 to 75% of the tension of battery
			descent: from 50 to 25% of the tension of battery
YV5	05 - 9	24.3	Block ON/OFF turret slewing (512a) from 50 to 75% of the battery voltage
YV6	05 - 6	26.3	Drive (612a)
			FWD from 50 to 75% of the battery voltage
			REV from 50 to 25% of the battery voltage
YV8	03 - 19	8.11	High speed drive (813)
YV9	04 - 5	15.4	Differential lock front axle (807a)
YV10	03 - 17	8.10/8.12	Medium and high speed drive (814a)
YV11	03 - 16	8.6	Brake release (814c)
YV12	03 - 15	8.3/8.9	Medium and high speed drive (814b)
YV13	04 - 4	15.9	High speed (807b)
YV14	04 - 2	31 21	Turret slewing
			YV14a Right (417a)
			YV14b Left (414a)
YV15a	03 - 5	18	compensation raise (401a)
YV15b	03 - 6	19	compensation descent (402a)
YV17	03 - 14	8.3/8.9	Medium and high speed drive (814b)
YV18a	03 - 4	17	jib descent (407a)
YV18b	03 - 4	10	jib raise (408a)
YV19a	03 - 7	35	Basket rotation left side (310a)
YV19b	03 - 8	34	Basket rotation right side (311a)
YV21a	03 - 9	15.8	Left steering rear axle (307)
YV21b	03 - 10	15.7	Right Steering rear axle (308)

YV22a	03 - 11	15.3	Left steering front axle (304)
YV22b	03 - 12	15.6	Right steering front axle (306)
YV23	03 - 18	8.10/8.12	Medium and high speed drive (814a)

BUZZER AND LIGHTS			
HA1	04 - 13	52.2/52.3	Buzzer (260 and 261)
HA2	05 - 4	28.15	overload upper control box (921a)
HA4	04 - 14	14	Buzzer lower control box (210)
HL1	01 - 11		Light alternator powered (109)
HL2	04 - 17	4.3	Light air filter clogging (110a)
HL3	04 - 17	4.2	Temperature oil engine (111a)
HL4	04 - 16	4.1	Oil pressure engine (112a)
HL5	02 - 15		Beacon (906) Option
HL6	02 - 16		Work headlight (905) Option
HL9	05 - 3	49.2	Light defect upper control box (253)
HL13	05 - 4	28.15	Light overload upper control box (914)

## 2.8. LOGICAL EQUATIONS OF OPERATION

### 2.8.1. ENGINE

Function	Action	CONDITIONS		
		Necessary	Prohibiting the function	Modifying the function
Start-up	KA2=1	SA1 (side T or N) + SB3=1 or SB4=1 and D+= 1	engine already started	
			Movement in progress	

Function	Action	CONDITIONS		
		Necessary	Prohibiting the function	Modifying the function
Engine supply	+ KP1=1 + YA1=1	KA2=1 then 0 W=1	Defect engine + 6 seconds: D+=0 and B3=GND	
			Clogged filter: B1=GND	
			T°engine oil B2=GND	

Function	Action	CONDITIONS		
		Necessary	Prohibiting the function	Modifying the function
Accelerator	KT2=1 + YA2=1	SA1 (side N or T) + SB6=1 or SA2=1		

The accelerator is time-lag during 0.5 second when released.

### 2.8.2. DRIVE

Function	Action	CONDITIONS		
		Necessary	Prohibiting the function	Modifying the function
Low speed forward	YV1=1 + YV6=1 +YV11 =1	SA1 (side N) + SA11a = 1 and SA11b = 0 and SM4ab=1 and SB6 = 1 and SM4 between 2,5V and 4,5V	SQ5=0 or SQ6=0 (overload if machine elevated)	Speed reduced if SQ2/SQ3/or SQ4 =0
			SQ5=0 or SQ6=0 (overload if machine elevated)	
Low speed reverse	YV1=1 + YV6=1 + YV11=1	SA1 (side N) + SA11a = 1 and SA11b = 0 and SM4ab=1 and SB6 = 1 and SM4 between 2,5V and 0,5V	SQ5=0 or SQ6=0 (overload if machine elevated)	

Function	Action	CONDITIONS		
		Necessary	Prohibiting the function	Modifying the function
Medium speed forward	$YV1=1$ $+ YV6=1$ $+ YV10=1$ $+ YV11=1$ $+ YV12=1$ $+ YV17=1$ $+ YV23=1$	$SA1 \text{ (side N)} + SA11a = 0$ $\text{and } SA11b = 0 \text{ and}$ $SM4ab=1 \text{ and } SB6 = 1 \text{ and}$ $SM4 \text{ between } 2,5V \text{ and }$ $4,5V$	$SQ2=0 \text{ or } SQ3=0 \text{ or }$ $SQ4=0$ $(\text{unfolded machine})$	
Medium speed reverse	$YV1=1$ $+ YV6=1$ $+ YV10=1$ $+ YV11=1$ $+ YV12=1$ $+ YV17=1$ $+ YV23=1$	$SA1 \text{ (side N)} + SA11a = 0$ $\text{and } SA11b = 0 \text{ and}$ $SM4ab=1 \text{ and } SB6 = 1 \text{ and}$ $SM4 \text{ between } 2,5V \text{ and }$ $0,5V$	$SQ2=0 \text{ or } SQ3=0 \text{ or }$ $SQ4=0$ $(\text{unfolded machine})$	

Function	Action	CONDITIONS		
		Necessary	Prohibiting the function	Modifying the function
High speed forward	$YV1=1$ $+ YV6=1$ $+ YV8=1$ $+ YV10=1$ $+ YV11=1$ $+ YV12=1$ $+ YV13=1$ $+ YV17=1$ $+ YV23=1$	$SA1 \text{ (side N)} + SA11a = 0$ $\text{and } SA11b = 1 \text{ and}$ $SM4ab=1 \text{ and } SB6 = 1 \text{ and}$ $SM4 \text{ between }$ $2,5V \text{ and } 4,5V$	$SQ2=0 \text{ or } SQ3=0 \text{ or }$ $SQ4=0$ $(\text{unfolded machine})$	
High speed reverse	$YV1=1$ $+ YV6=1$ $+ YV8=1$ $+ YV10=1$ $+ YV11=1$ $+ YV12=1$ $+ YV13=1$ $+ YV17=1$ $+ YV23=1$	$SA1 \text{ (side N)} + SA11a = 0$ $\text{and } SA11b = 1 \text{ and}$ $SM4ab=1 \text{ and } SB6 = 1 \text{ and}$ $SM4 \text{ between }$ $2,5V \text{ and } 0,5V$	$SQ2=0 \text{ or } SQ3=0 \text{ or }$ $SQ4=0$ $(\text{unfolded machine})$	

Function	Action	CONDITIONS		
		Necessary	Prohibiting the function	Modifying the function
Differential lock	$YV9=1$	$SA1 \text{ (side N)} + SA3=1 \text{ and }$ $SA11a = 1$	Selection medium speed Selection high speed $YV11= 0 \text{ (brake release)}$	

## 2.8.3. STEERING

Function	Action	CONDITIONS		
		Necessary	Prohibiting the function	Modifying the function
Steering front axle	$YV1 + YV5a + YV22a=1$ or $YV22b=1$	$SA1 \text{ (side N)} + SB6=1 +$ $SM4 g=1 \text{ or } SM4 d=1$		
			$SQ5=0 \text{ or } SQ6=0$ (Overload)	

Function	Action	CONDITIONS		
		Necessary	Prohibiting the function	Modifying the function
Steering rear axle	$YV1 + YV5b + YV21a=1$ or $YV21b=1$	$SA1 \text{ (side N)} + SB6=1 +$ $SA12a=1 \text{ or } SA12b=1$	$SQ5=0 \text{ or } SQ6=0$ (Overload)	

## 2.8.4. BOOM

Function	Action	CONDITIONS		
		Necessary	Prohibiting the function	Modifying the function
Raise upper control box	$YV1=1 + YV3=1$	$SA1 \text{ (side N)} + SB6=1 +$ $SM1ab=1 \text{ and } SM31y$ between 2,5V and 4,5V	$SQ1=0$	
			$SQ5=0 \text{ or } SQ6=0$ (overload if machine elevated)	
Descent upper control box	$YV1=1 + YV3=1$	$SA1 \text{ (side NR)} + SB6=1 +$ $SM1ab=1 \text{ and } SM31y$ between 2,5V and 0,5V	$SQ5=0 \text{ or } SQ6=0$ (overload if machine elevated)	

Function	Action	CONDITIONS		
		Necessary	Prohibiting the function	Modifying the function
Raise lower control box	$YV1=1 + YV3=1$	$SA1 \text{ (side T)} + SA13a=1$	$SQ1=0$	$SQ5=0 \text{ or } SQ6=0$ (Overload)
			$SQ5=0 \text{ or } SQ6=0$ (Overload)	
Descent lower control box	$YV1=1 + YV3=1$	$SA1 \text{ (side T)} + SA13b=1$		

## 2.8.5. TELESCOPING

Function	Action	CONDITIONS		
		Necessary	Prohibiting the function	Modifying the function
Extension upper control box	YV1=1 + YV2=1	SA1 (side N) + SB6=1 and SA9b=1	SQ1=0 SQ5=0 or SQ6=0 (Overload)	
Retraction upper control box	YV1=1 + YV2=1	SA1 (side N) + SB6=1 and SA9a=1	SQ5=0 or SQ6=0 (Overload)	
extension lower control box	YV1=1 + YV2=1	SA1 (side T) + SA8b=1	SQ1=0	
			SQ5=0 or SQ6=0 (Overload)	
Retraction lower control box	YV1=1 + YV2=1	SA1 (side T) + SA8a=1		

## 2.8.6. ARM

Function	Action	CONDITIONS		
		Necessary	Prohibiting the function	Modifying the function
Raise upper control box	YV1=1 + YV4=1	SA1 (side N) + SB6=1 + SM2ab=1 and SM2y between 2,5V and 4,5V	SQ1=0	
			SQ5=0 or SQ6=0 (Overload)	
Descent upper control box	YV1=1 + YV4=1	SA1 (side N) + SB6=1 + SM2ab=1 and SM2y between 2,5V and 0,5V	SQ5=0 or SQ6=0 (Overload)	Slowed movements SQ4 =0

Function	Action	CONDITIONS		
		Necessary	Prohibiting the function	Modifying the function
Raise lower control box	YV1=1 + YV4=1	SA1 (side T) + SA14a=1	SQ1=0	Slow down movement if SQ5=0 or SQ6=0 (Static Overload)
Descent lower control box	YV1=1 + YV4=1	SA1 (side T) + SA14b=1		Slow down movements SQ4 =0

## 2.8.7. TURRET SLEWING

Function	Action	CONDITIONS		
		Necessary	Prohibiting the function	Modifying the function
Orientation upper control box	YV1=1 + YV5a=1 +YV14a=1 or YV14b=1	SA1 (side N) + SB6=1 and SM31ab=1 and SM31y between 2,5V and 4,5V or 2,5V and 0,5V	SQ5=0 or SQ6=0 (Overload)	
Orientation lower control box	YV1=1 + YV5a=1 +YV14a=1 or YV14b=1	SA1 (side T) + SA15a=1 or SA15b=1		Slow down movement if SQ5=0 or SQ6=0 (Static Overload)

## 2.8.8. JIB

Function	Action	CONDITIONS		
		Necessary	Prohibiting the function	Modifying the function
Raise upper control box	YV1=1 + YV5b=1 + YV18b=1	SA1 (side N) + SB6=1 and SA7b=1	SQ1=0	
			SQ5=0 or SQ6=0 (Overload)	
Descent upper control box	YV1=1 + YV5b=1 + YV18a=1	SA1 (side N) + SB6=1 and SA7a=1	SQ5=0 or SQ6=0 (Overload)	
			SQ1=0	
Raise lower control box	YV1=1 + YV5b=1 + YV18b=1	SA1 (side T) + SA6b=1	SQ5=0 or SQ6=0 (Overload)	
Descent lower control box	YV1=1 + YV5b=1 + YV18a=1	SA1 (side T) + SA6a=1		

## 2.8.9. COMPENSATION

Function	Action	CONDITIONS		
		Necessary	Prohibiting the function	Modifying the function
Raise upper control box	YV1=1 + YV5b=1 + YV15b=1	SA1 (side N) + SB6=1 + SA5b=1	SQ5=0 or SQ6=0 (Overload)	
			Telescope in progress	
			Orientation in progress	
			Lift in progress	
Descent upper control box	YV1=1 + YV5b=1 + YV15a=1	SA1 (side N) + SB6=1 + SA5a=1	SQ5=0 or SQ6=0 (Overload)	
			Telescope in progress	
			Orientation in progress	
			Lift in progress	
Raise lower control box	YV1=1 + YV5b=1 + YV15b=1	SA1 (side T) + SA17b=1 + SQ2=1 + SQ3=1 + SQ4=1	Telescope in progress	
			Orientation in progress	
			Lift in progress	
			Telescope in progress	
Descent lower control box	YV1=1 + YV5b=1 + YV15a=1	SA1 (side T) + SA17b=1 + SQ2=1 + SQ3=1 + SQ4=1	Orientation in progress	
			Lift in progress	

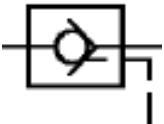
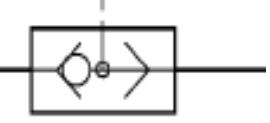
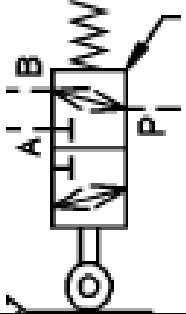
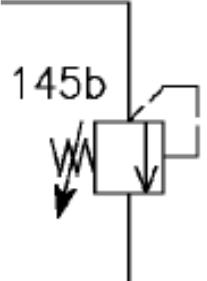
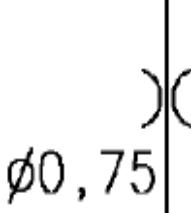
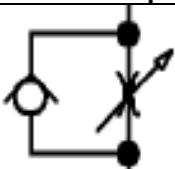
## 2.8.10. BASKET ROTATION

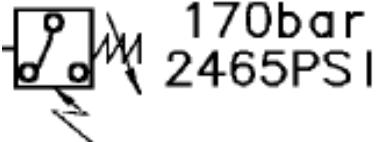
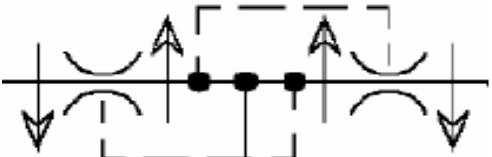
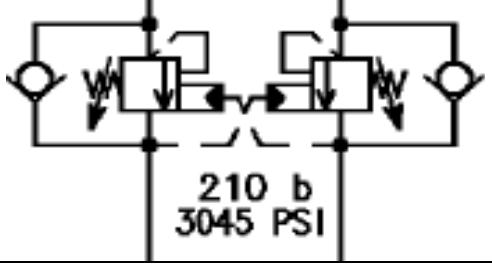
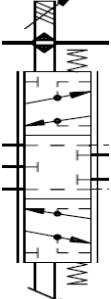
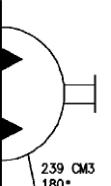
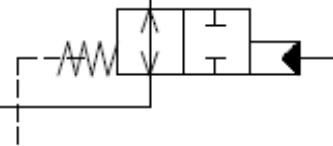
Function	Action	CONDITIONS		
		Necessary	Prohibiting the function	Modifying the function
Right rotation upper control box	YV1=1 + YV5b=1 + YV19b=1	SA1 (side N) + SB6=1 and SA4b=1	SQ5=0 or SQ6=0 (Overload)	
			SQ20=0	
Left rotation upper control box	YV1=1 + YV5b=1 + YV19a=1	SA1 (side N) + SB6=1 and SA4a=1	SQ5=0 or SQ6=0 (Overload)	
			SQ21=0	

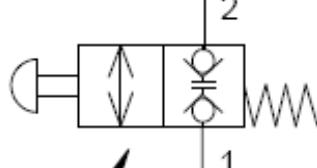
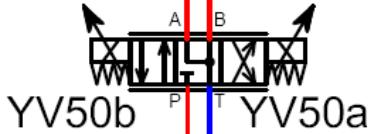
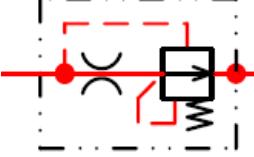
### 3. THE HYDRAULIC PART

#### 3.1. SYMBOLS USED

	Pump with variable cubic capacity (here maximum 38 cc /rpm)
	Pump Fixed cubic capacity flow (here 23 cc/rpm)
	Pump with bi-directional variable flow (used for the hydrostatic transmission in closed circuits on HAULOTTE superior booms like HA32PX, HA41PX, H28TJ+, H43TPX)
	Hydraulic motor with 2 directions of drive (ex FWD/REV)
	Variable cubic capacity drive motor with 2 directions of drive 15cc for High speed drive 45 cc for Low speed drive
	Filter (normally 10 microns)
	check valve

	check calibrated valve
	Priority valve /shuttle valve
	piloted check valve
	Circuit selector switch/shuttle valve
	Position hydraulic valve(used for the HA32PX/HA41PX)
	Adjustable pressure relief valve (here set at 145 bars/2104 psi)
	Fixed flow restrictor (here diameter of 0.75 mm)
	Adjustable flow restrictor

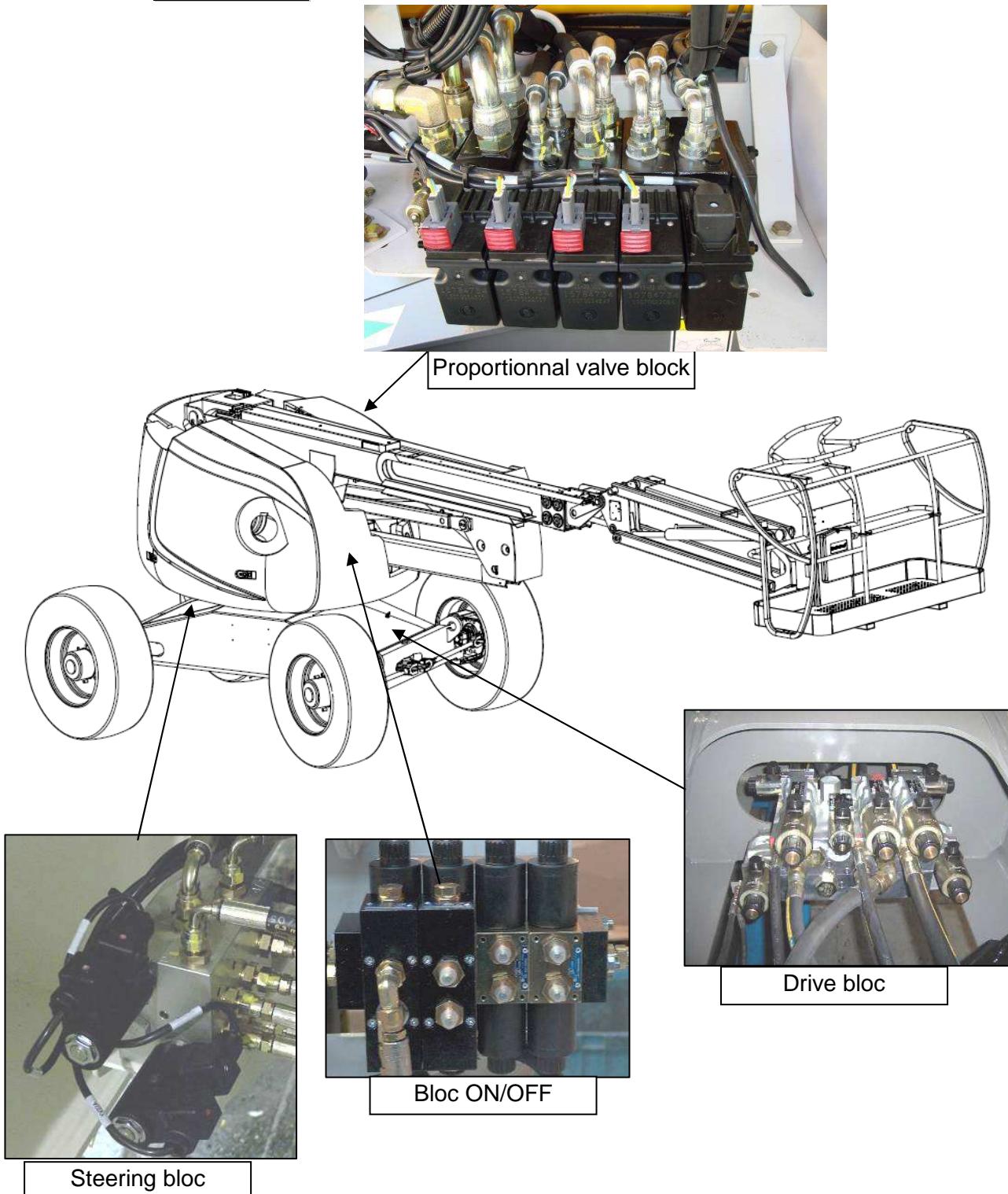
	Pressure sensor (used for weighing)
 170bar 2465PSI	Adjustable pressure switch (here set at 170 bars)
	Flow divider
 YY19a P YY19b	Position valve 4 ways, 3 positions in closed center
	Distributor/ safety valve
 210 b 3045 PSI	Counter balance valve with piloting line of the opposite line (here set at 210bars)
	Position valve proportional 5/3 with piloting manual by lever
 239 CM3 180°	Rotary cylinder /jack (here range at 180°)
	Piloted valve

	Manual valve with automatic return (used to readjust the part of compensation on HA32/41PX)
	proportional valve 4 ways/3 positions
	Pressure balance/flow control valve
	Flow regulator

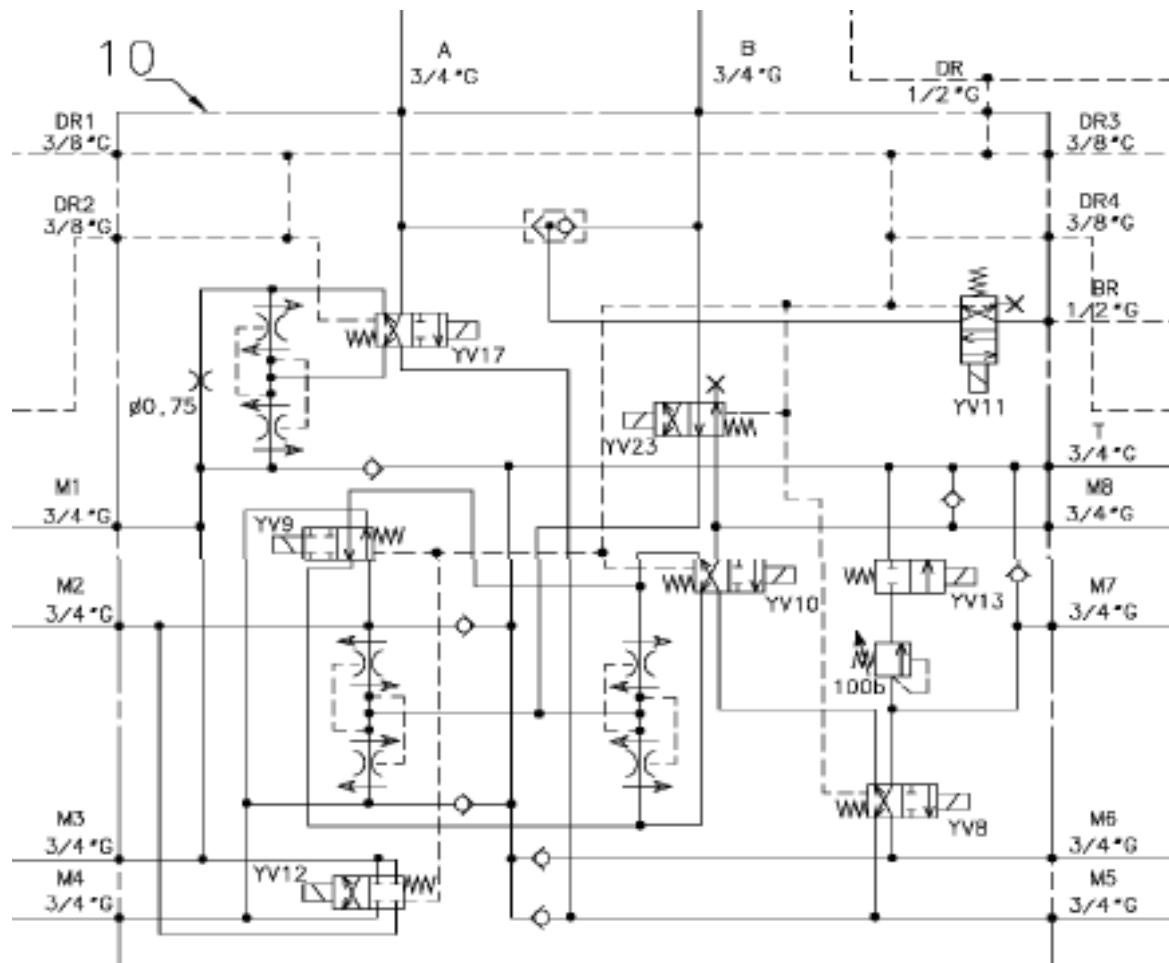
### 3.2. HYDRAULIC DIAGRAM (P22513G)

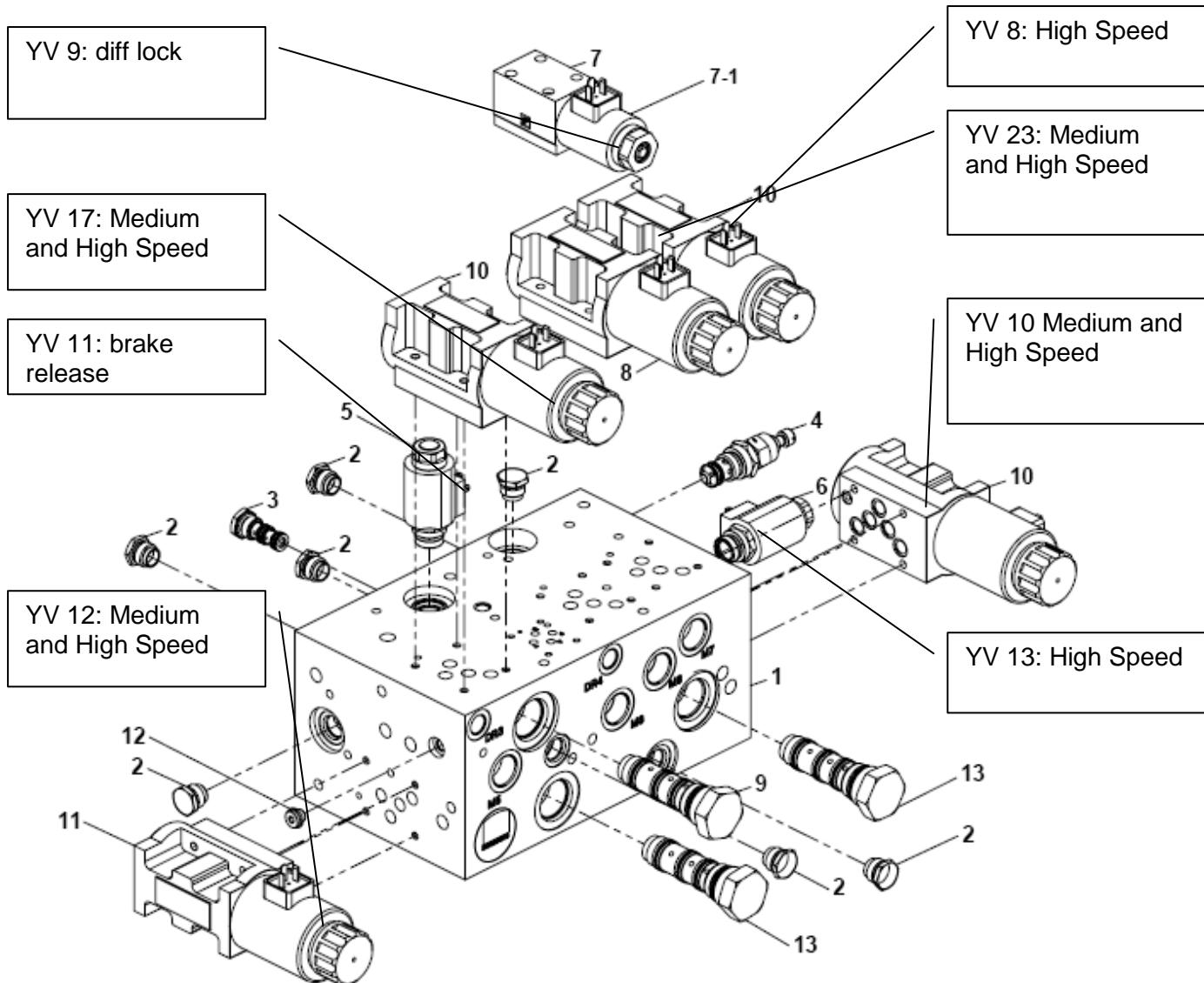
See at this end of this manual

### 3.3. MANIFOLD



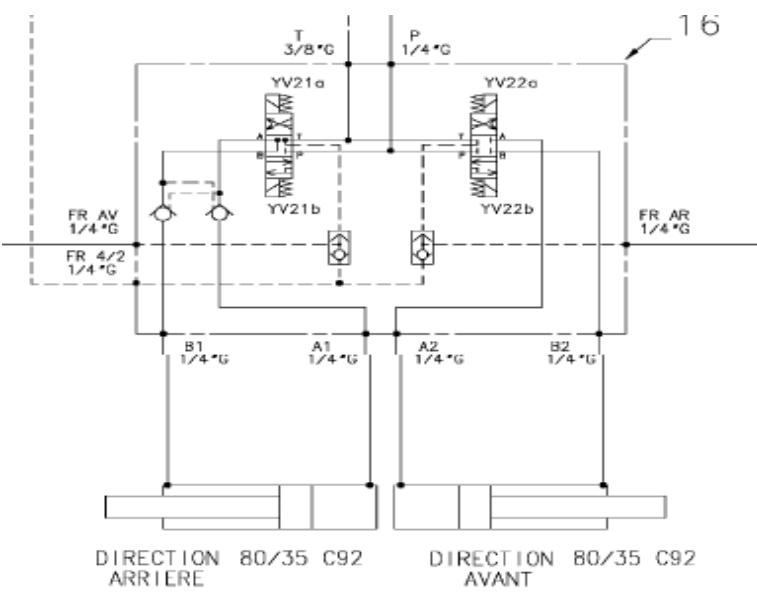
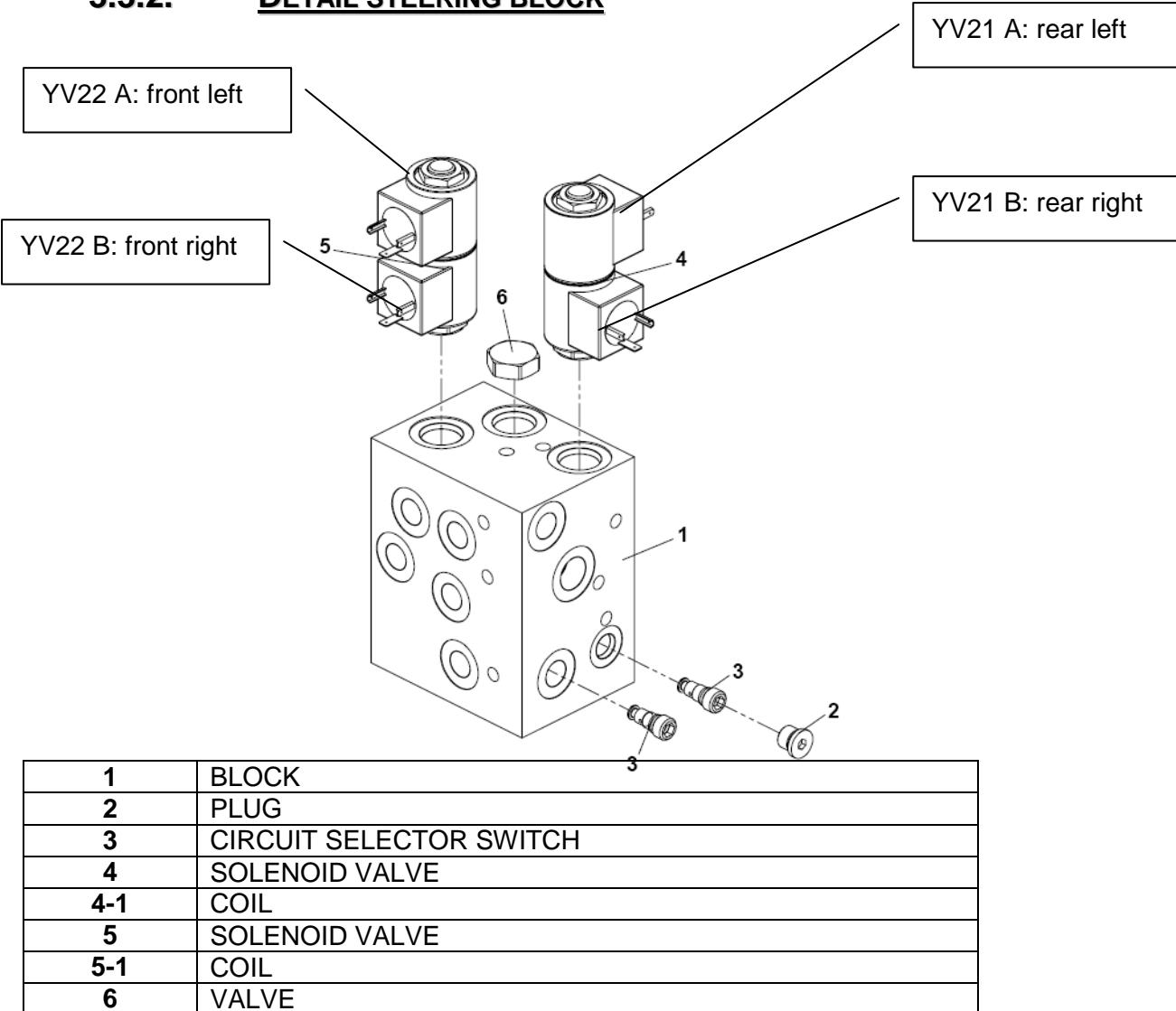
### 3.3.1. DETAIL DRIVE BLOCK



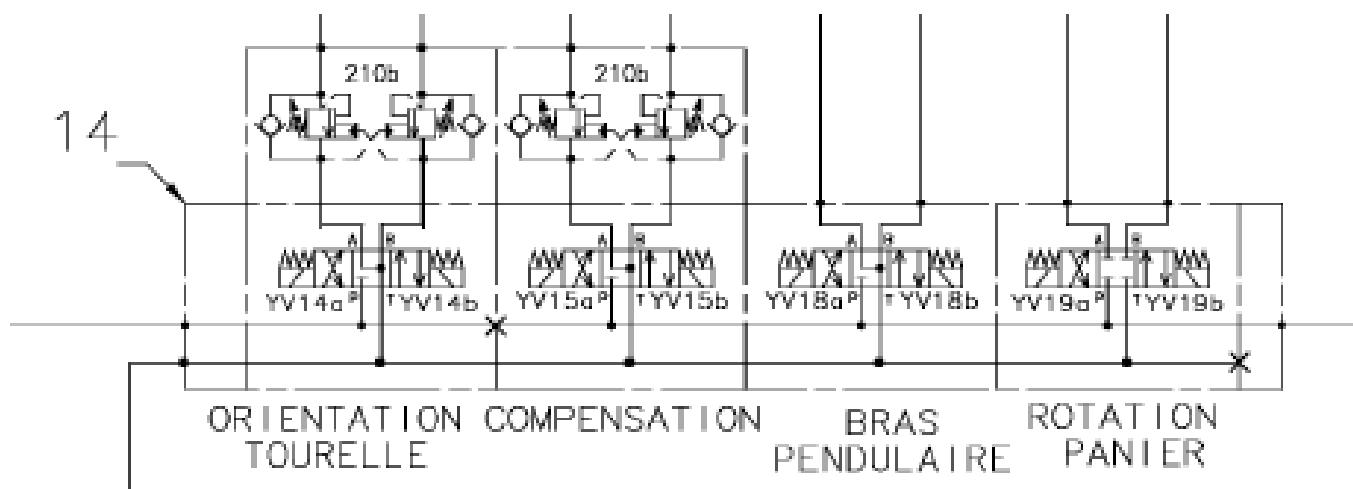
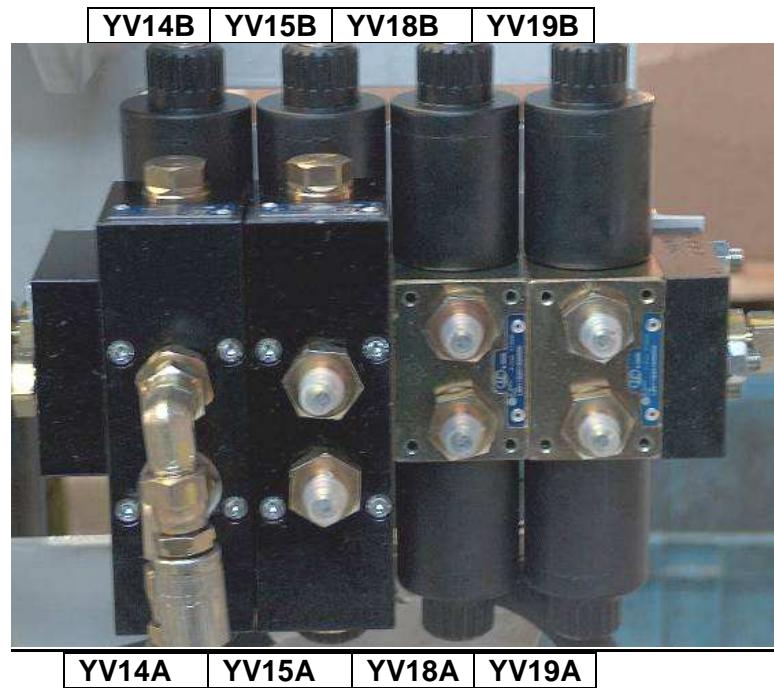


<b>1</b>	BLOCK
<b>2</b>	VALVE
<b>3</b>	CIRCUIT SELECTOR SWITCH
<b>4</b>	PRESSURE RELIEF VALVE
<b>5</b>	COIL
<b>6</b>	COIL
<b>7</b>	SOLENOID VALVE
<b>7-1</b>	COIL
<b>8</b>	SOLENOID VALVE
<b>9</b>	FLOW DIVIDER
<b>10</b>	SOLENOID VALVE
<b>11</b>	SOLENOID VALVE
<b>12</b>	PLUG
<b>13</b>	FLOW DIVIDER

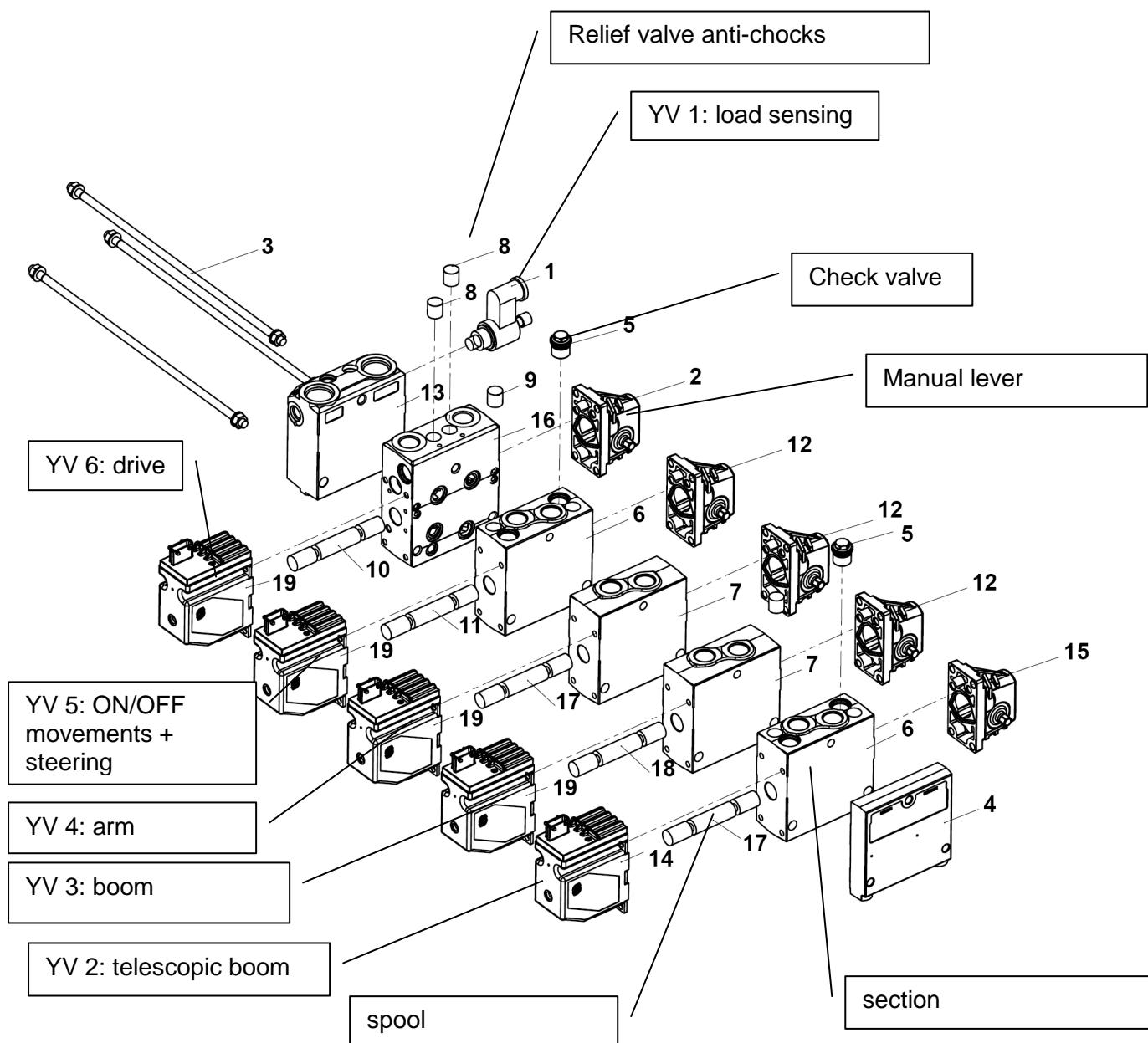
### 3.3.2. DETAIL STEERING BLOCK

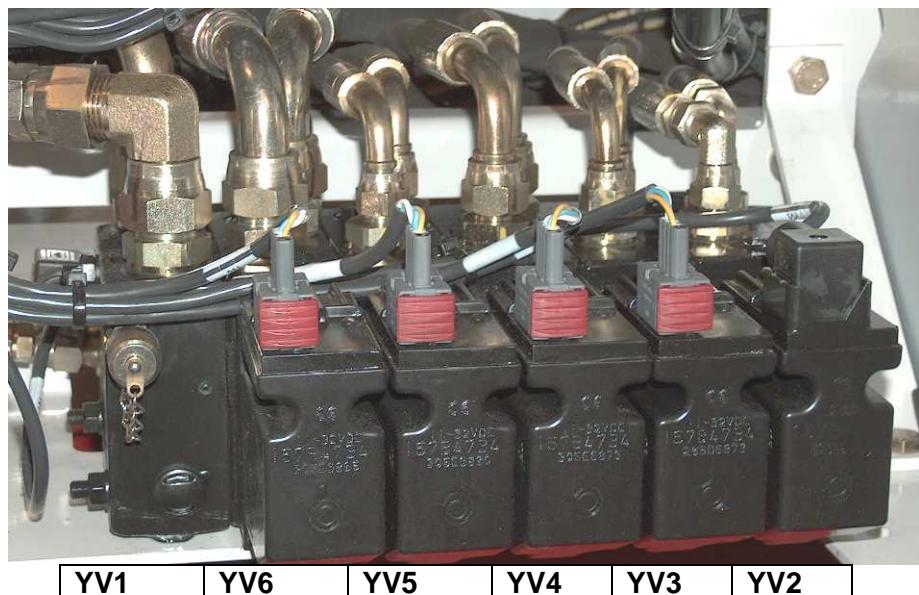


### 3.3.3. BLOCK ON/OFF

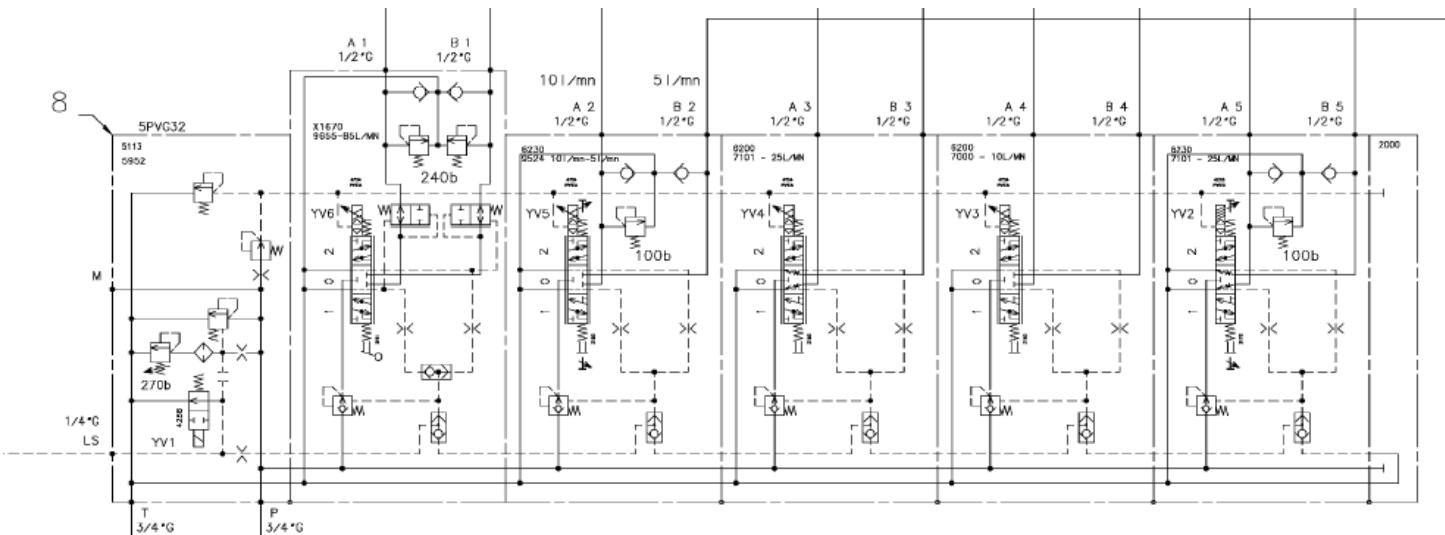


### 3.3.4. BLOCK PROPORTIONAL



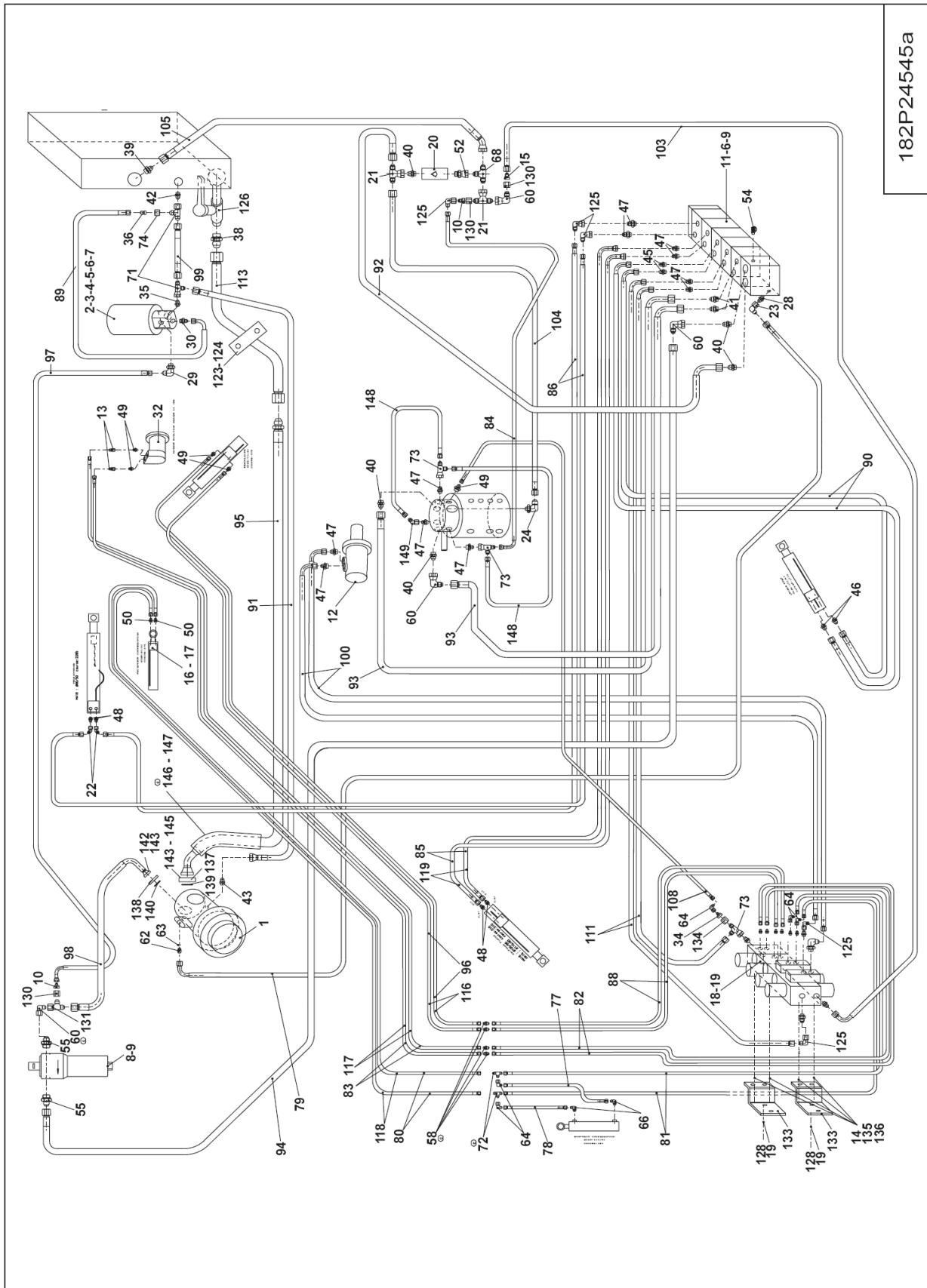


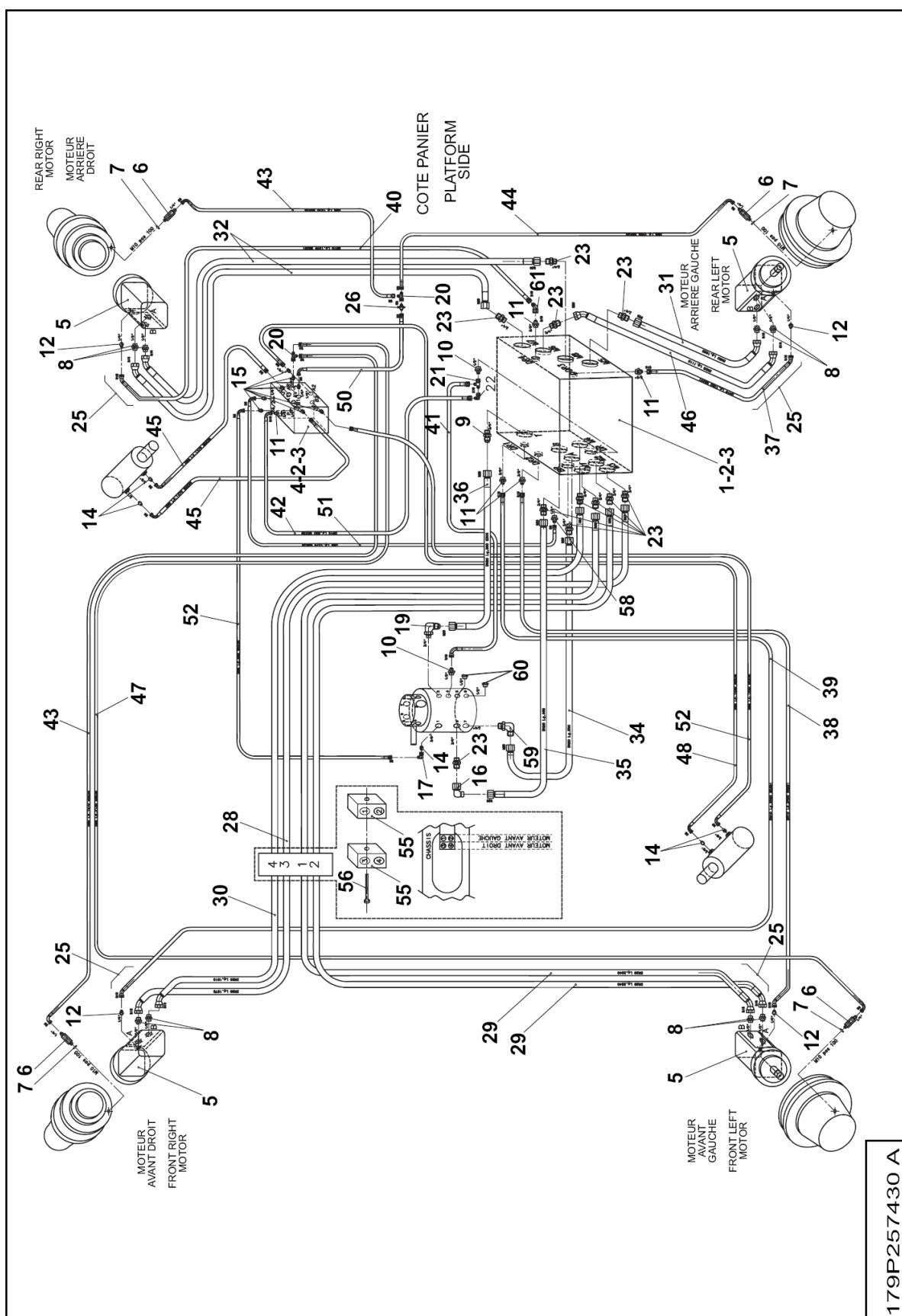
YV1    YV6    YV5    YV4    YV3    YV2



### 3.4. THE LOOMS

#### 3.4.1. TURRET





## 4. ADJUSTMENTS

### 4.1. ADJUSTMENTS WITH OPTIMIZER CONSOLE

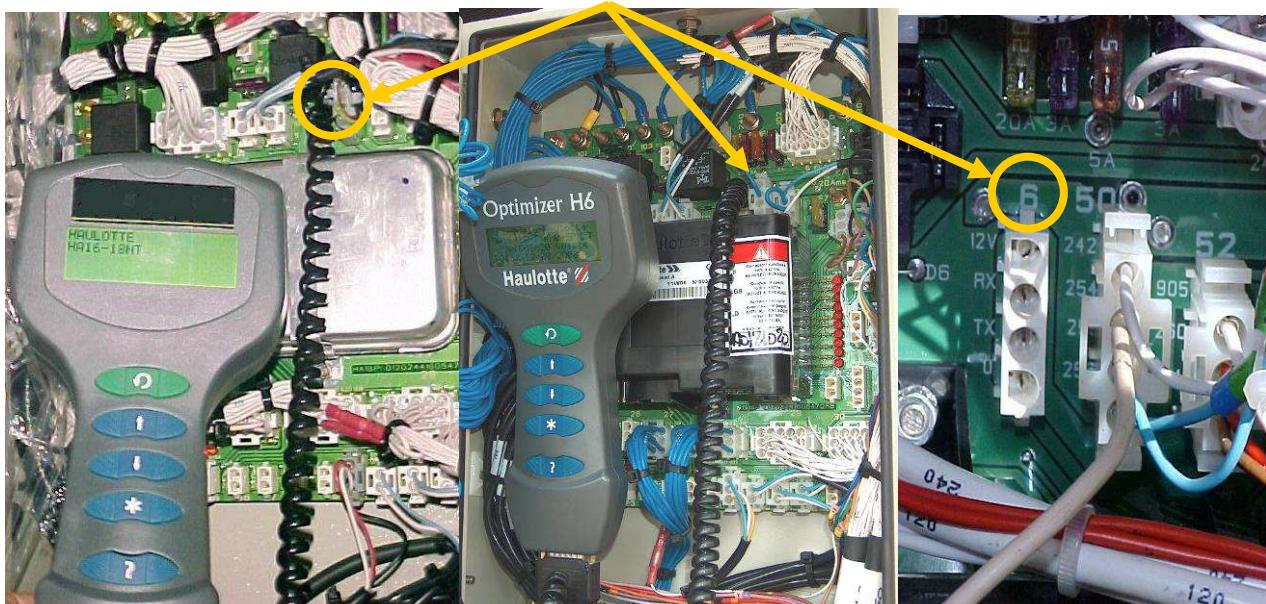
The adjustments, parameter settings and lists of alarms of the machine are accessible through this console.

#### Use OPTIMIZER console with module HEAD

##### Connection bottom panel (turret)

connect the plug socket on the connector number 6:

Connector n°6 on main printed circuit



Description of the console

**NOTE :** on any blue key pads , pressing on left , right or in the center have the same result

**List of menus**

**Access to the menu**



Pinguely-Haulotte  
HA20-260PX EUR  
2901001340 V01.08  
20:38 23/10/2006

-----MAIN MENU-----

PARAMETERS

1

Parameters setting access

-----MAIN MENU-----

INPUTS - OUTPUTS

2

Input/output state access

-----MAIN MENU-----

DIAGNOSTIC

3

Trouble shooting guide per function

-----MAIN MENU-----

INFORMATIONS

4

Machines status

-----FAILURES-----

FAILURES

Failures list



Pinguely-Haulotte  
HA20-260PX EUR  
2901001340 V01.08  
20:38 23/10/2006

-----MAIN MENU-----

PARAMETERS

1

Speed parameters adjust

--PARAMETERS MENU--

SPEEDS

1

ramp parameters adjust

--PARAMETERS MENU--

RAMPS

2

Options setting

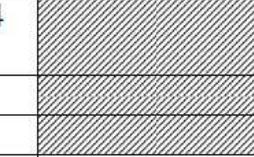
--PARAMETERS MENU--

OPTIONS

3



## 4.2. FLASH CODE ON UPPER CONTROL BOX

Catégorie	Code	Détail	Numéro	Commentaires	Niveau
CO & CC	01	CC TOR (YV)	1	CC sur YV concernées	2
		CC ANA (PVG)	2	CC sur tous les PVG	1
		CC ANA (PWM)	3	CC sur tous les PWM	1
		CO TOR (YV)	4	CO sur YV concernées	2
		CO ANA (PVG)	5	CO sur tous les PVG	1
		CO ANA (PWM)	6	CO sur tous les PWM	1
Alarme Fusible	02	FU05 ou FU06	1	Via le commutateur	1
		FU07	2		1
		FU08	3		1
Circuit d'Urgence	03	KMG	1	Surveillance TRT	3
Relais d'aiguillage	04			1	
				2	
				3	
Alarme Sortie PVG	05	S.Anal PVG 1 (R)	1	Au relevage	1
		S.Anal PVG 2 (L)	2	Au levage	1
		S.Anal PVG 3 (O)	3	A l'orientation	1
		S.Anal PVG 2 (TL)	4	Au télescopage	1
		S.Anal PVG 4 (TR)	5	A la Translation	1
Alarme Joystick 1	06	SM31 incompatible	1	Manipulateur 2 axes	1
		SM31 hors neutre	2		1
		SM31 hors plage	3		1
Alarme Joystick 2	07	SM2 incompatible	1	Manipulateur simple	1
		SM2 hors neutre	2		1
		SM2 hors plage	3		1
Défauts Machines	08	Dévers	1	Sécurité dévers	1
		Surcharge	2	Sécurité surcharge	1
		Blocage Pédale	3	Homme mort (>10s)	2
		Lim. Portée	4	Sécurité Limitation de portée	3

### 4.3. PARAMETER SETTINGS

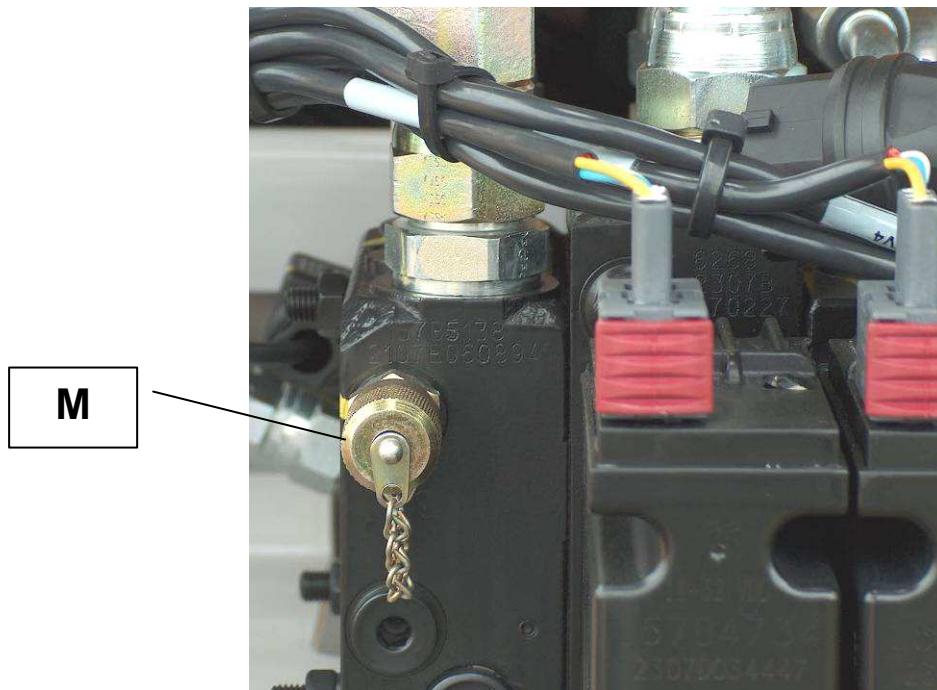
<b>Movement from Turret</b>	
<b>Movements</b>	<b>Time</b>
Boom lift	30 + 3s
Boom descent	33 +-3s
Arm lift	35 +-3s
Arm descent	23 +-3s
Left turret rotation	75 +-1,5s 1/2 turn
Right turret rotation	75 +-1,5s 1/2 turn
<b>Movement from Platform</b>	
<b>Movements</b>	<b>Time</b>
Boom lift	27 +-3s
Boom descent	30 +-3s
Arm lift	29 +-3s
Arm descent	20 +-3s
Left turret rotation	44 +-1,5 sec 1/2 turn
Right turret rotation	44 +-1.5 sec 1/2 turn
Drive in Micro V FWD	45 sec on 10 m
Drive in Micro V REV	45 sec on 10 m
Drive in Low Speed FWD (for Machine 4*2 only)	29 sec on 10 m
Drive in Low Speed REV (for Machine 4*2 only)	29 sec on 10 m
<b>Checking of the movements</b>	
<b>Movement</b>	<b>distance</b>
deceleration ramp in High speed drive	FWD 1,30m (+ 20cm)
	REV 1,30m (+ 20cm)
<b>Movement</b>	<b>time</b>
High speed drive output of pump	FWD 13 sec on 20 m
	REV 13 sec on 20 m
<b>Adjustment speeds of ON/OFF movements (oil &gt; 30°C mini )</b>	
<b>Movements</b>	<b>Times</b>
telescope extension HA16PXNT-HA18PXNT speed adjustment speed (adj on PVG ON/OFF element)	extension 18 + 3s
	Retraction 12 + 3s
Steering speed adjustment speed (adj on PVG ON/OFF element)	extension 6 sec
	Retraction 5 sec
jib regulation with relief valve on movements block	Raise 26 + 2 s
	Descent 35 + 2s
Basket rotation basket to be regulated with relief valve on hydraulic motor	Right 15 + 2s
	Left 15 + 2s
Compensation regulation with relief valve on movements block	Raise 27 + 5s
	Descent 35 + 5s

## 4.4. ADJUSTMENT OF PRESSURES

### 4.4.1. TABLE OF PRESSURES

DESIGNATION	IN BARS
General	240 +-5
Load Sensing	30 +-5
Emergency unit (movement of retraction at full stroke)	130 +-5
Arm lift full height	240 +-5
arm bottom position	140+-5
Boom full stroke	240 +-5
Boom bottom position	150 +-5
Telescoping extension	70 +-5
Telescoping retraction	240 +-5
Turret slewing	100 +-5
Movements ON/OFF	240 +-5

### 4.4.2. PORT PLUG FOR THE PRESSURES

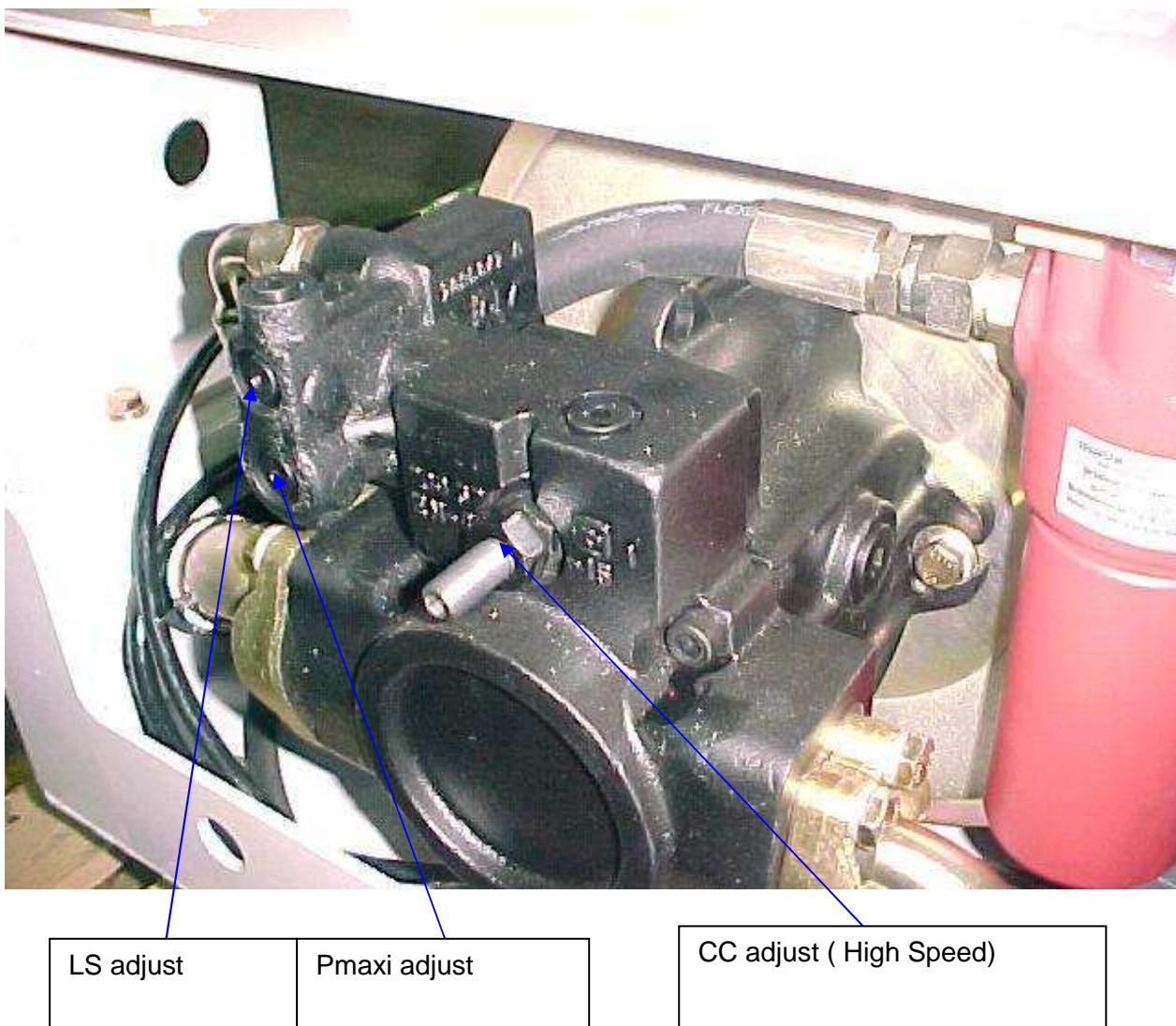


#### 4.4.3. ADJUSTMENTS

- Load sensing (LS)
- main flow
- Cubic capacity pump

##### Standard pump 1

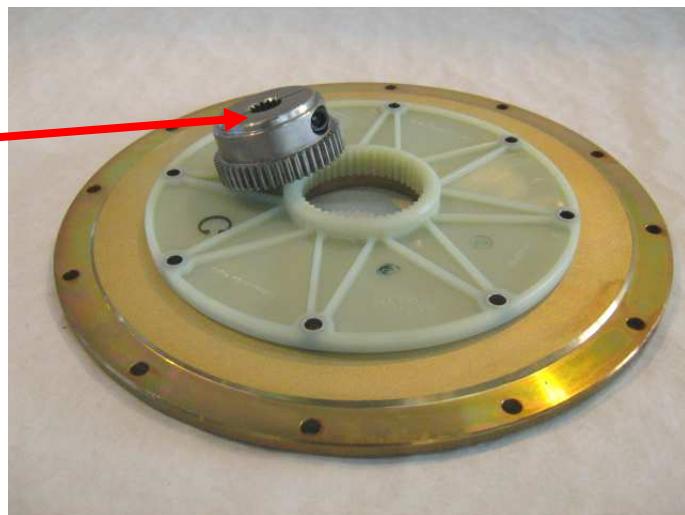
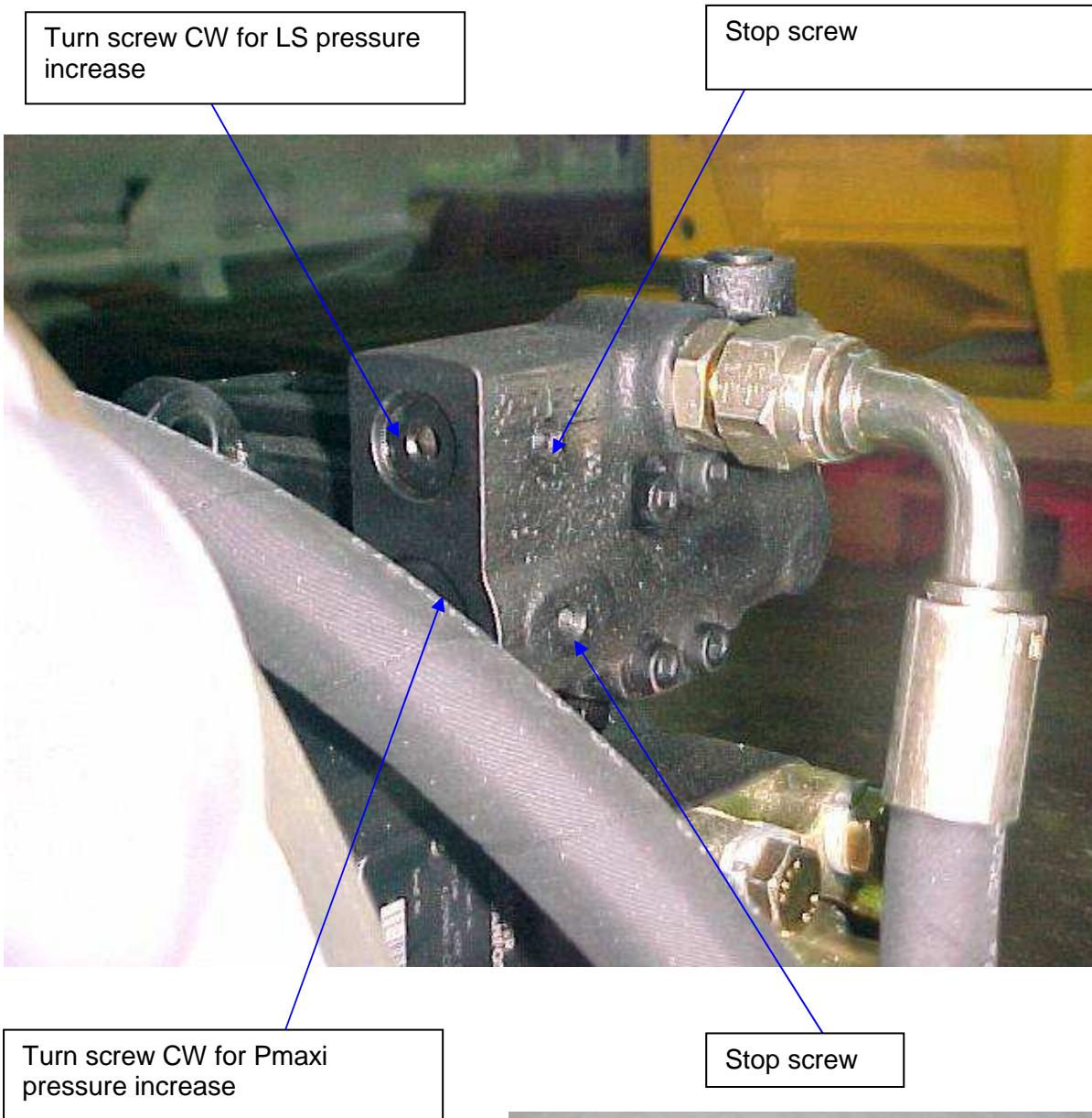
- The pump is preset with a pressure Load sensing of 30b (+-2b)
- The pump is preset with a general pressure of 240b (+-5b)
- The cubic capacity of the pump is preset to reach the high speed (20 seconds for 25 meters)



LS adjust

Pmaxi adjust

CC adjust ( High Speed)

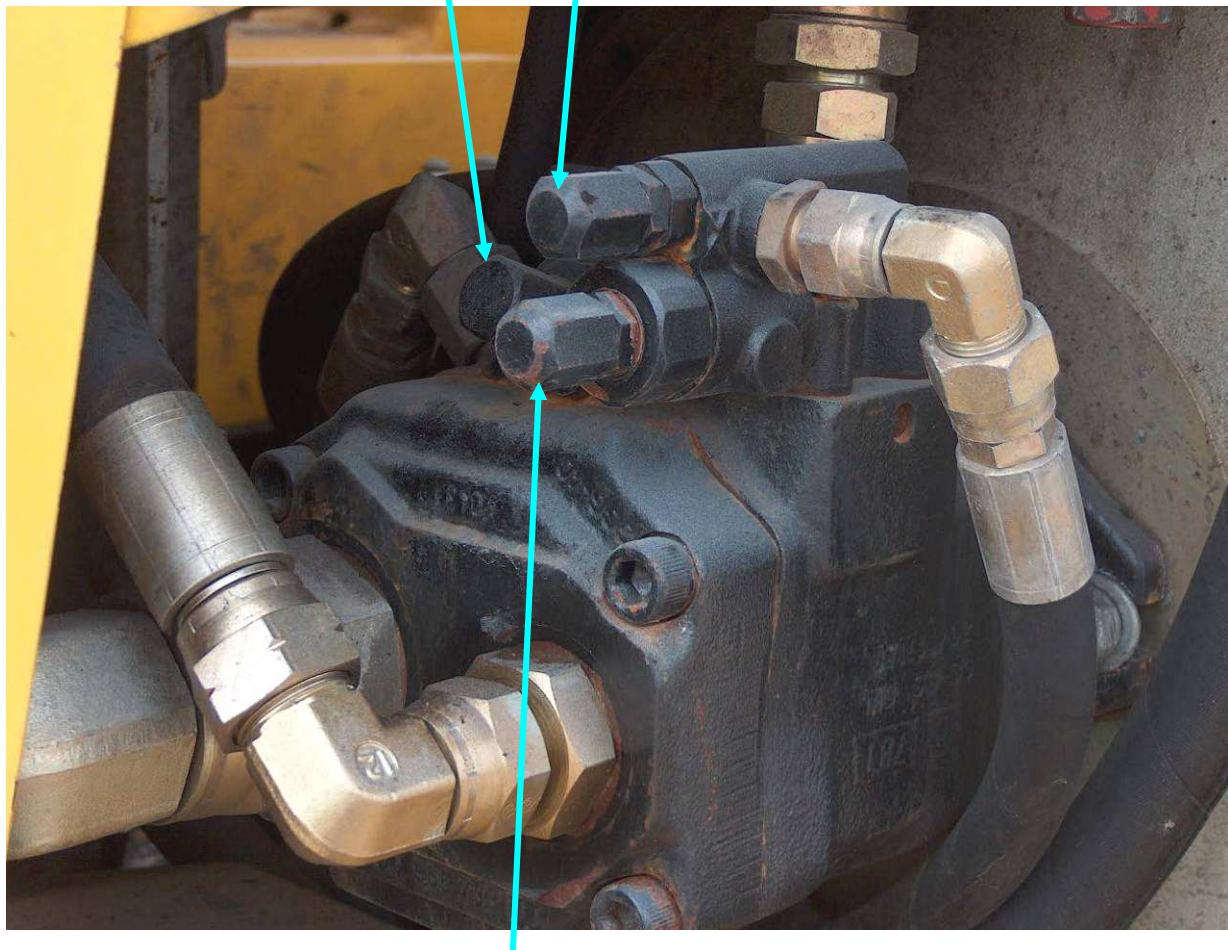


### Standard pump 2

- The pump is preset with a pressure LS of 30b (+-2b)
- The pump is preset with a general pressure of 240b (+-5b)
- The cubic capacity of the pump is preset to reach the high speed (20 seconds for 25 meters)
- unscrew the cap (wrench)
- turn the HEX screw until obtaining the desired value

CC adjust for high speed

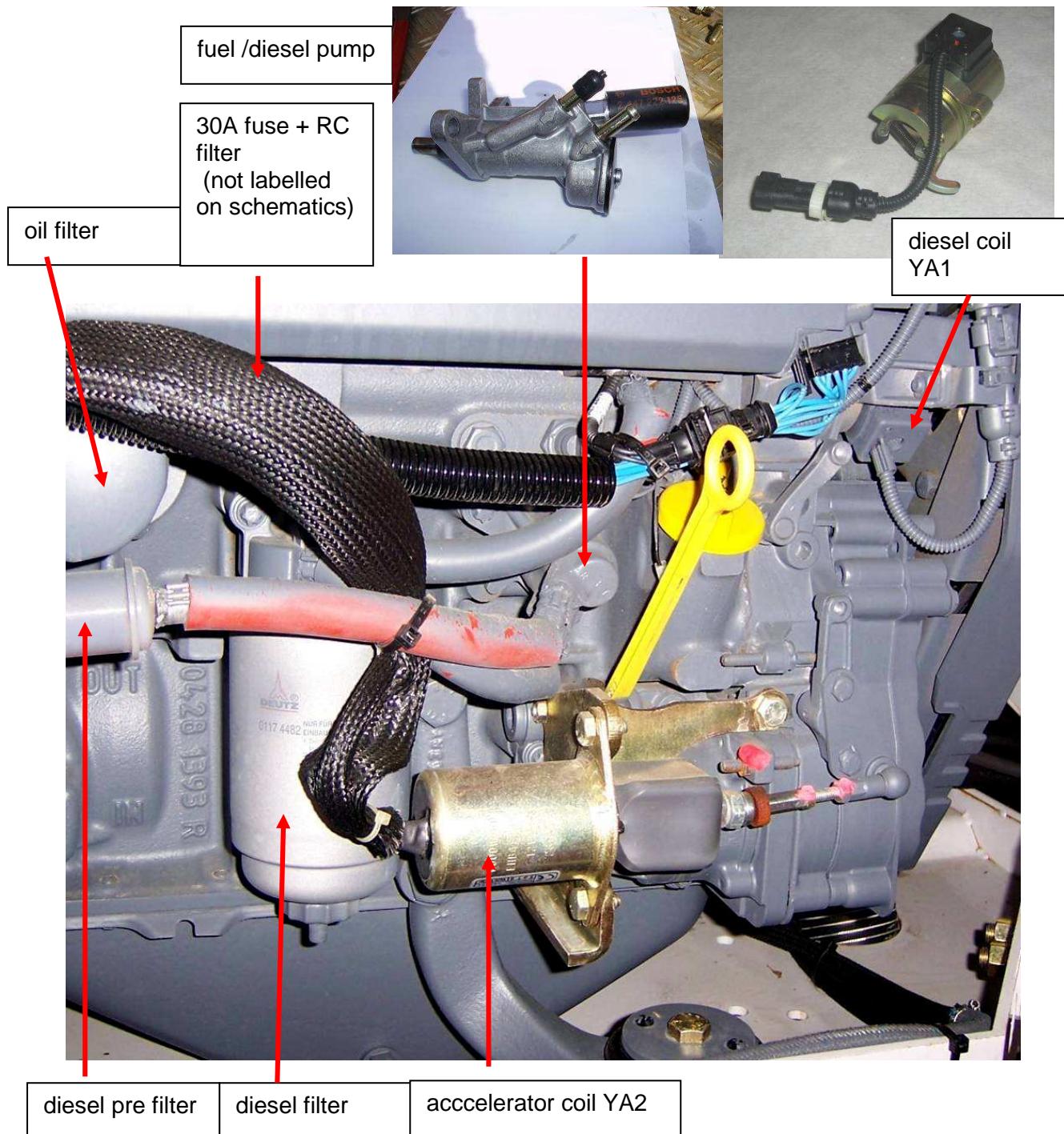
LS adjust



Pmaxi adjust

## 4.5. ACCELERATOR ENGINE COIL

This adjustment must be done when the accelerator coil has been replaced

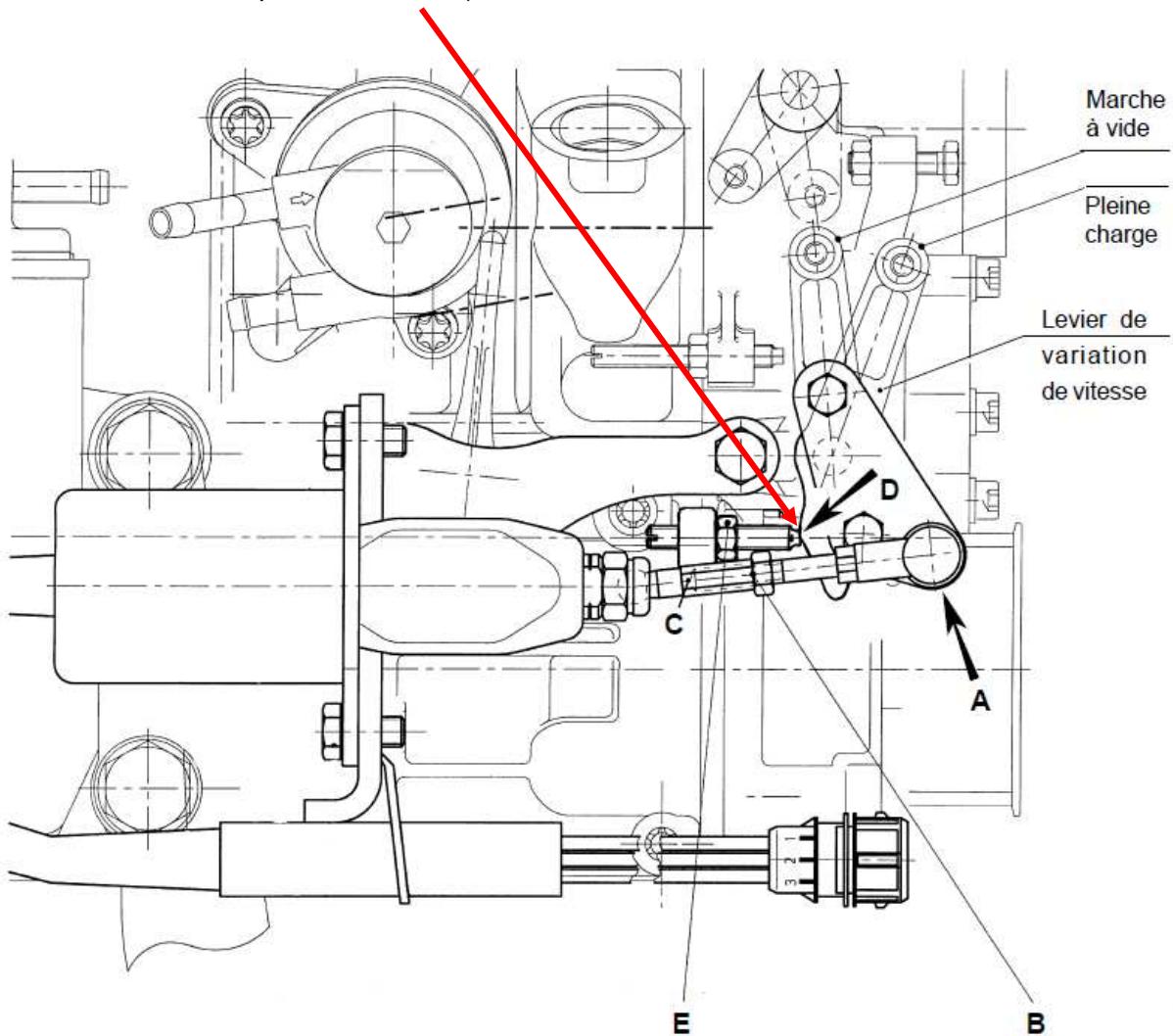


Fuse 30A on accelerator coil :



- **Procedure**

the coil rod A must be aligned straight with coil  
 the clearance D must be adjusted at +/- 0.5mm when accelerator is at maxi stroke  
 ( it must never touch the stop screw mark D )

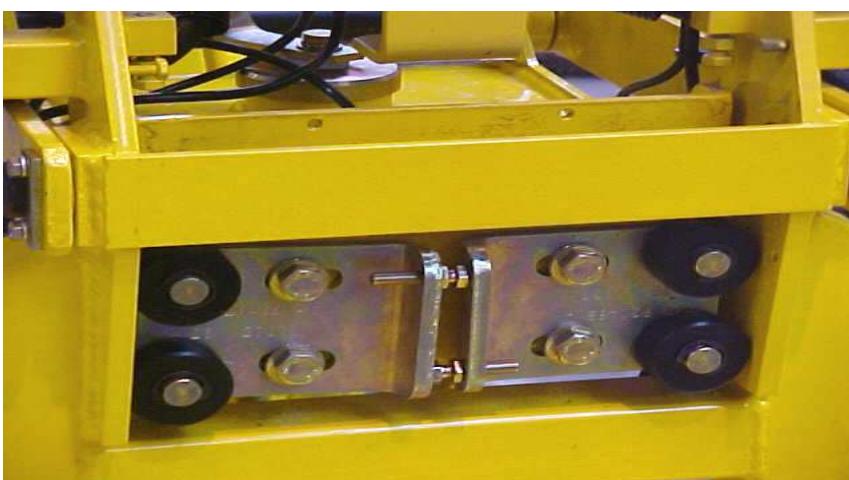


## 4.6. OVERLOAD

### Procedure :

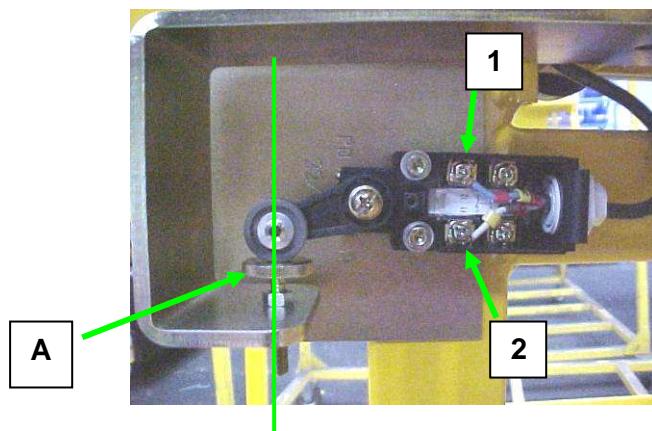
#### Adjust the wheels

- Centre the basket with the link part
- Push on the left the 2 plastics wheels
- Tighten 2 screws HM12 on left side
- Put a steel wedge (thickness = 0.1 mm) on the right (between plastics wheels and steel parts - see photo)
- Push the right part with the 2 screws HM8, and tighten them
- Tighten 2 screws HM12 on the right
- Take out the steel wedge
- the plastics wheels shoud turn freely only by hand



#### Overload

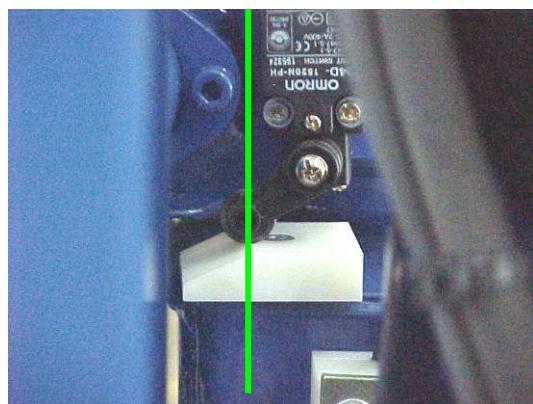
- Put the weight in the centre of the basket (weight = 120% x nominal weigh).
- stop unscrew the part "A" when you hear the buzzer
- The plastic wheel and the screw must be in the same axis
- Check the opening of the contact between 1 & 2
- Lift and lower the weight to check the adjust
- Check the light on the console, the buzzer on, and you can't have movements.
- Block the part "A" with the nut
- Repeat the same operation for the second limit switch



- Adjust electrical contactor for the basket rotation
- Put a wedge (thickness = 5 mm) on the mechanic stop of basket rotation
- Turn the basket to put it on this wedge
- Check the light on the console, the buzzer on, and you can't have movements.
- Block the part "A" with the nut
- Repeat operation for the second limit switch

Adjust electrical contactor for the basket rotation

- Put a wedge (thickness = 5 mm) on the mechanic stop of basket rotation
- Turn the basket to put it on this wedge
- Adjust the limit switch, it must activate in this position.
- Do the same thing for the second limit switch



## 5. BREAKDOWN SERVICE GUIDE

This guide does not replace the logical equations described previously in this manual, it allows him to have a logical step of breakdown service, detailing the successive steps to be followed starting from general tips until details.

The checking of the electric part is carried out in priority because less sensitive to the external parameters than the hydraulics part (temperature, pollution, viscosity...).

The denomination of the movements describes below implies the 2 phases (ex not arm lift: neither raise, nor descent from both controls)

### 5.1. NO START

- Battery (14V)
- Emergency push buttons SB1-SB2
- Start switchs SB3-SB4
- Key switch SA1
- Fuse FU8
- Engine oil Temperature B2
- Pressure Oil engine B3
- Clogged air filter B1
- Alternator light HL1
- Relays KA2 –KP1-KMG
- Alternator charge D+ =0
- Drive joystick SM4 ( signal and/or neutral position)
- Head module

### 5.2. NO MOVEMENT

- Machine in overload and/or in slope
- Fuses FU7 –FU10
- Load Sensing Valve YV1
- Foot dead man pedal SB6 / lower box dead man switch SA19
- Head module

### 5.3. NO MOVEMENT > 3 M

- Machine in slope (SQ1)
- Machine in overload (SQ5/SQ6)

### 5.4. NO ARM LIFT

- Signal on YV4 (25-50-75%Vbat)
- Signal on SM2 joystick (0.5/2.5/4.5VDC)
- Toggle switch SA14
- Valve YV4
- Head module

## **5.5. NO BOOM LIFT**

- Signal on YV3 (25-50-75% Vbat)
- Signal on SM31 joystick ( 0.5/2.5/4.5VDC)
- Toggle switch SA13
- Head module
- No pressure
- 

## **5.6. NO TELESCOPIC BOOM EXTENSION**

- Valve YV2
- Toggle switch SA8/SA9
- Head module

## **5.7. NO TURRET ROTATION**

- valves YV5 –YV14
- Signal on SM31 (0.5/2.5/4.5VDC)
- Toggle switch SA15
- Distributor YV5 or ON/OFF block
- Head module
- No pressure

## **5.8. NO ON/OFF MOVEMENTS**

- valves YV5/YV 15/YV18/YV19
- toggles switch (SA4/SA5/SA6/SA7/SA17)
- valve YV5 or ON/OFF block
- Head module

## **5.9. NO DRIVE**

- Signal on joystick SM4 (0.5/2.5/4.5VDC)
- Signal on YV6 (YV7) ( 25-50-75%Vbat)
- Valve YV11( brakes)
- Brake circuit
- Head module

## **5.10. ONLY LOW SPEED**

- Valves YV8/YV12/YV13/YV17/YV23
- Limit switch SQ2/SQ3/SQ4
- Toggle switch SA11
- Head module

## **5.11. NO STEERING**

- Valves YV5/YV11/YV21/YV22
- Head module

## 6. SUMMARY OF VERSIONS HA16PX –HA18PX

<b>HA15X/HA16X</b>		<b>Electric</b>	<b>Hydraulic</b>
Pre version 280 with pedals	Standard EC	E572	B16529
Pre-280 version without pedals	Standard EC	E565	B16529
Version IN 280 (until June 2006)	Standard EC	E603	P22873
+ change steering axle- with the joystick	Standard EC	137P270910	180P212140
Aus version		E603	P22873
Usa version		E603	P22873

<b>HA16PE</b>		<b>Electric</b>	<b>Hydraulic</b>
Pre version 280 (without pedals) (until May 2005)	Standard EC	E436 C	B15160
Version IN 280	Standard EC	E567	B15160
Version IN 280 + basket rotation with limit switchs	Standard EC	E586	B15160
Aus version		E586 B E436 C	B15160
Usa version		E436 (P20251) E586 B E436 C	B15160

<b>HA16PE-PX</b>		<b>Electric</b>	<b>Hydraulic</b>
Pre version 280 (without pedals) (until June 2003)	Standard EC	E436 C	B15832
Version IN 280 (until June 2004)	Standard EC	E567	B15832
Version IN 280 + basket rotation with limit switchs	Standard EC	E586	B15832
Aus version		E586 B E436 C	B15832
Usa version		E436 (P20251) E586 B E436 C	B15832

<b>HA16-18NT Phase 1 Machine with relay EHR-EHF</b>		<b>Electric</b>	<b>Hydraulic</b>
Pre version 280 + relay EHR (until September 2003)	Standard EC	E567	P22513
Version IN 280 + relay EHR (until September 2003)	Standard EC	E567	P22513
Version Aus (until September 2003)		E584	P22513
Usa version (until September 2003)		E584	P22513

<b>HA16-18NT Phase 2 EN280 Joystick 3v/6v/9v</b>		<b>Electric</b>	<b>Hydraulic</b>
Standard (until January 2006)	Standard EC	E567	P22513
+ addition of steering relays + change steering axle- with the joystick + button compensation bottom panel	Standard EC	E584	P22513
Aus version		E567	P22513
Usa version		E567	P22513

<b>HA16SPX and NT Phase 0 EN280 machine with progressivity</b>		<b>Electric</b>	<b>Hydraulic</b>
Standard (until March 2005)	Standard EC	E595	P21214
+ turret slewing plug socket on block TOR	Standard EC	E595	P21214
Only NT model	Standard EC	E598	179P260650
Aus version		E582 E595	P21214
Usa version		E582 E595	P21214

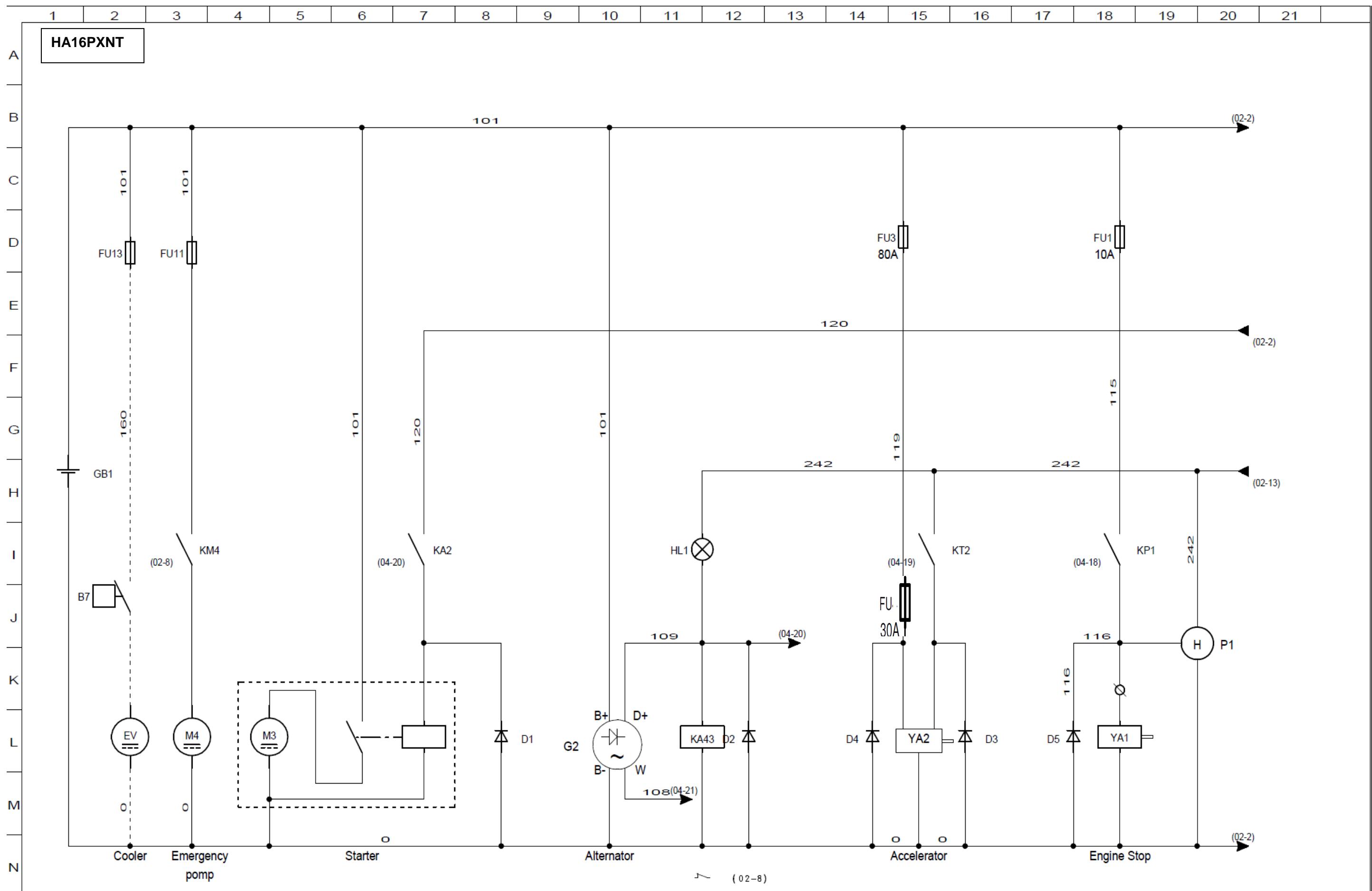
Pre version 280 = Detection overload (threshold of alarm then cut-off movements)

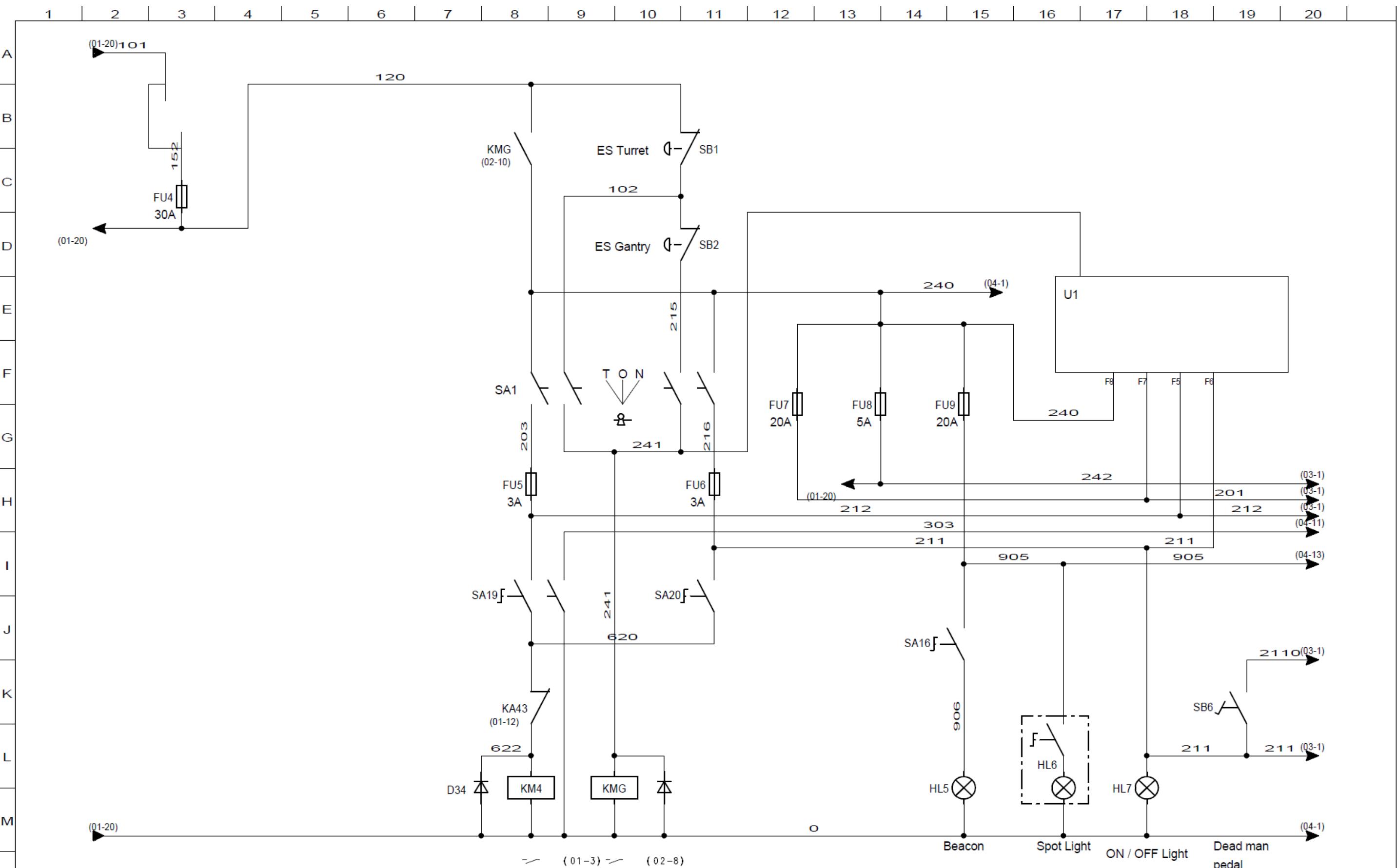
Version EN 280 = detection overload with cut-off movements

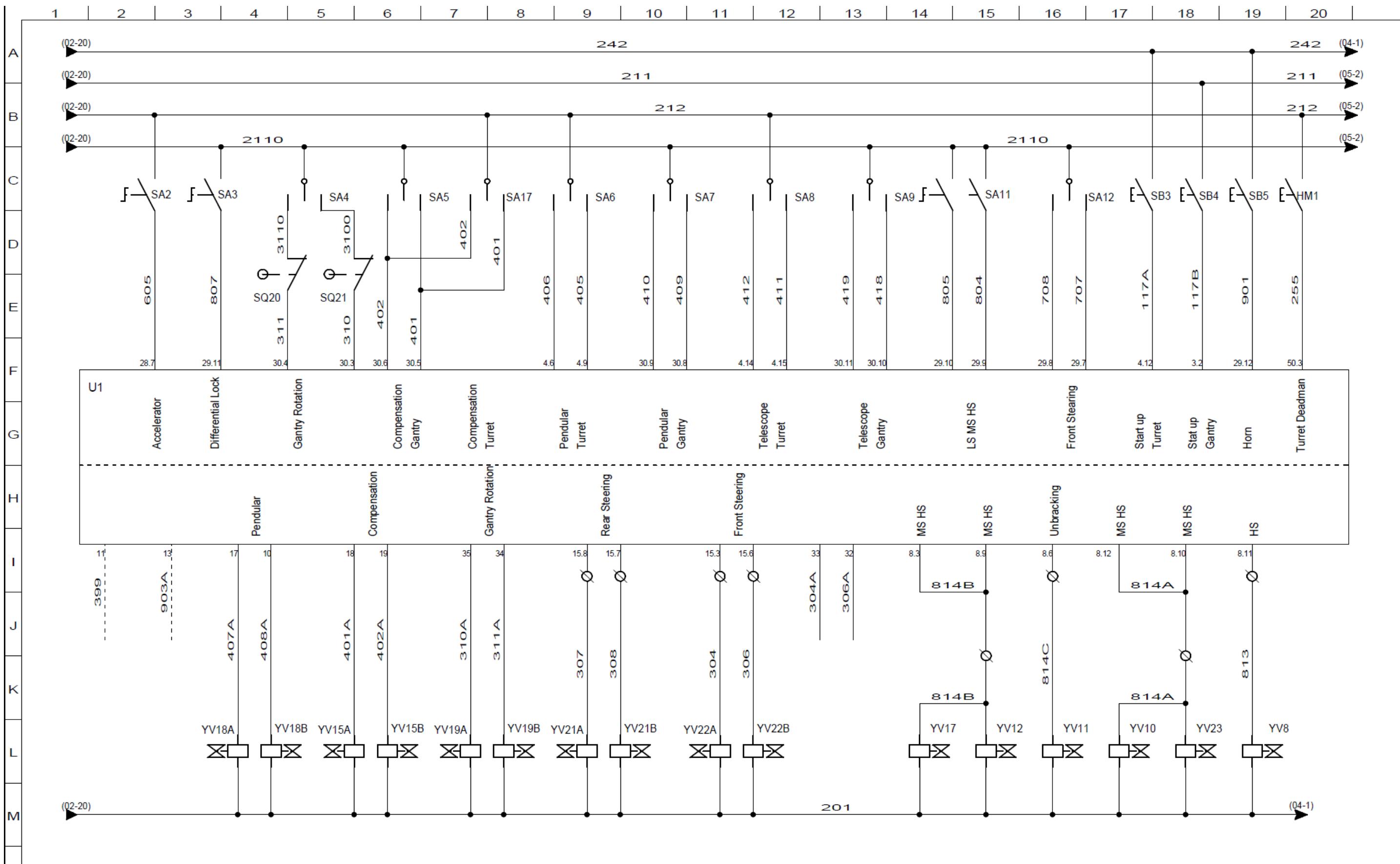
## 7. SPECIAL FUNCTIONS

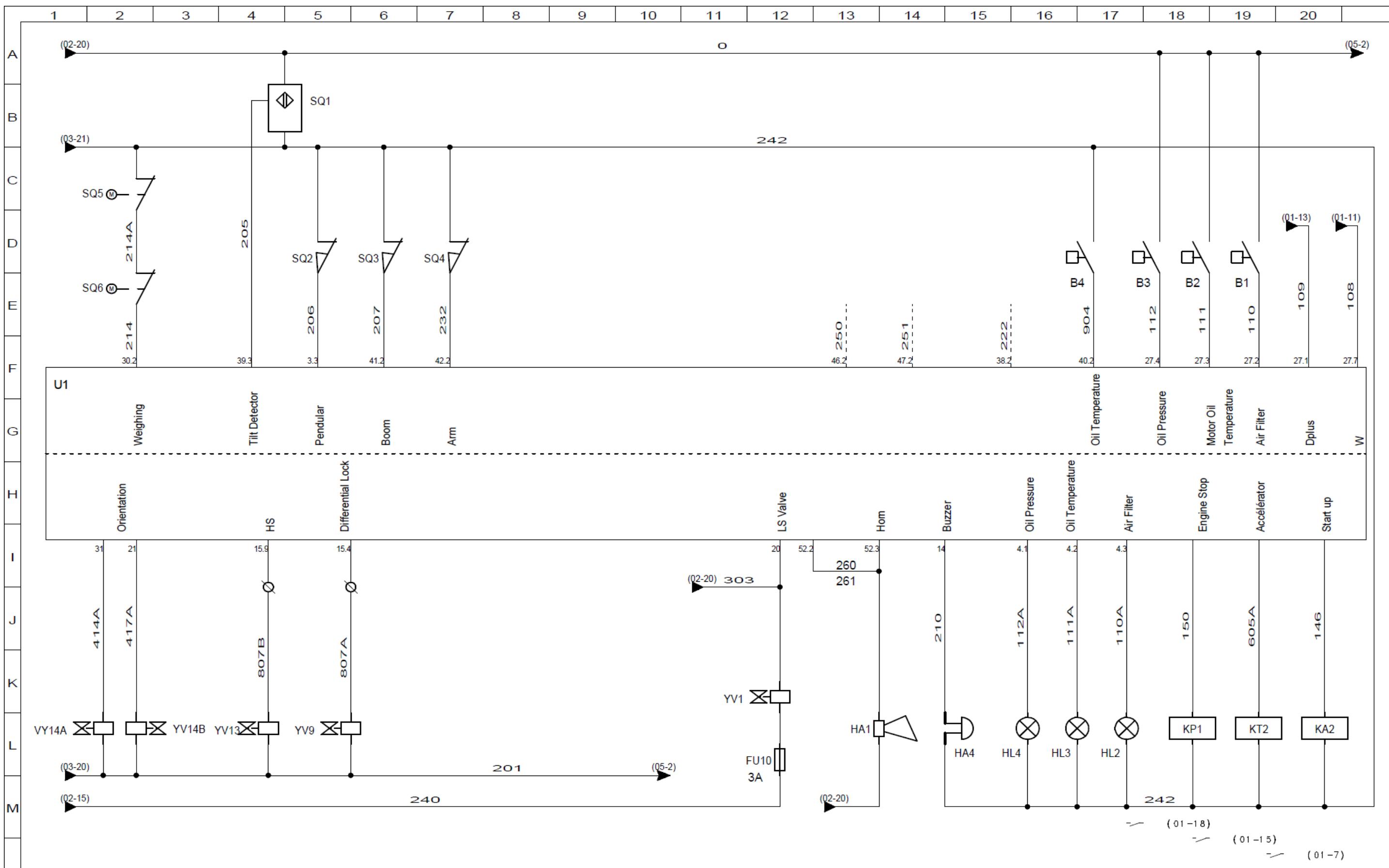
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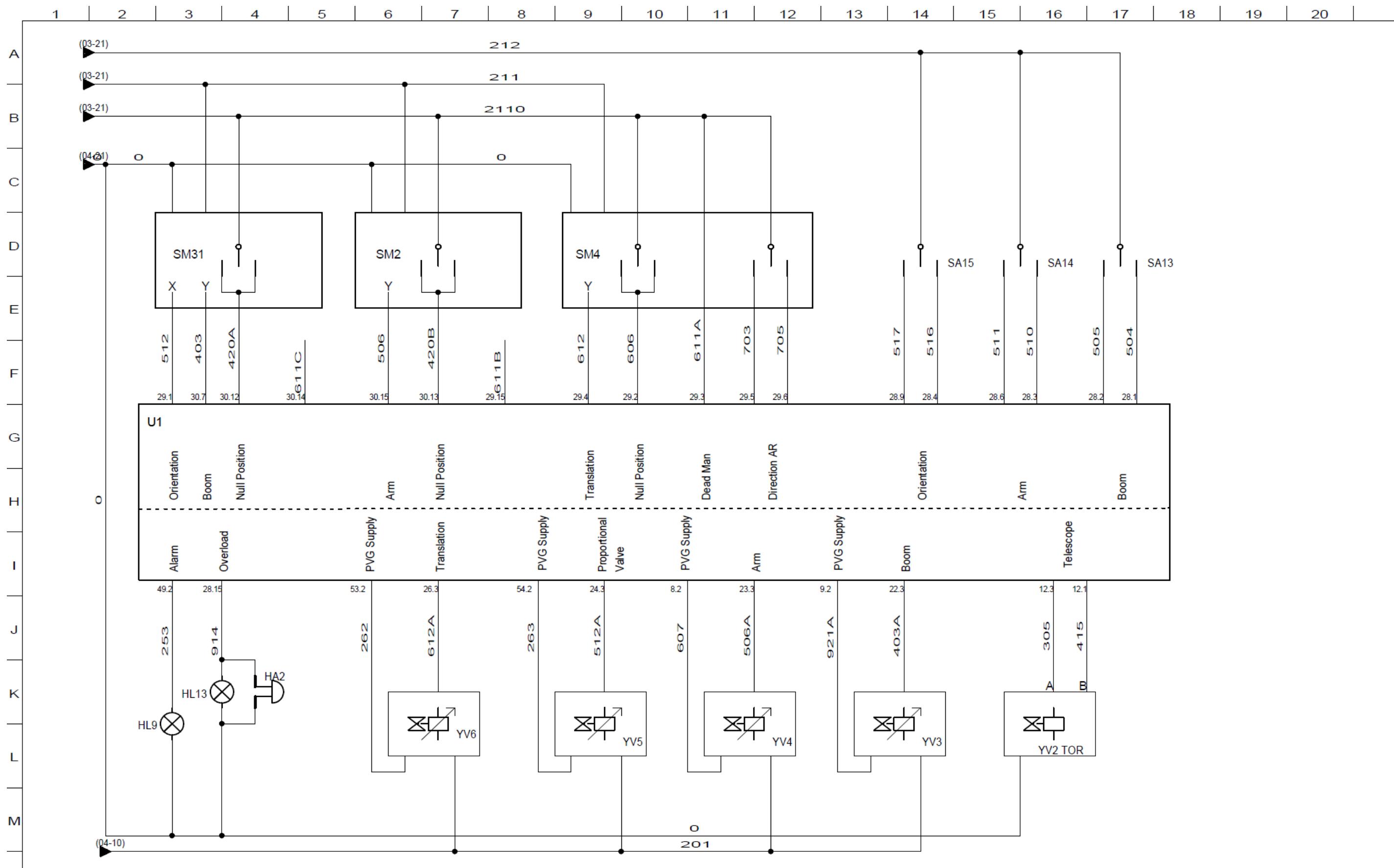
there is no special functions for these models

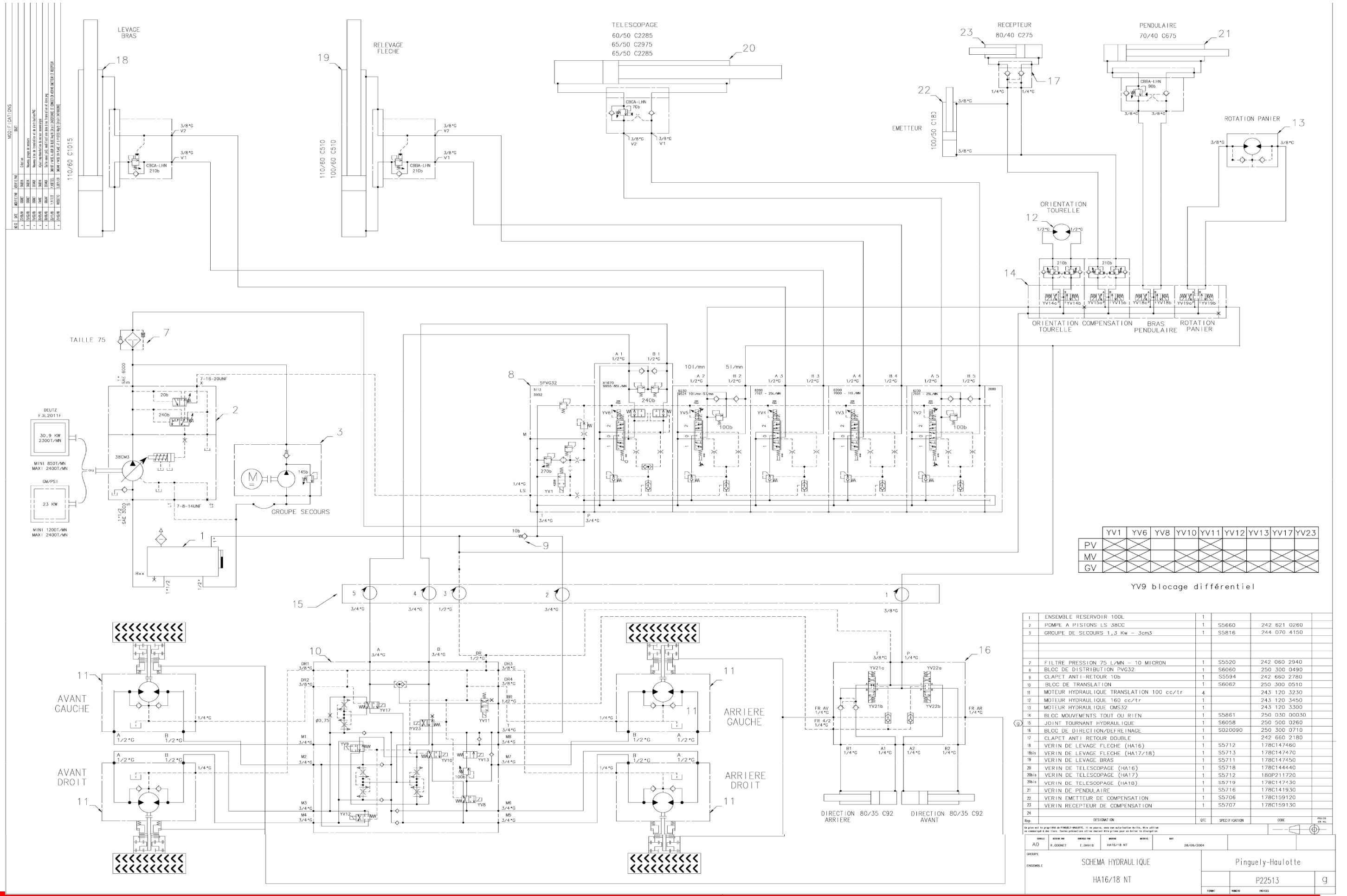


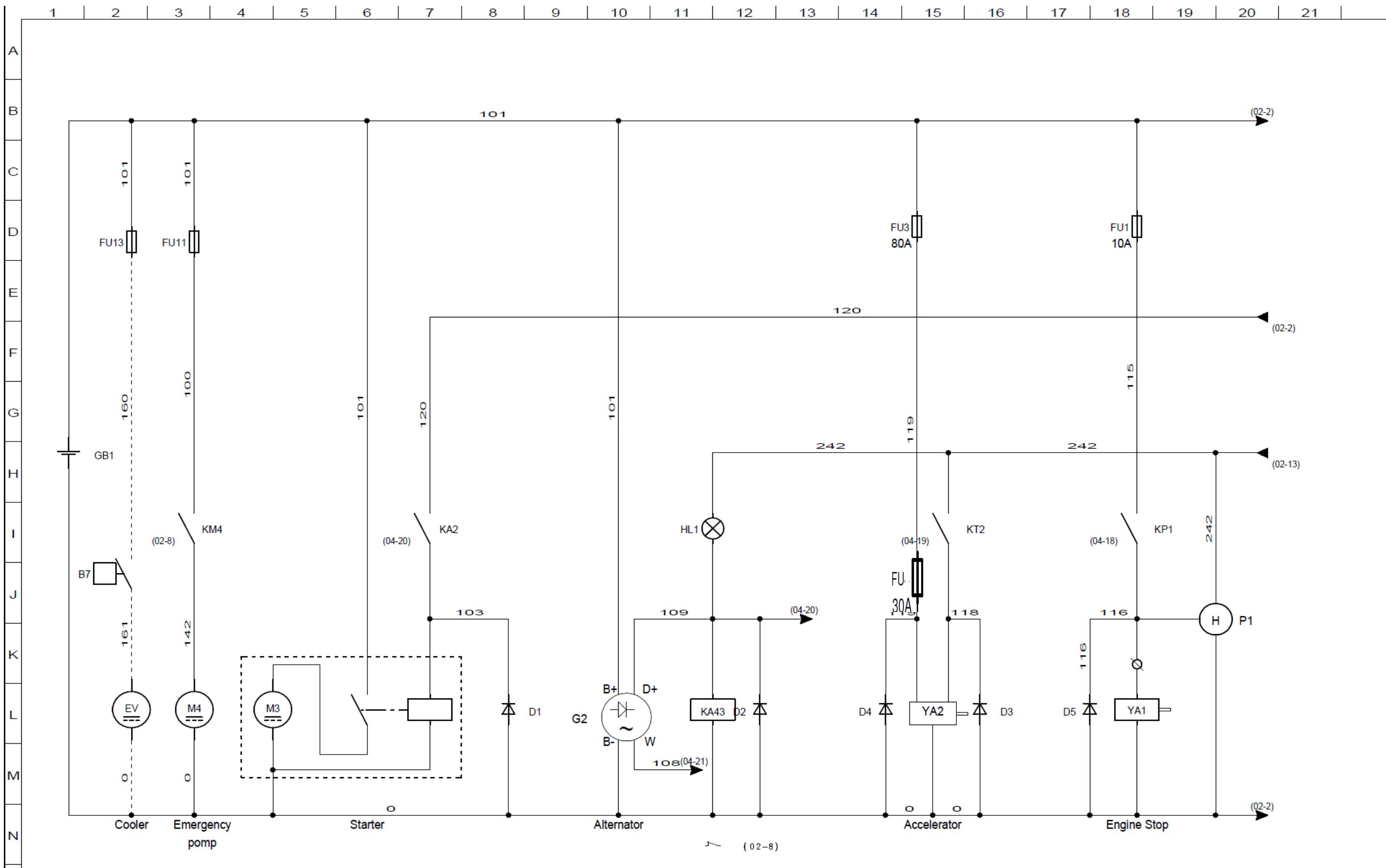


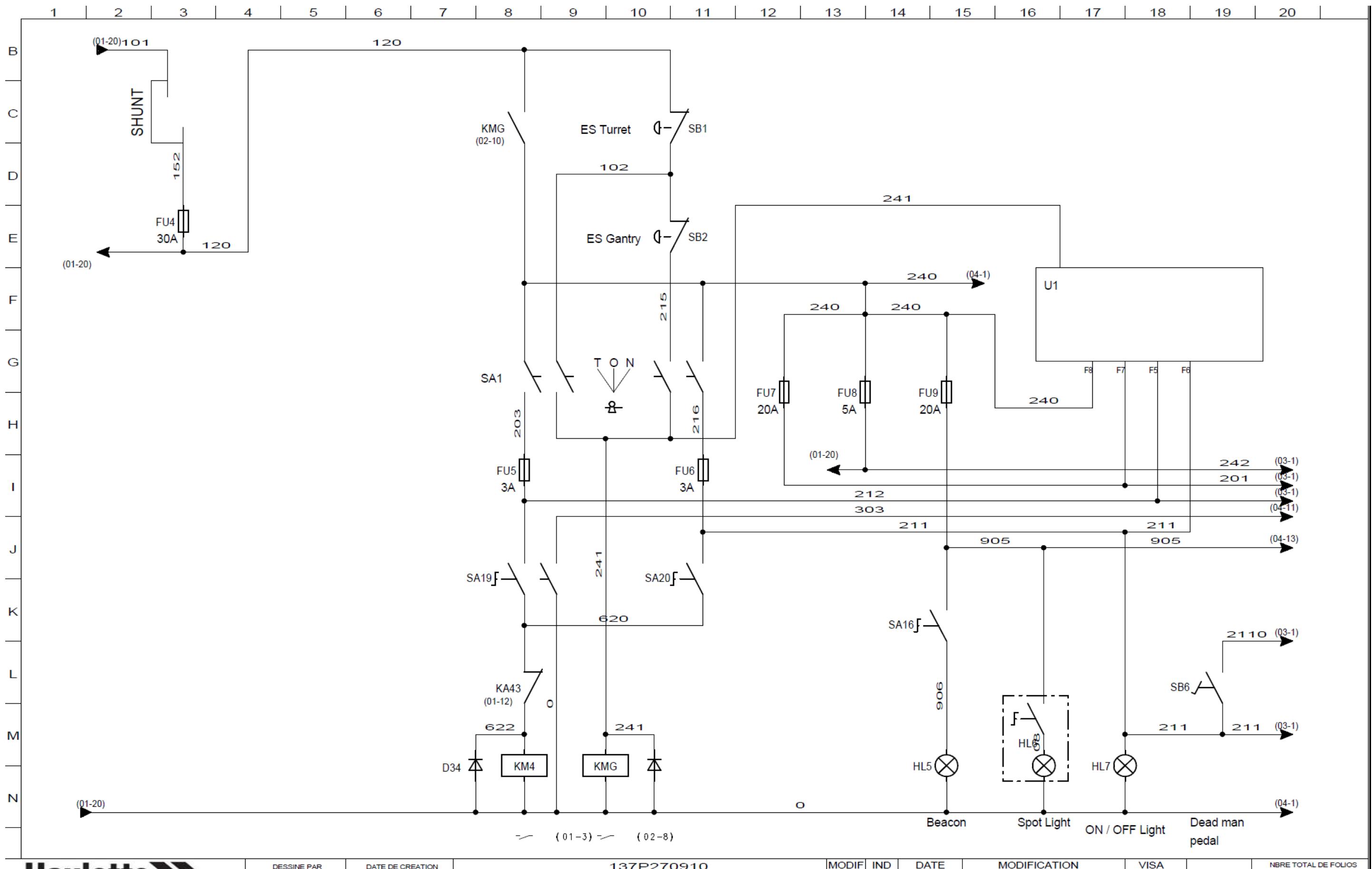


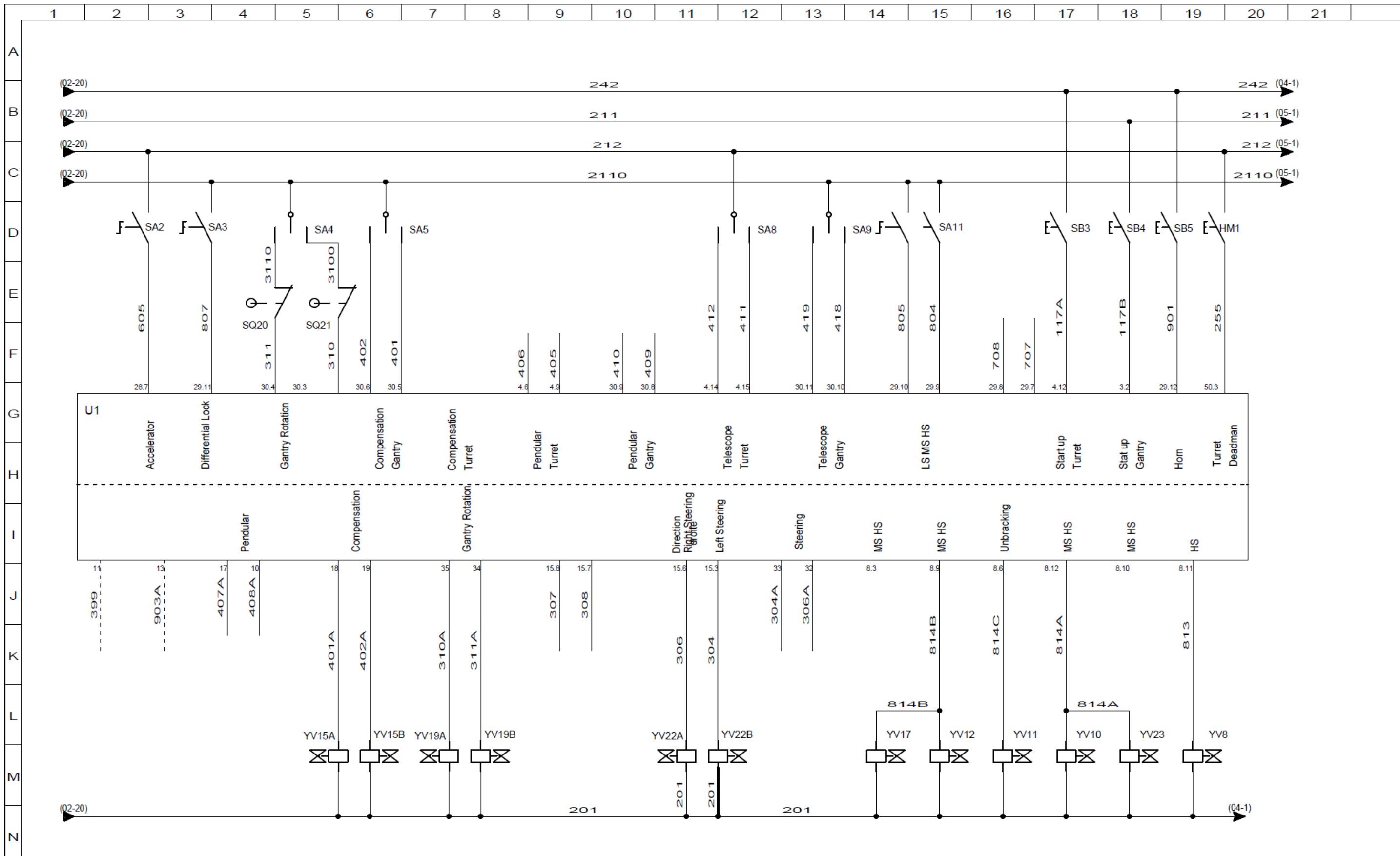


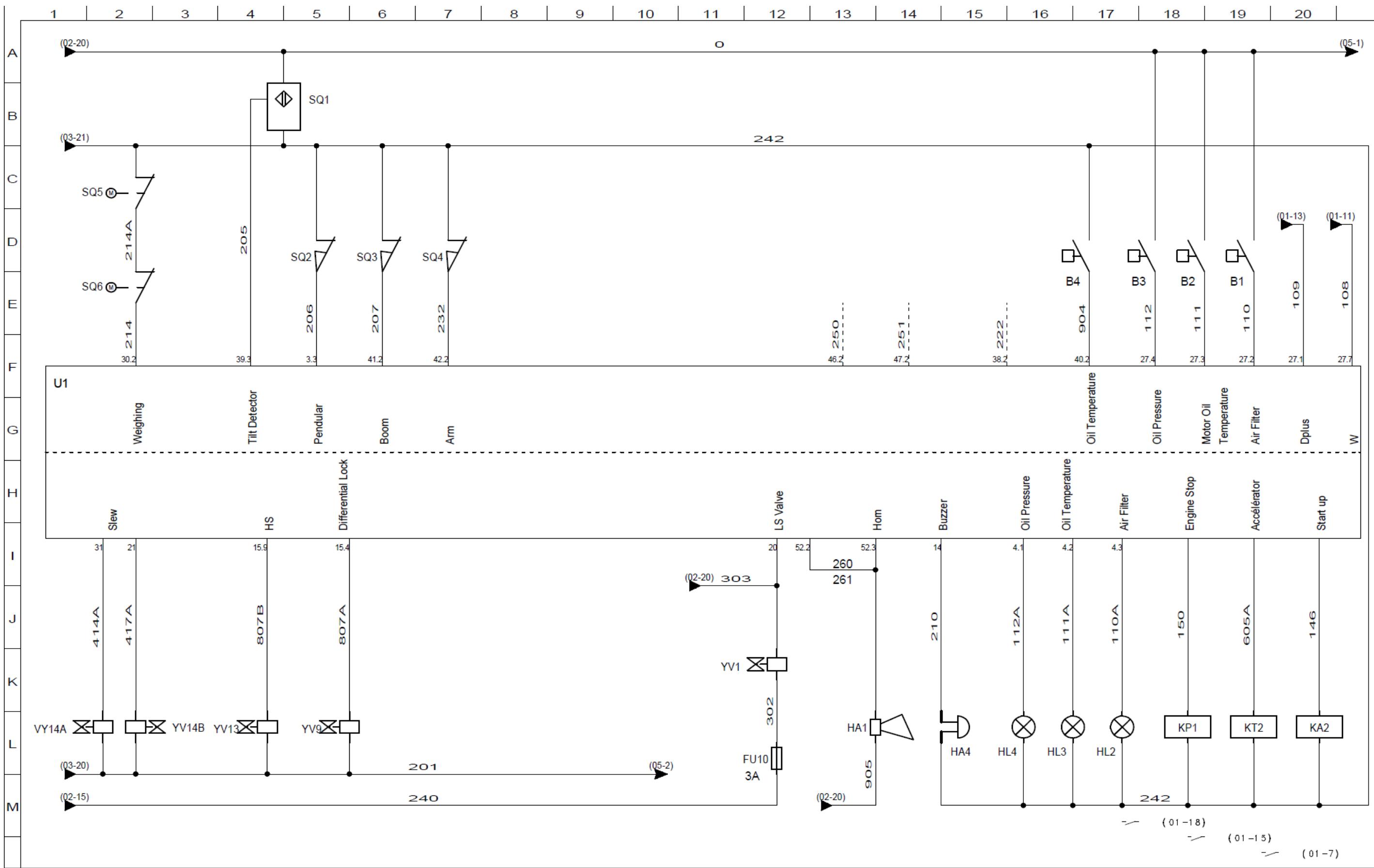


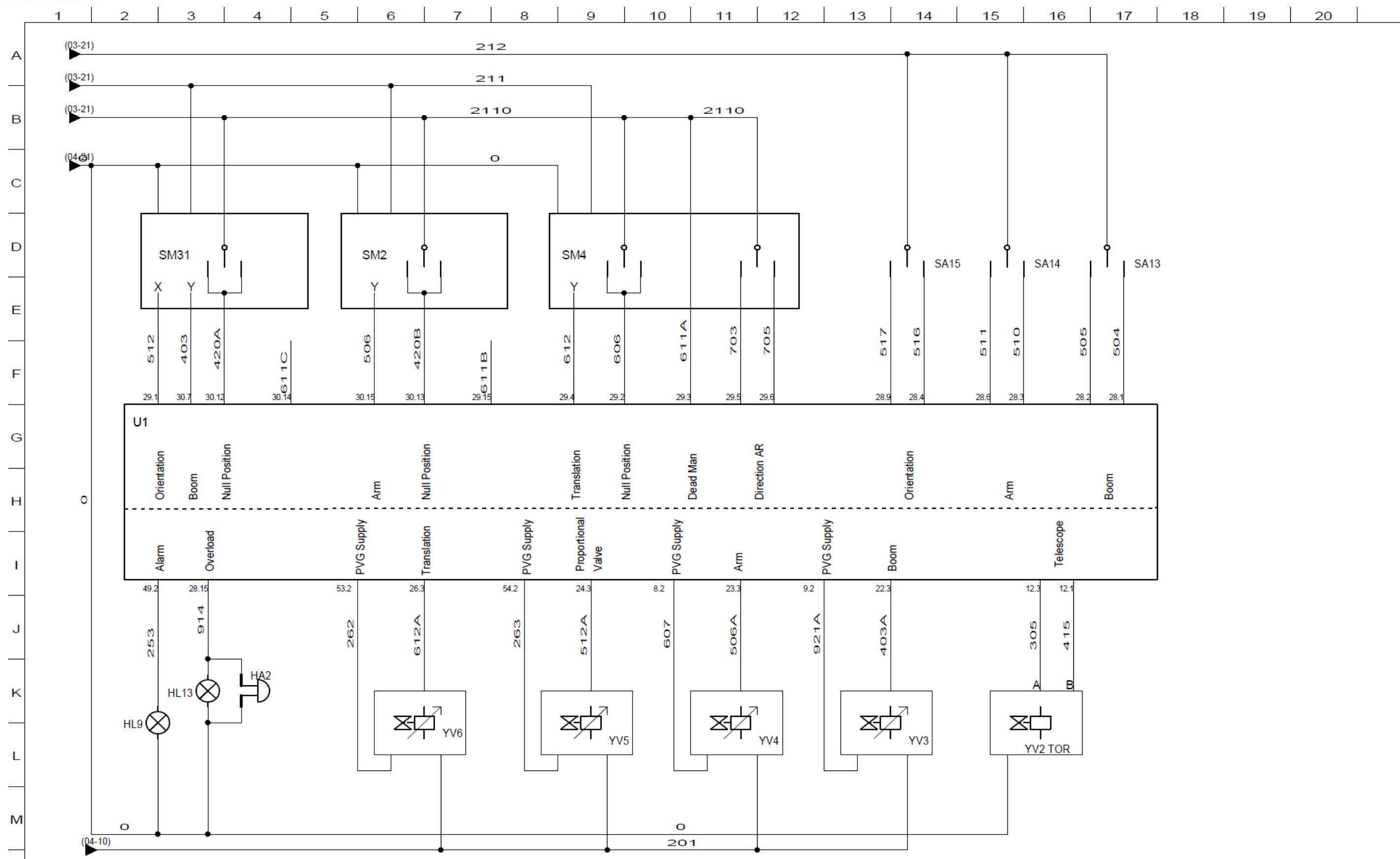


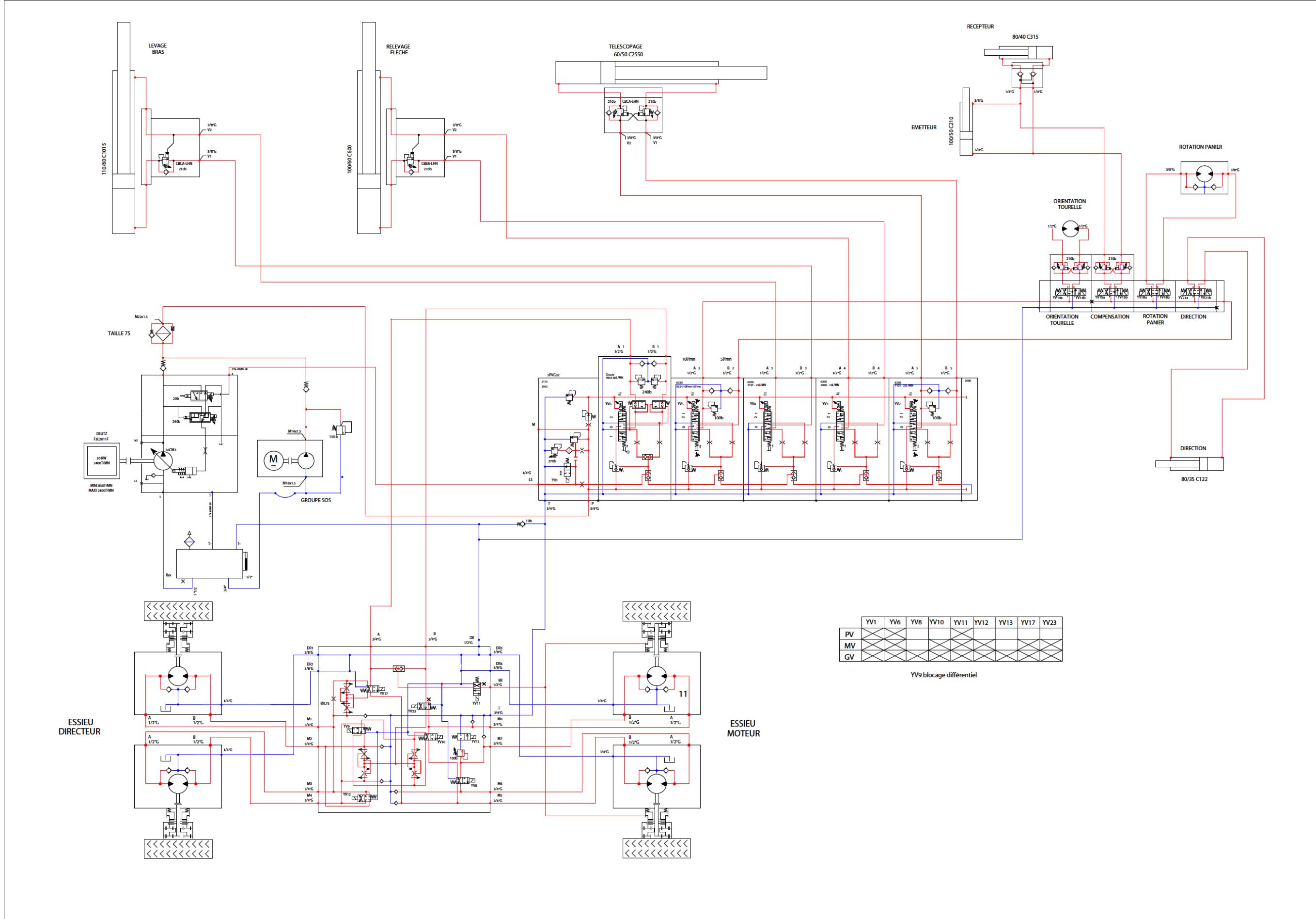








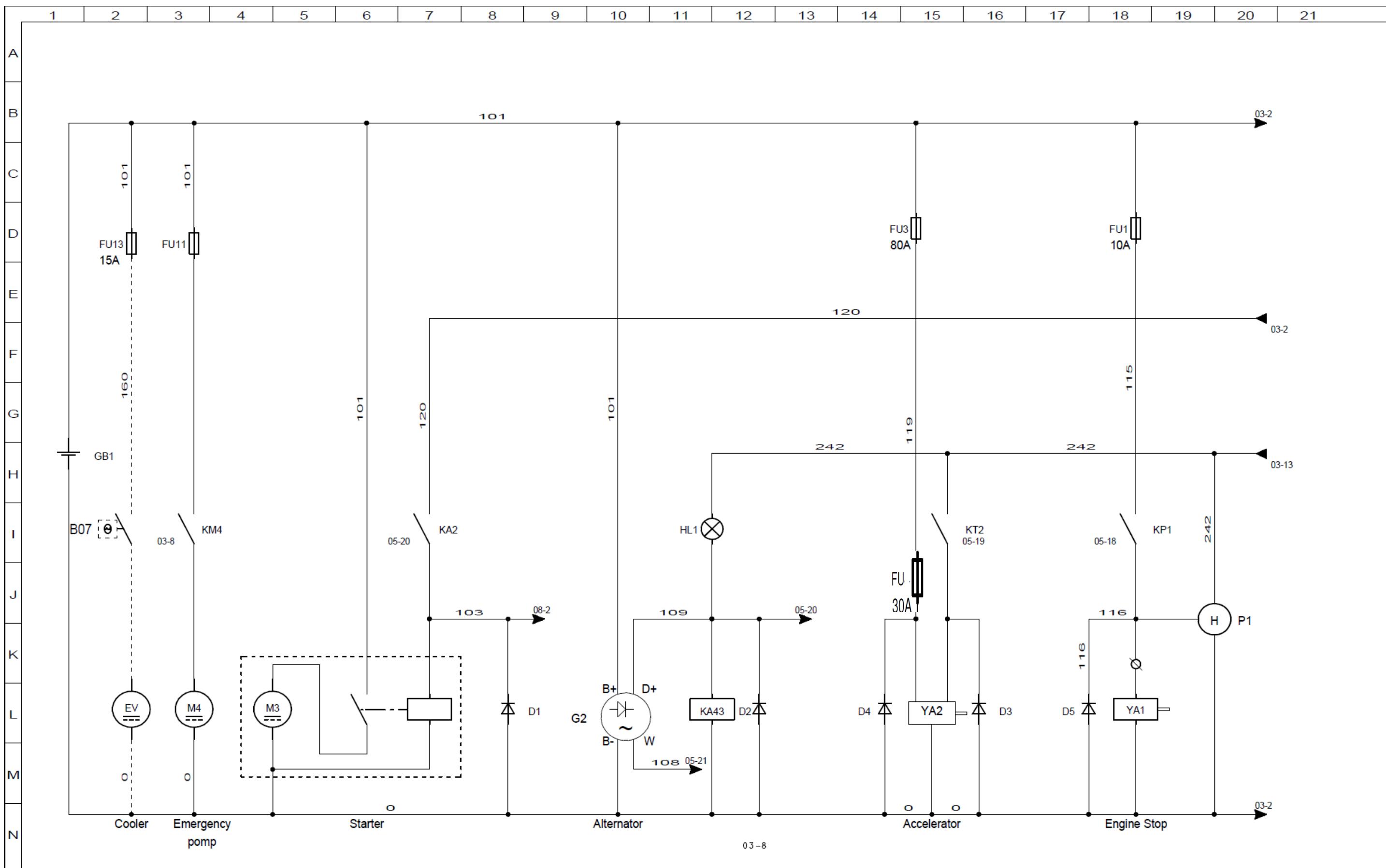


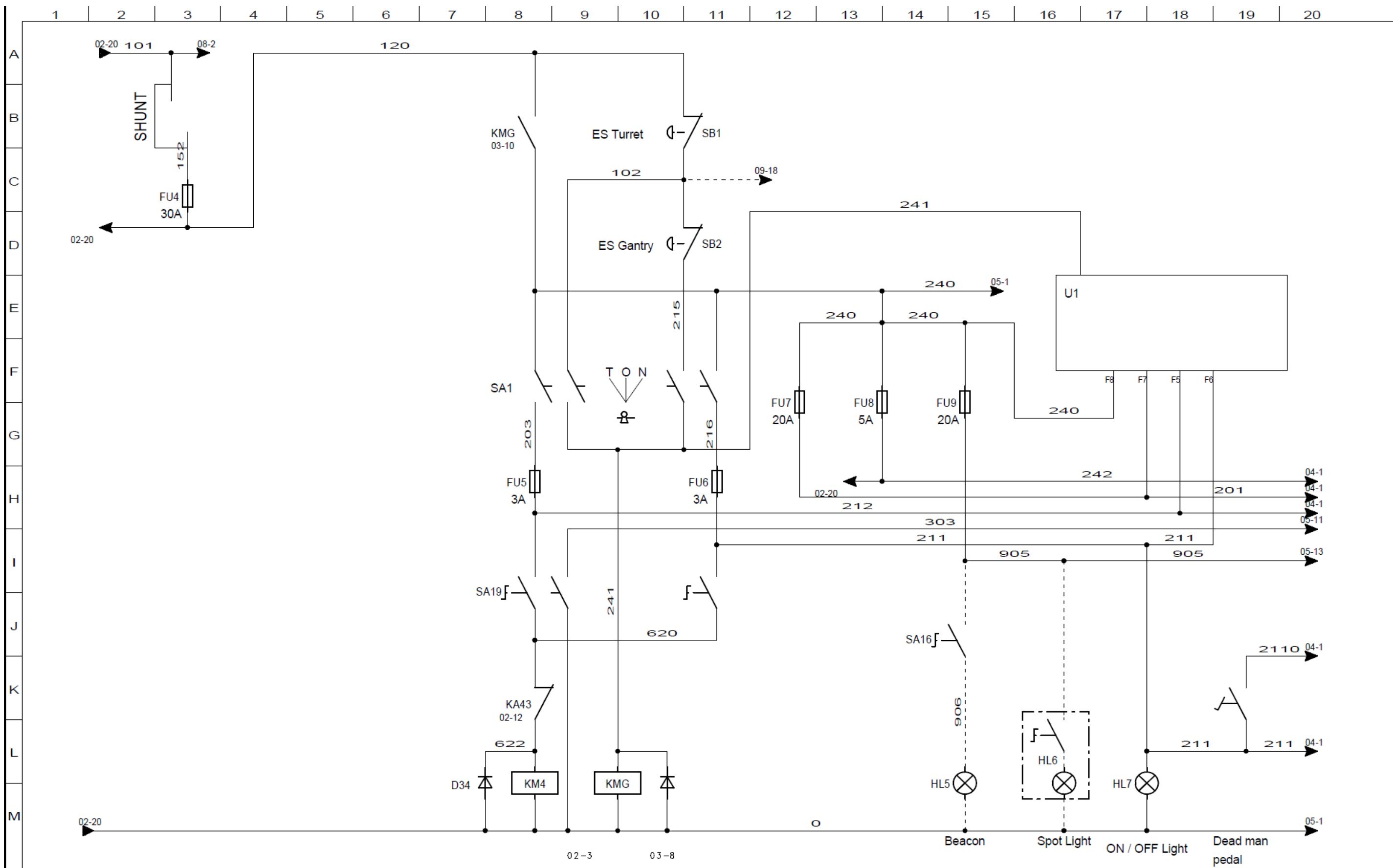


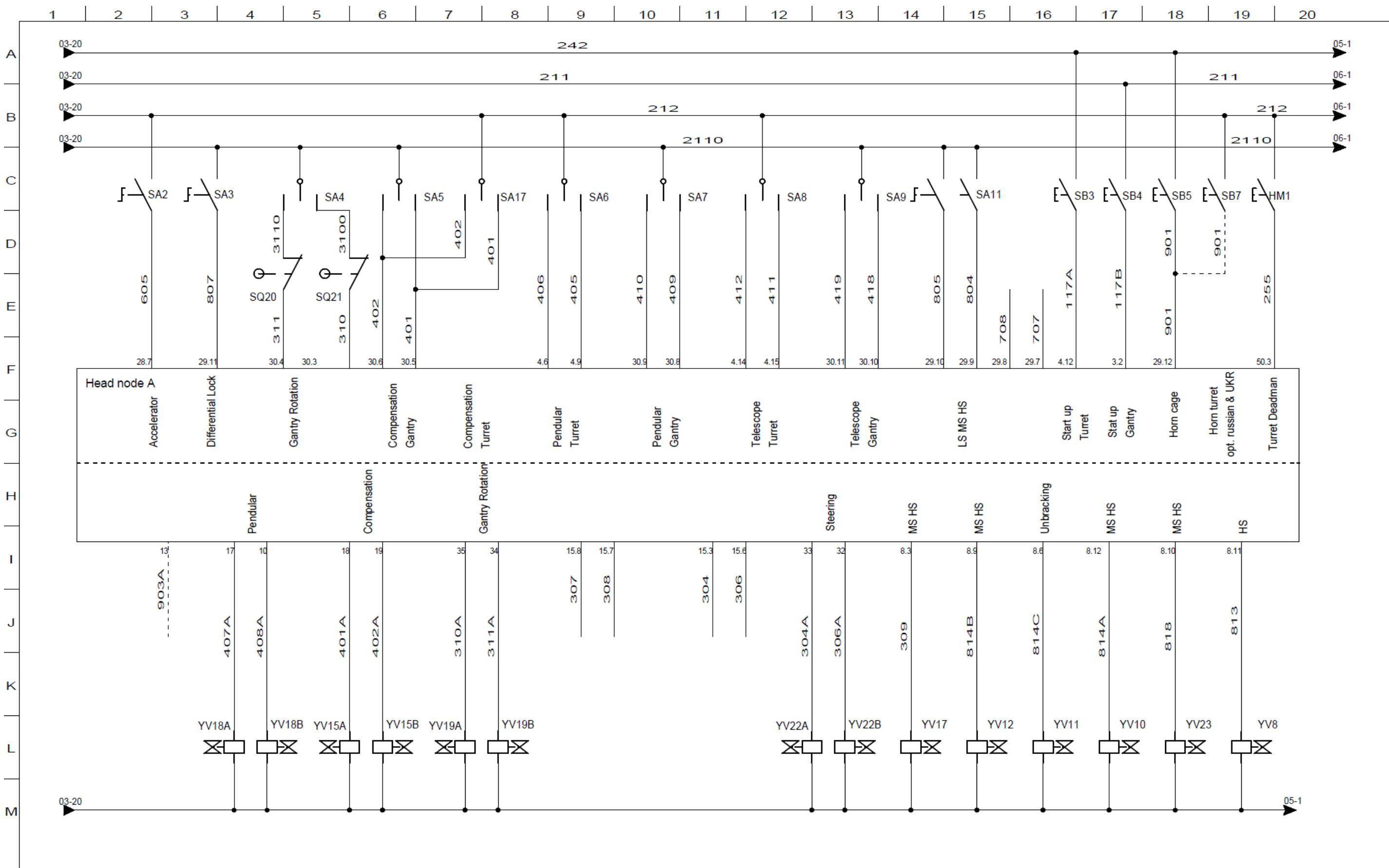
E595		HA16SPX					
F	ajout de toutes les opt. (DM7424)	DM7424	D.FERRATON	02/06/2009			
E	mod. câblage YV17 & YV23 (DM7588)		A. DURO	16/03/2009			
D	mod. alim. PVG + bouton HM DM7074 et DM7217		A DURO	12/03/2009			
C			A. DURO	01/07/2008			
B			A DURO	12/03/2009			
A			A.DURO	29/10/2008			
IND	MODIFICATION	N°MODIF	VISA	DATE	FOLIO		
DESSINE PAR	D.FERRATON	DATE DE CREATION	13/03/2009		SCHEMAS		
VERIFIE PAR	N. DEAUX	DATE DE VERIFICATION	30/10/2008		Page de garde		
					NBRE TOTAL DE FOLIOS 09		
					FOLIO 01		

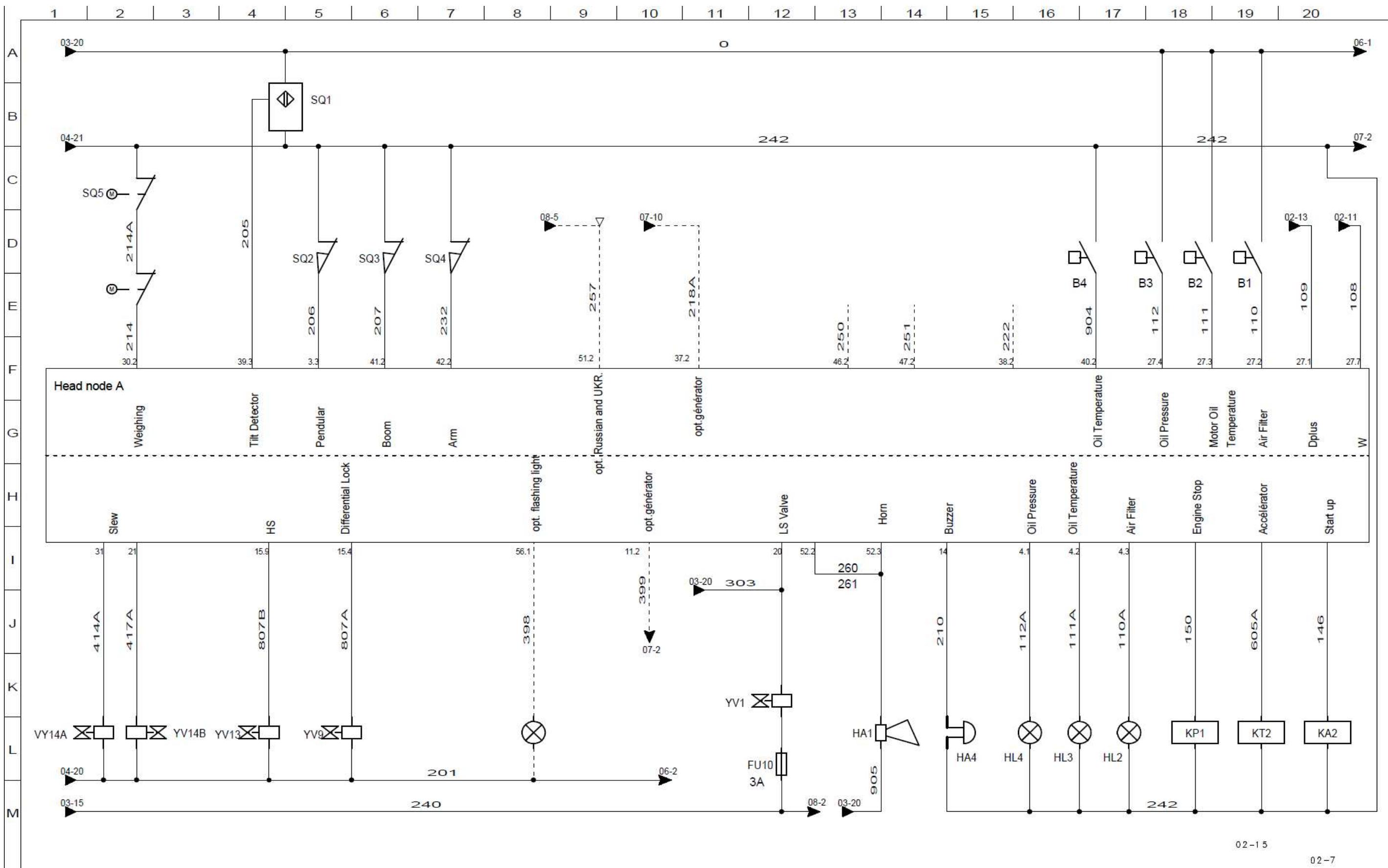


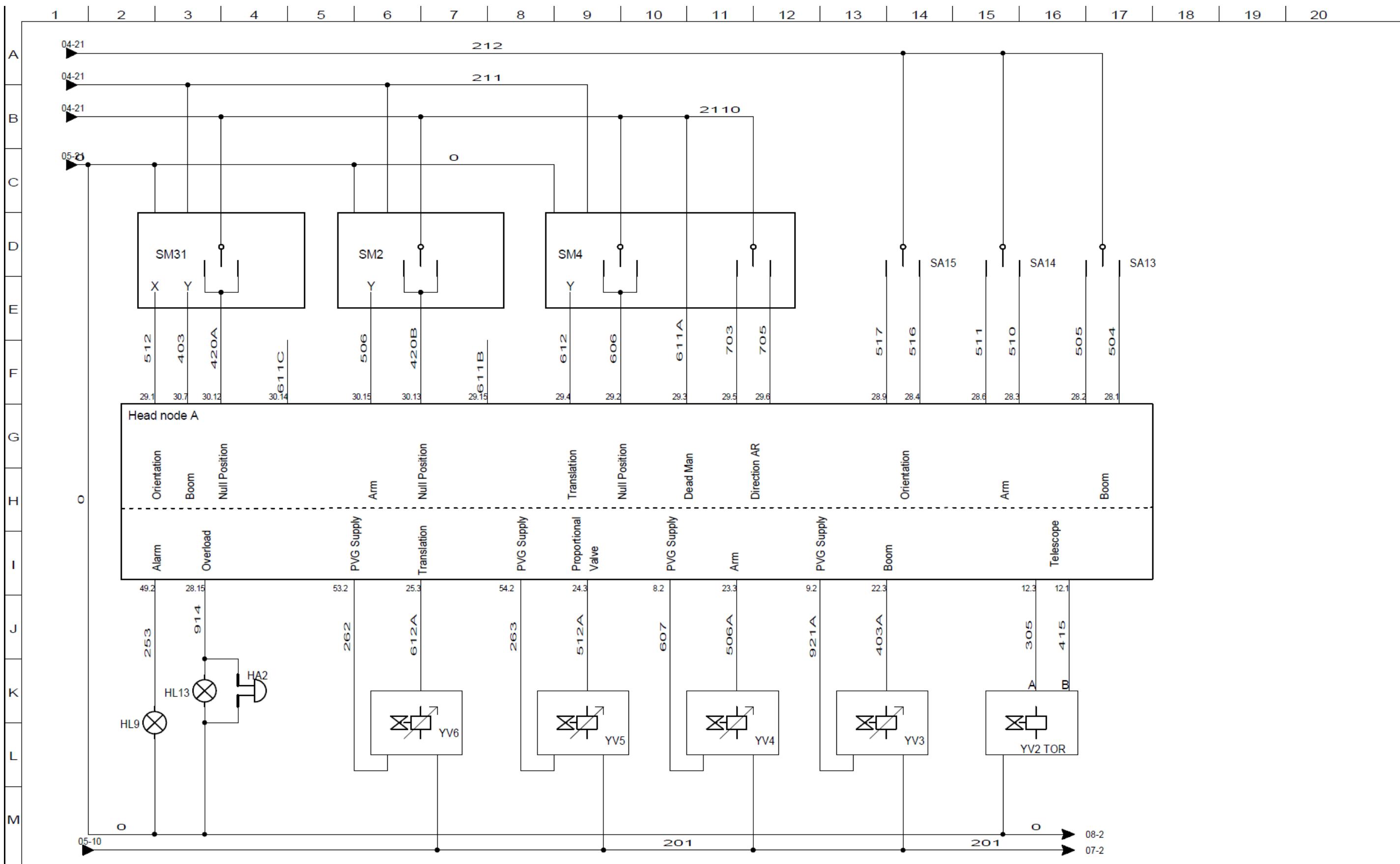
FOLIO	DESIGNATION	COMMENTAIRES
1	Title page	
2	Power	
3	Station selection	
4	Input-output Calculator	
5	Input-output Calculator	
6	Joysticks	
7	Options	
8	Options	
9	Options	

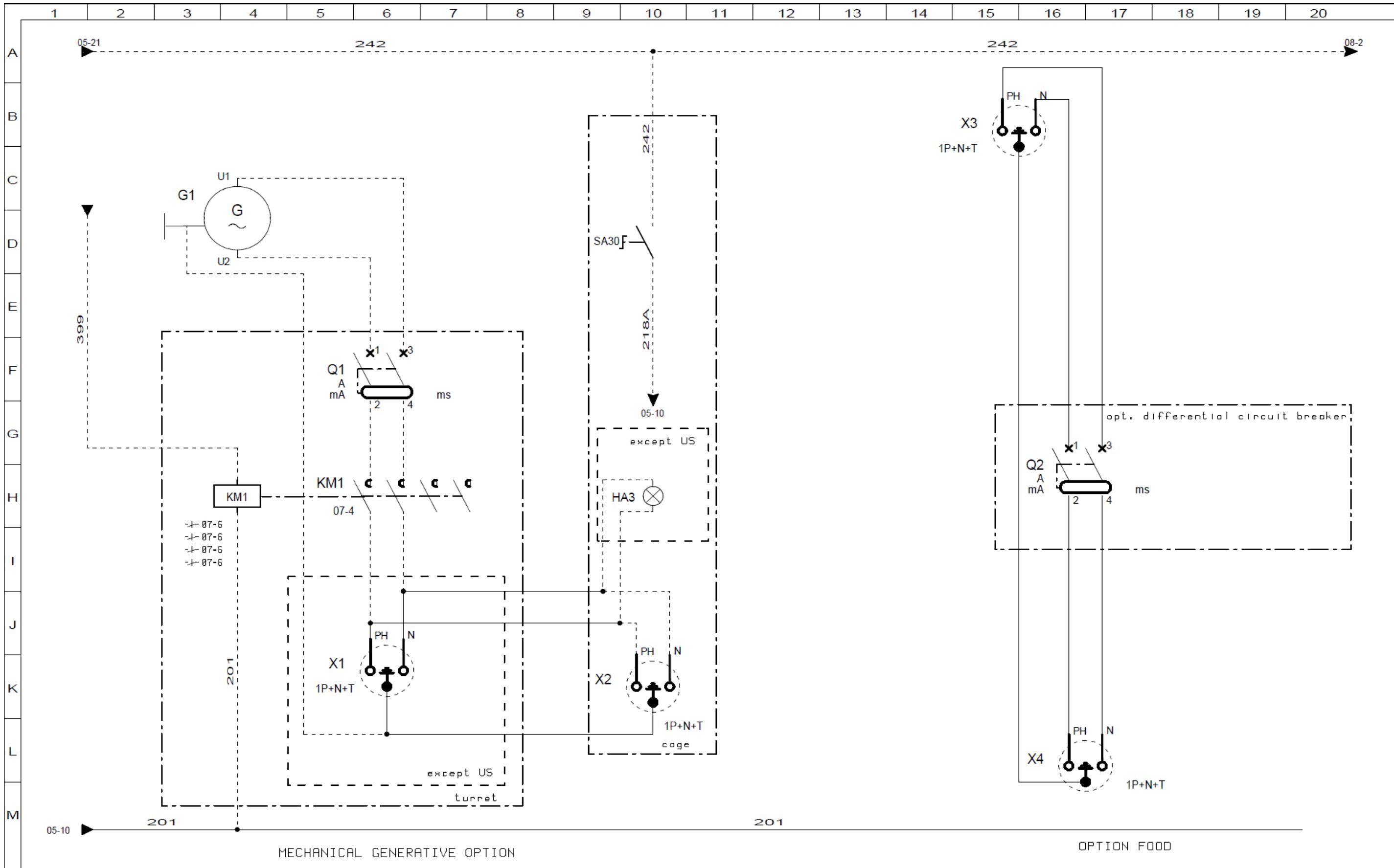


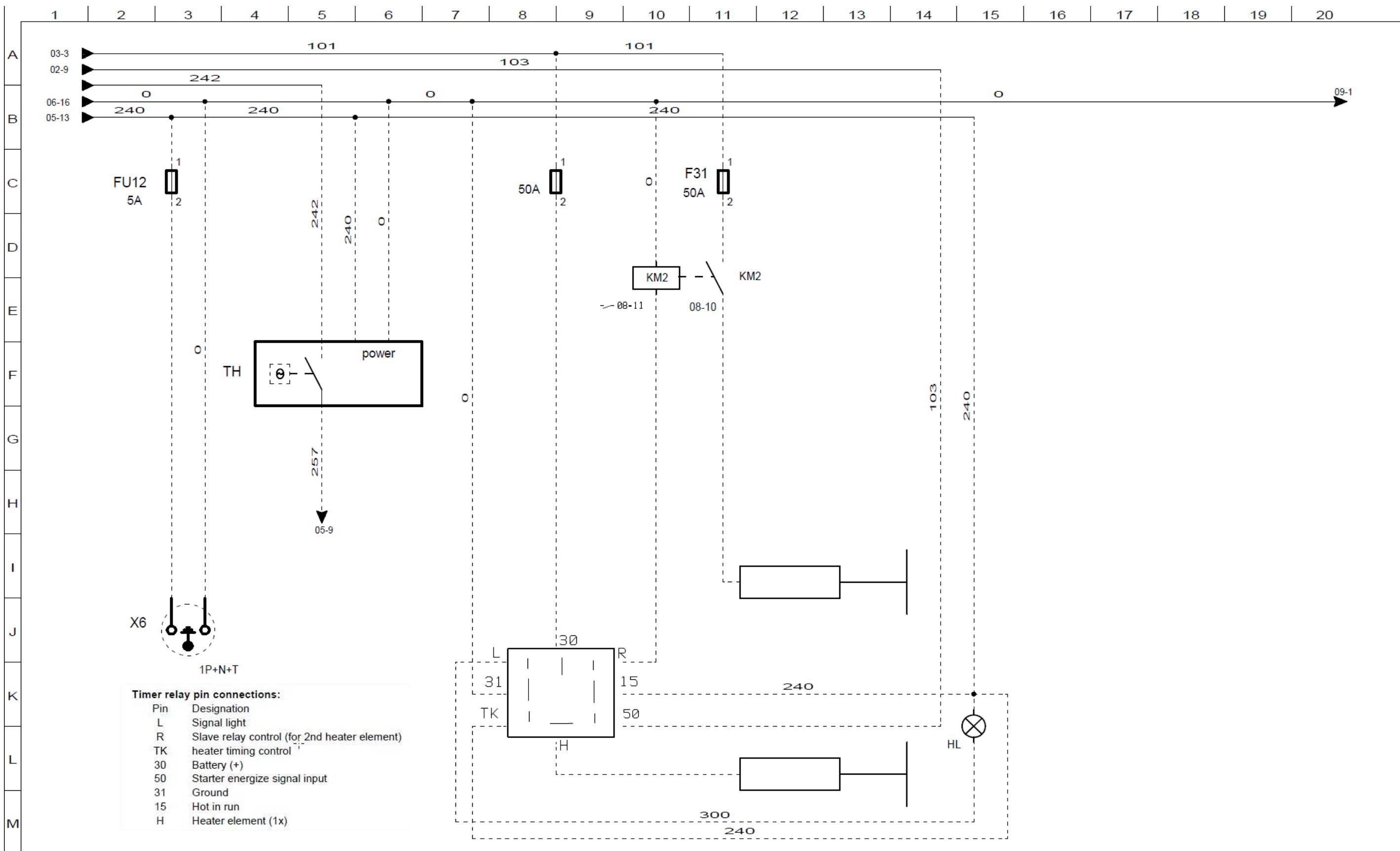










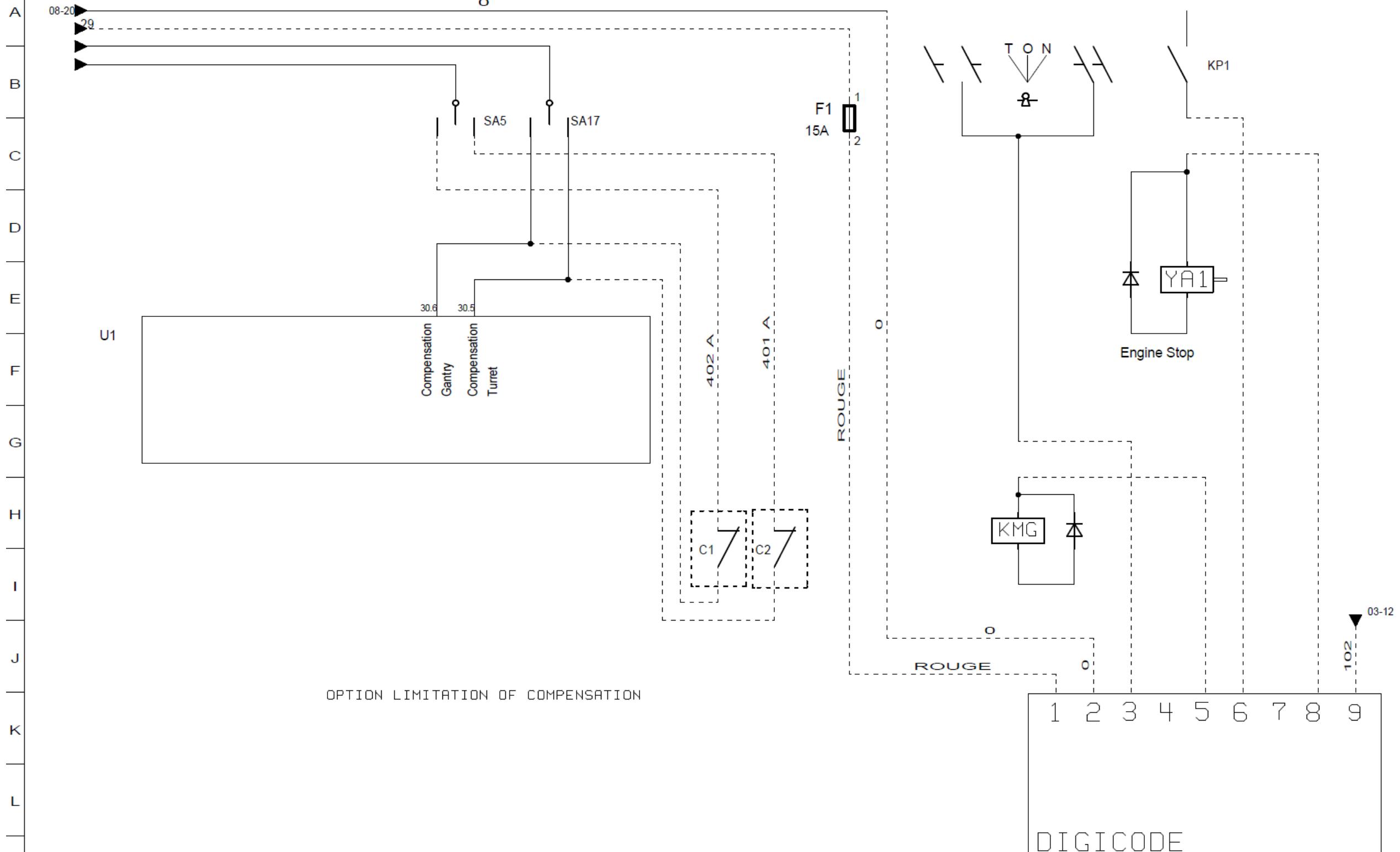


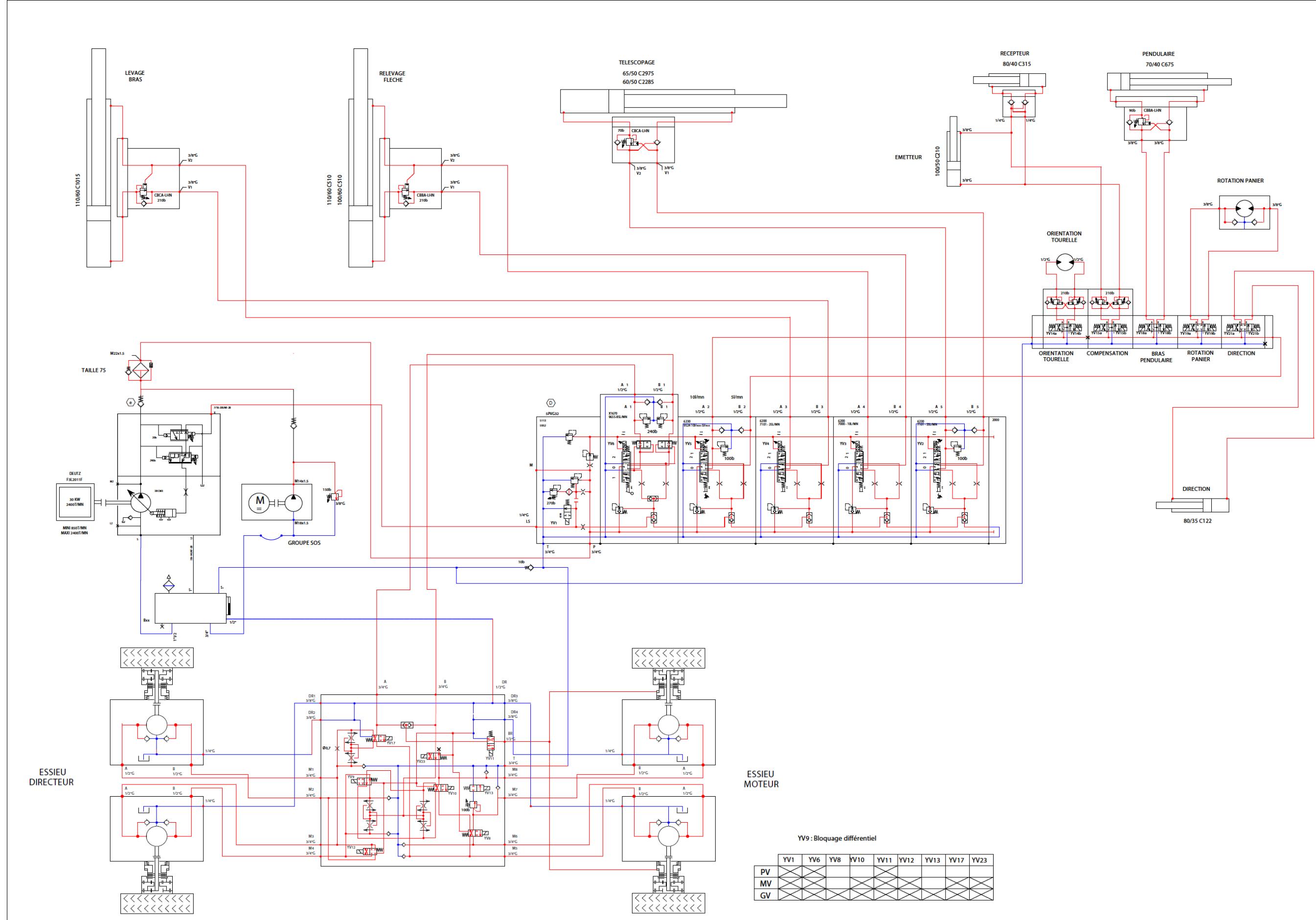
#### Timer relay pin connections:

Pin	Designation
L	Signal light
R	Slave relay control (for 2nd heater element)
TK	heater timing control
30	Battery (+)
50	Starter energize signal input
31	Ground
15	Hot in run
H	Heater element (1x)

RUSSIAN OPTION

## OPTION PREHEATING TO MOTOR



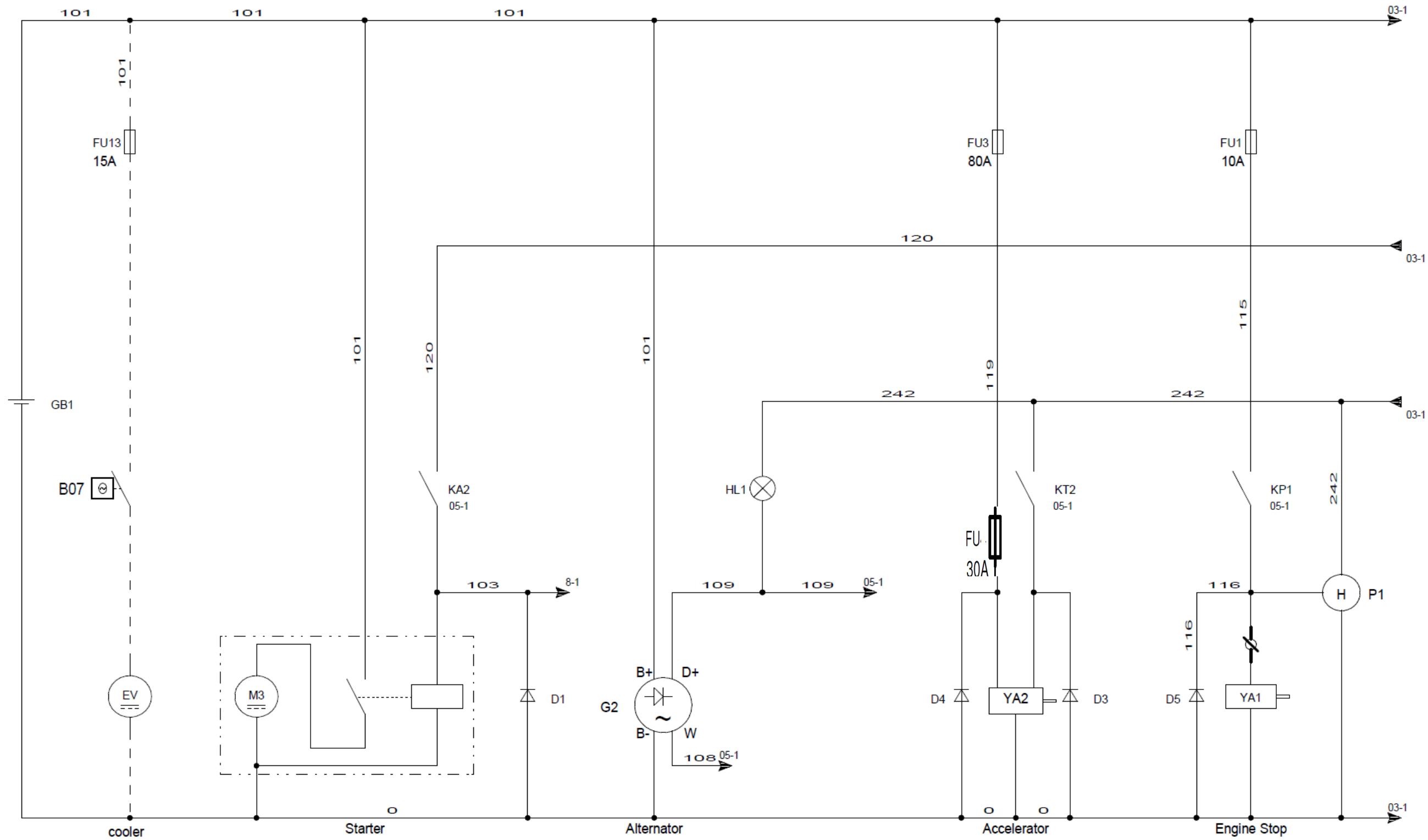


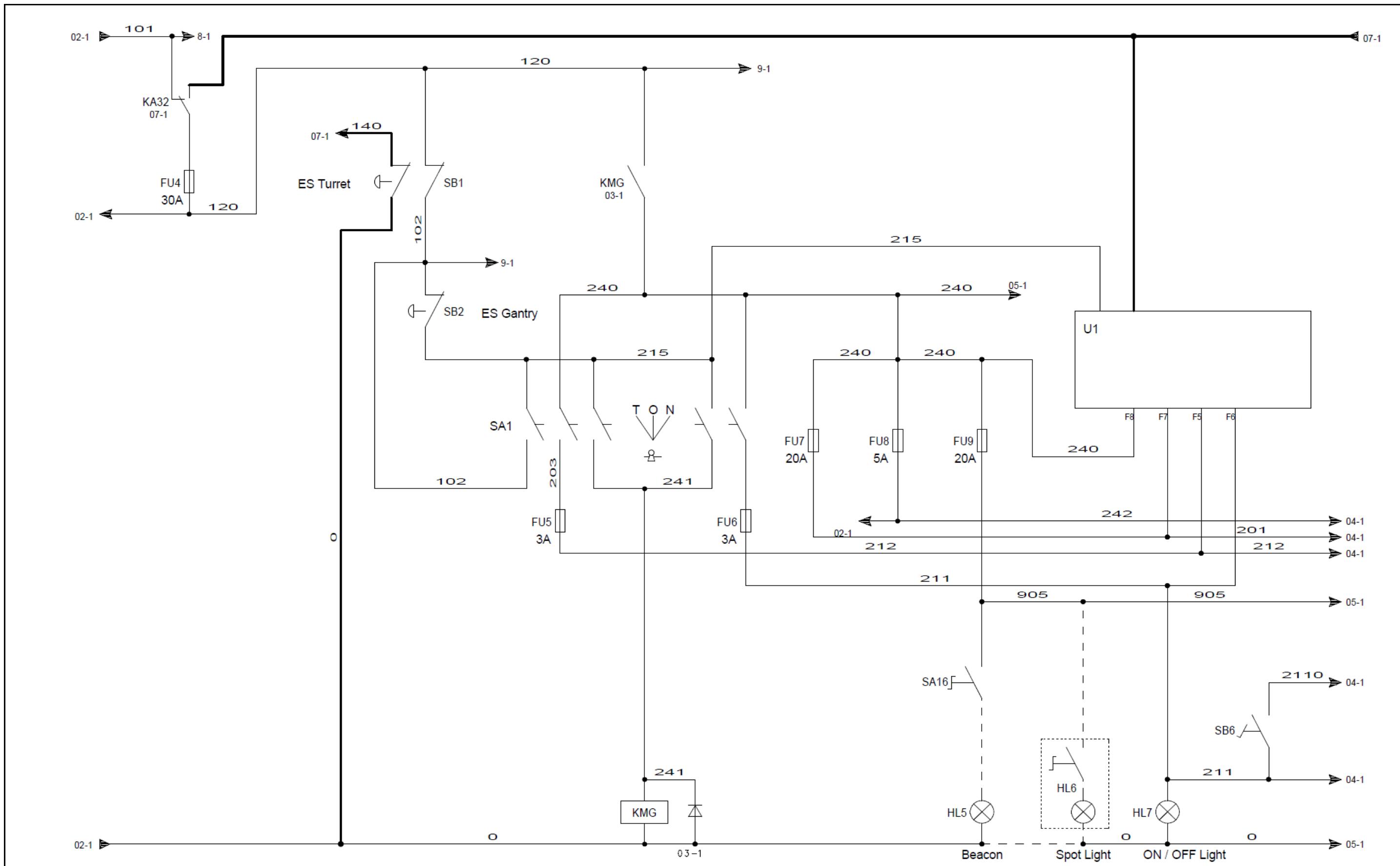
**E586**
**HA16PE**

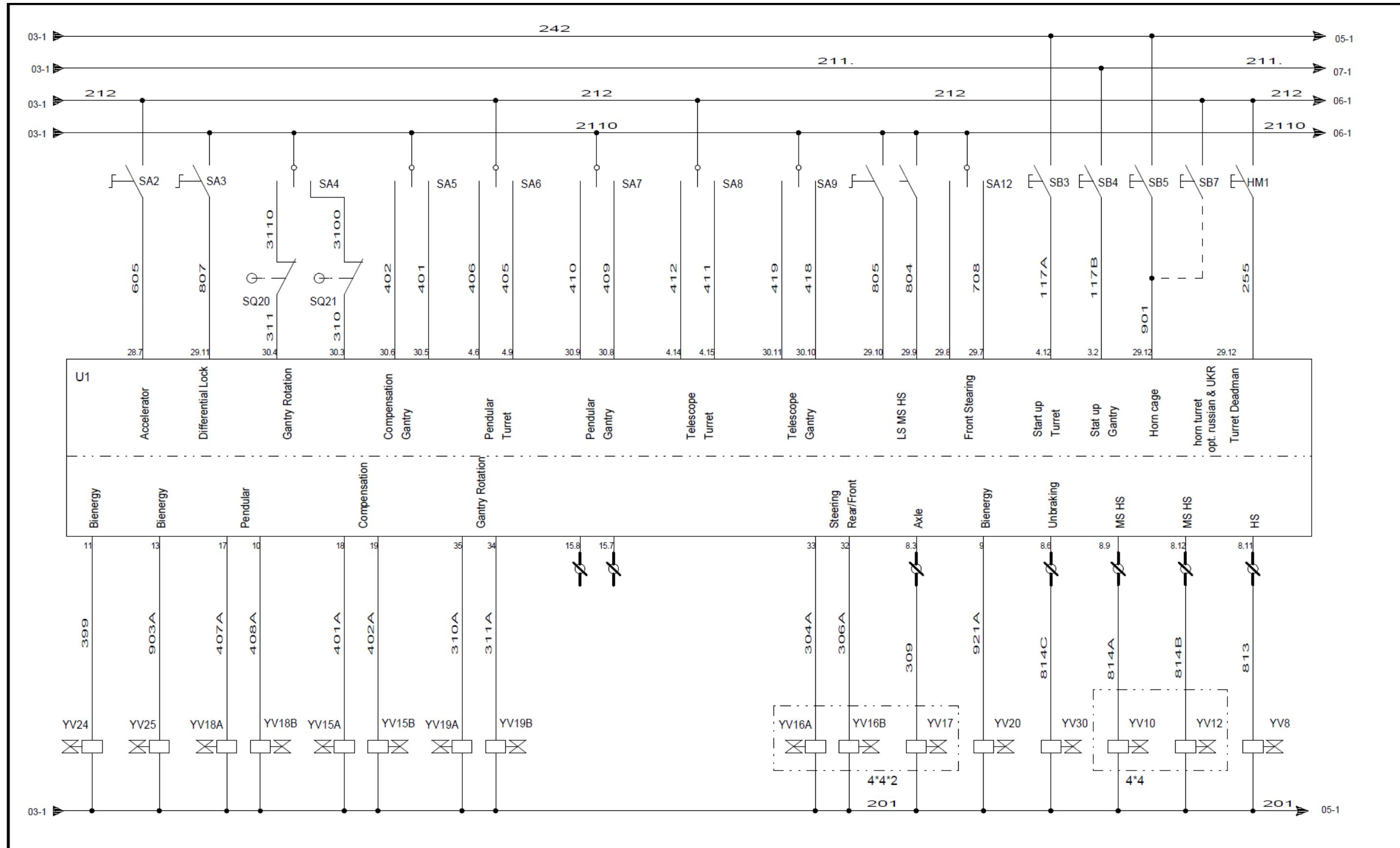
E	ajout de toutes les options(DM7424)	DM7424	D FERRATON	17/03/2009	
D	modif. câblage YV17 et YV23 (DM7588)		A. DURO	12/03/2009	
C	mod. alim. PVG + bouton HM (DM7074 et DM7217)		A. DURO	01/07/2008	
B			A DURO	12/03/2009	
A			A.DURO	29/10/2008	
IND	MODIFICATION	N°MODIF	VISA	DATE	FOLIO
DESSINE PAR	D.FERRATON	DATE DE CREATION	13/03/2009	<b>SCHEMAS</b>	
VERIFIE PAR	N. DEAUX	DATE DE VERIFICATION	30/10/2008	Page de garde	
				NBRE TOTAL DE FOLIOS 10	FOLIO 01

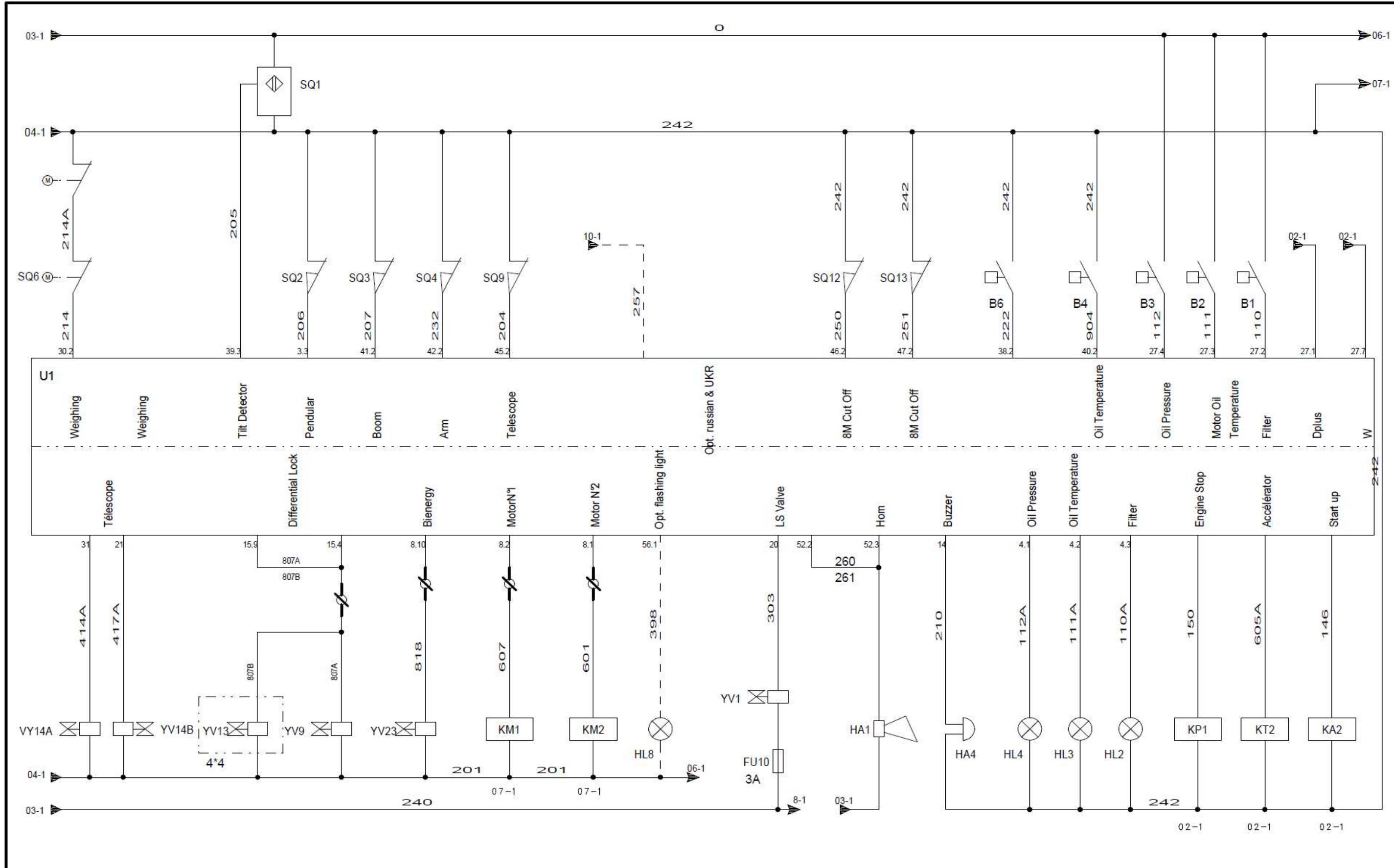

**Haulotte**  
GROUP

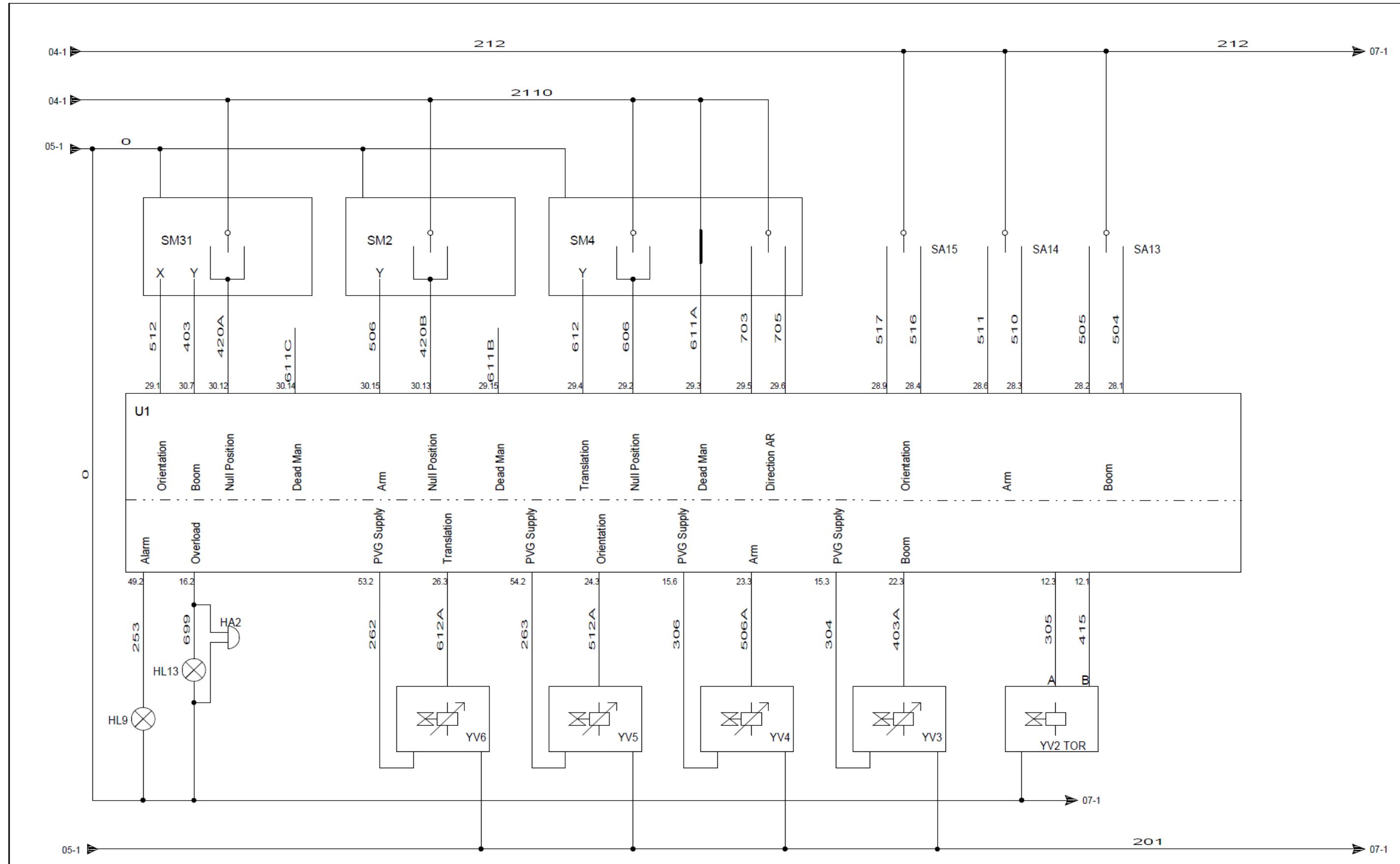
FOLIO	DESIGNATION	COMMENTAIRES
1	Title page	
2	Power	
3	Station selection	
4	Input-output Calculator	
5	Input-output Calculator	
6	Joysticks	
7	Options	
8	Options	
9	Options	

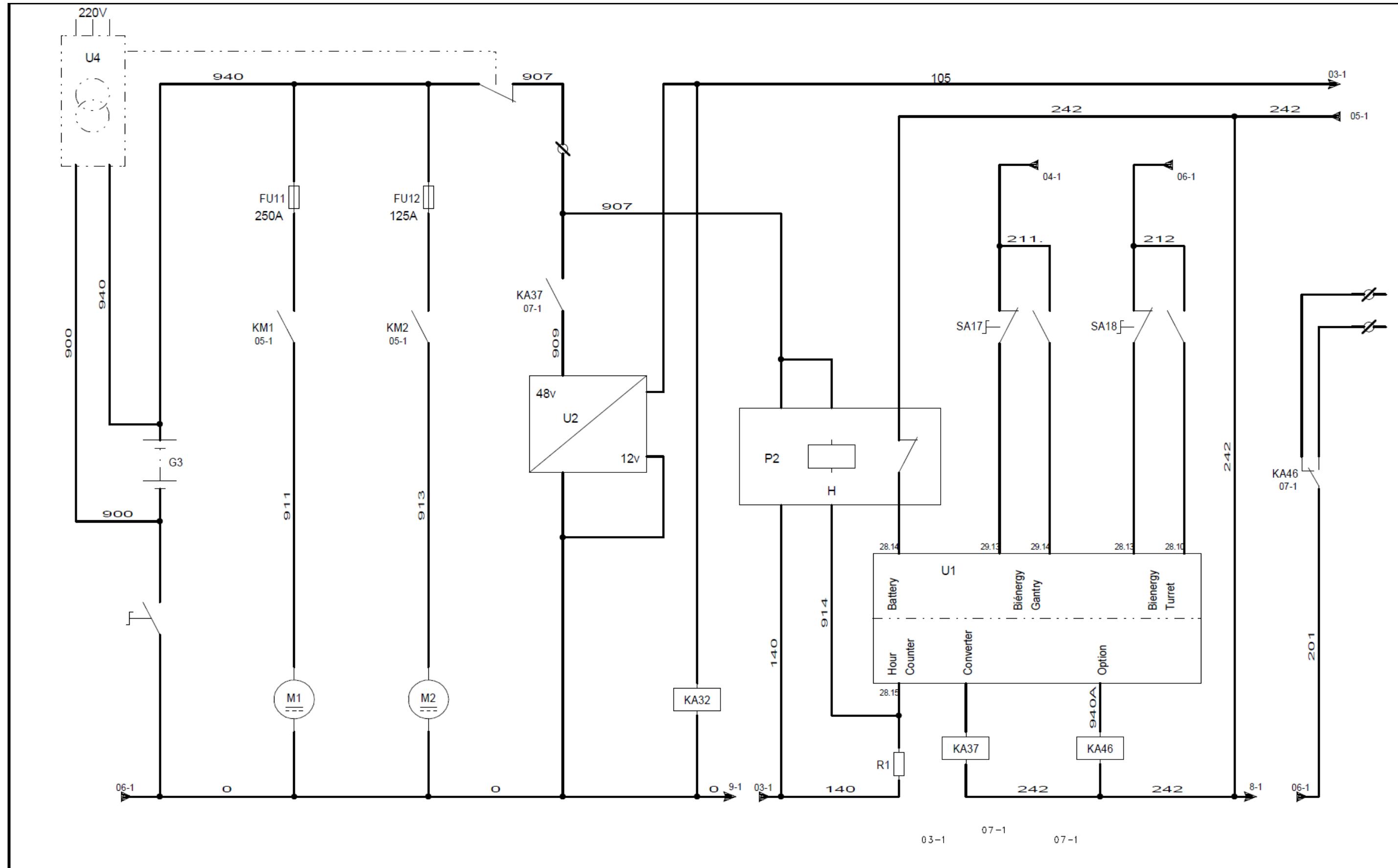


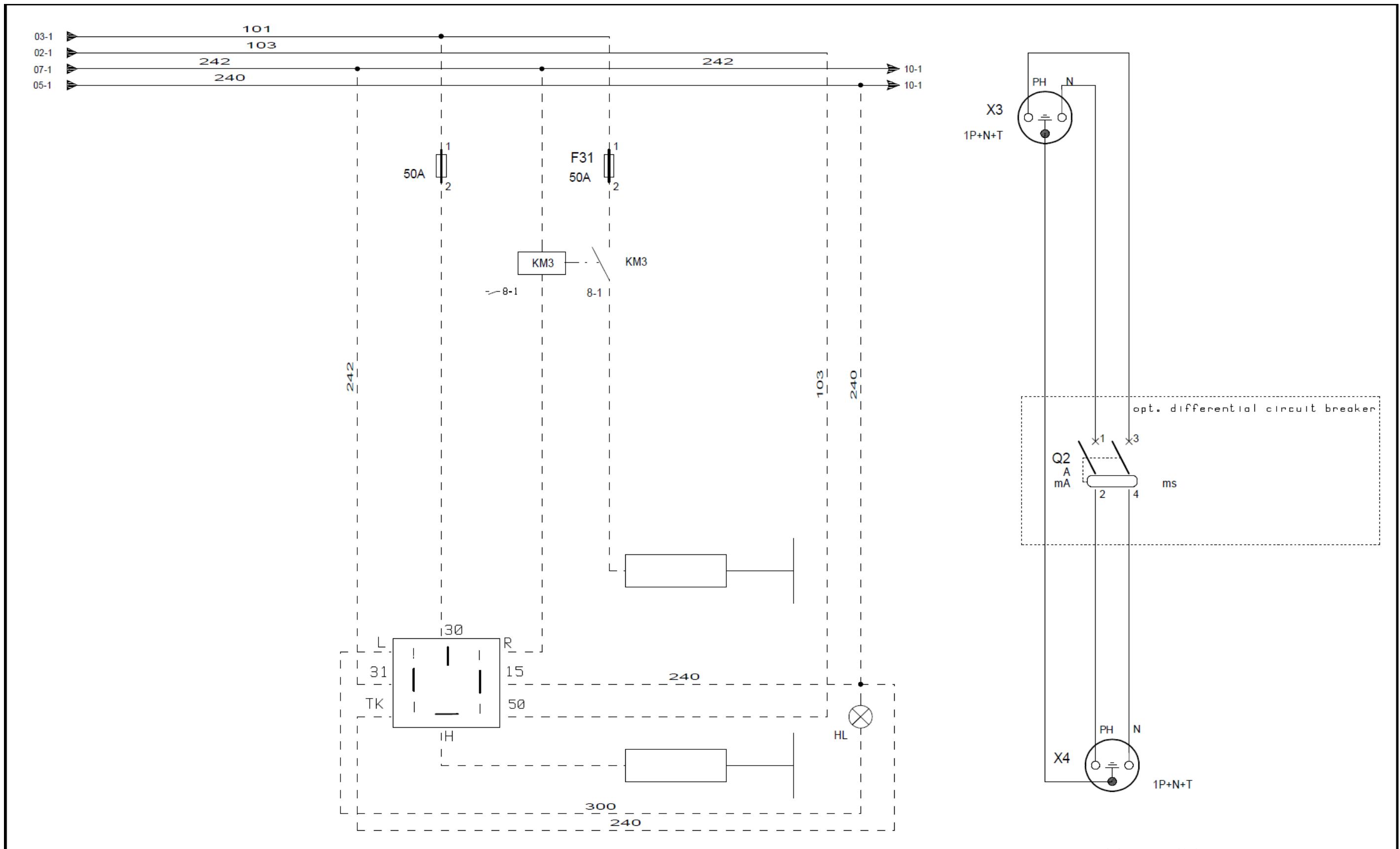






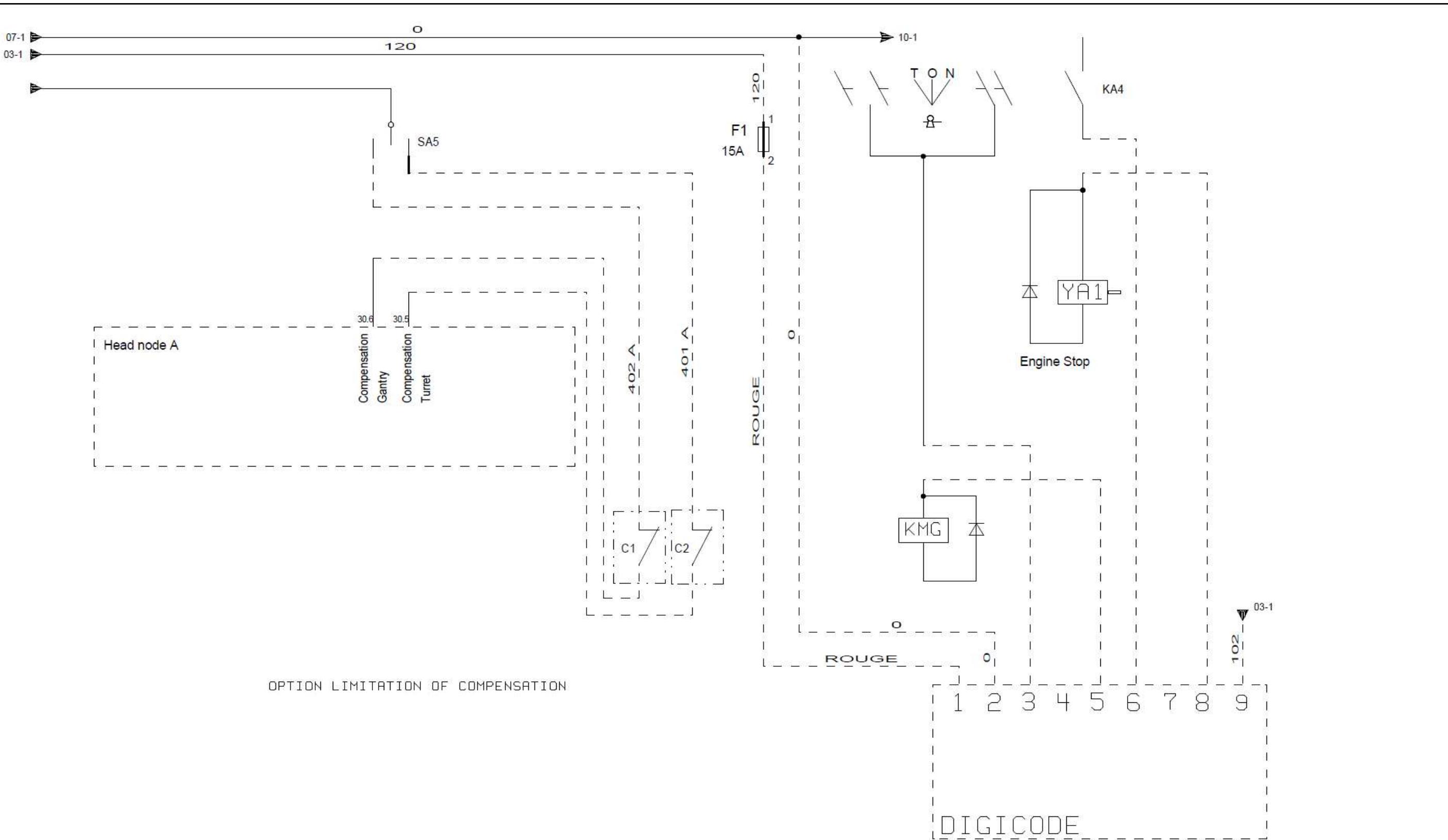




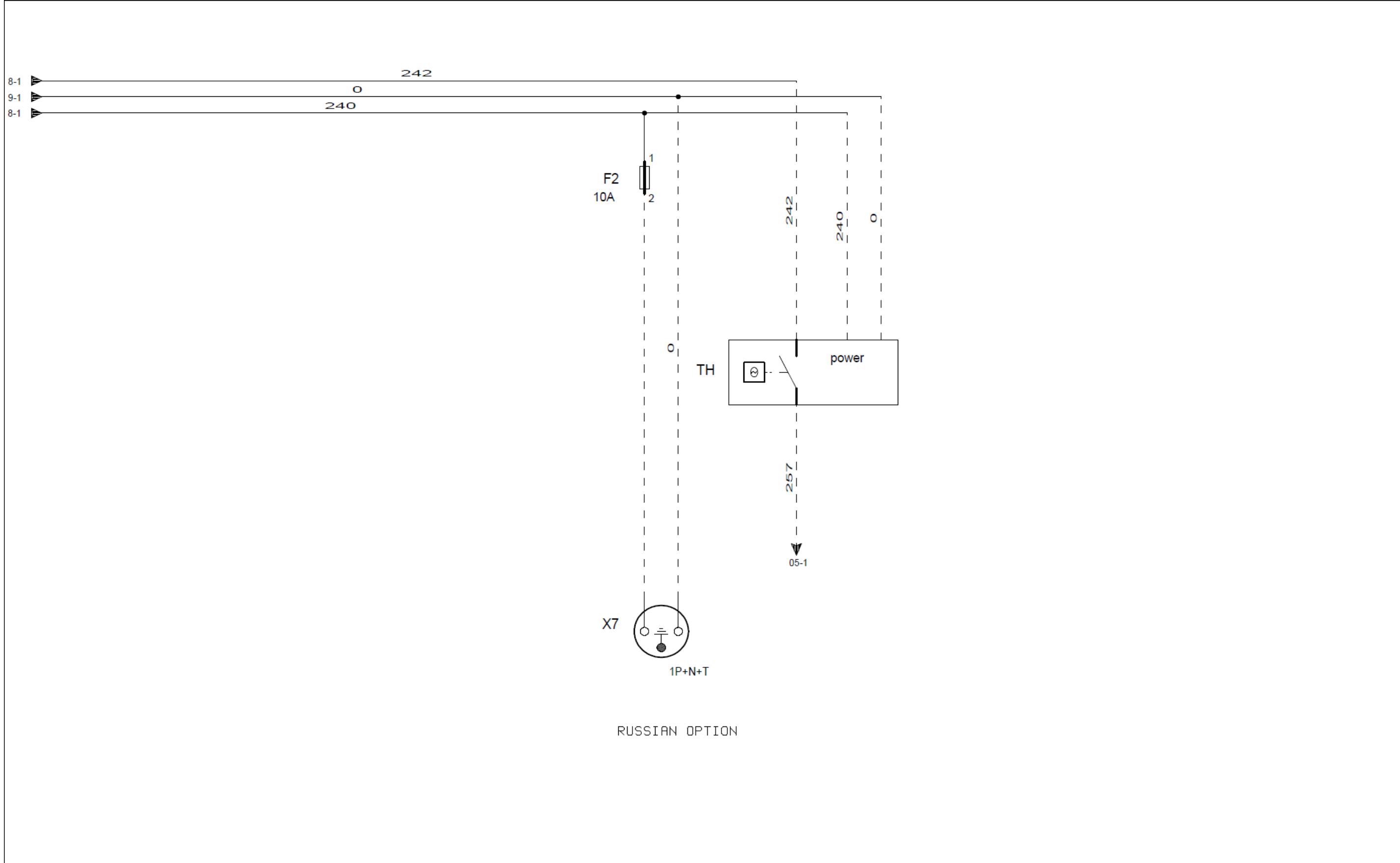


#### OPTION PREHEATING TO MOTOR

OPTION FOOD



OPT. MODULATE CODED STARTING UP



DESSINE PAR	DATE DE CREATION	OPTIONS HA16PE	MODIF	IND	DATE	MODIFICATION	VISA	NBRE TOTAL DE FOLIOS
D FERRATON	08/10/2008		D FERRATON	D	17/03/2009	(DM7424)	A DURO	10
VERIFIE PAR	DATE DE VERIFICATION		A DURO	D	12/03/2009	(DM7074 & DM7217)	N DEAUX	
A DURO	30/04/1999		A DURO	C	01/07/2008	(DM7074 & DM7217)	N DEAUX	
							SCHEMAS	10

## **LOCATION OF COMPONENTS ON MAIN PRINTED CIRCUIT**

